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Absorbent head band

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United States Patent [19]

Dean et al.

[11] **Patent Number:** **6,100,207**[45] **Date of Patent:** **Aug. 8, 2000**[54] **ABSORBENT HEAD BAND**

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Mount Carmel, all of Tenn.

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Kingsport, Tenn.

[21] Appl. No.: **08/383,027**

[22] Filed: **Feb. 2, 1995**

[51] **Int. Cl.⁷** **D04H 1/58**

[52] **U.S. Cl.** **442/350; 442/118; 442/334;**
442/352; 2/174; 2/209.3; 2/207; 2/DIG. 1

[58] **Field of Search** 2/174, 209.3, 207,
2/DIG. 11; 428/288, 296, 297; 442/118,
334, 350, 352

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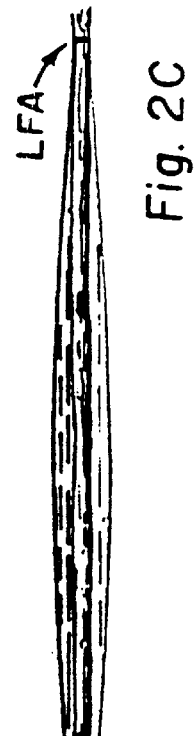
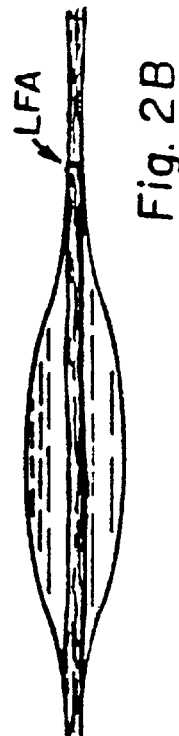
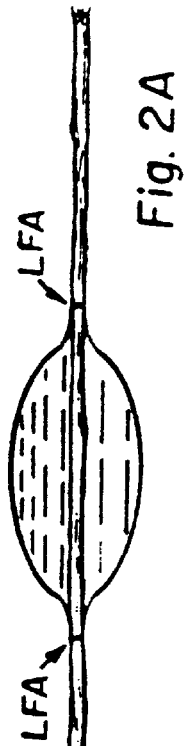
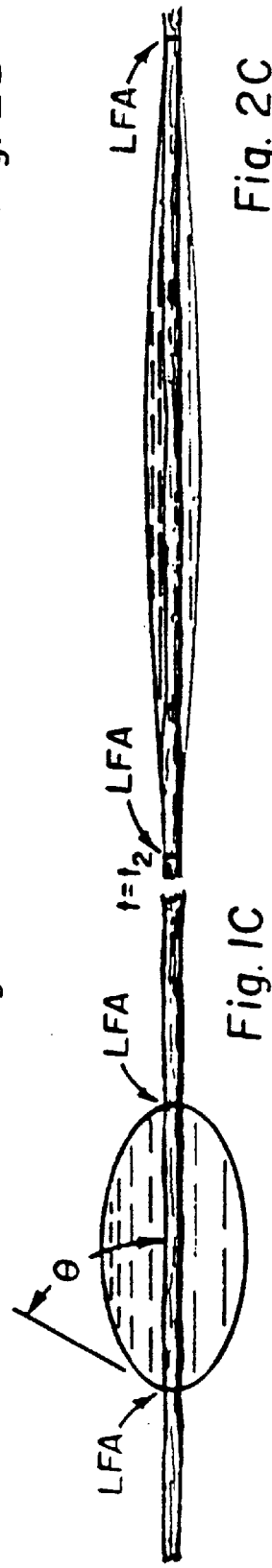
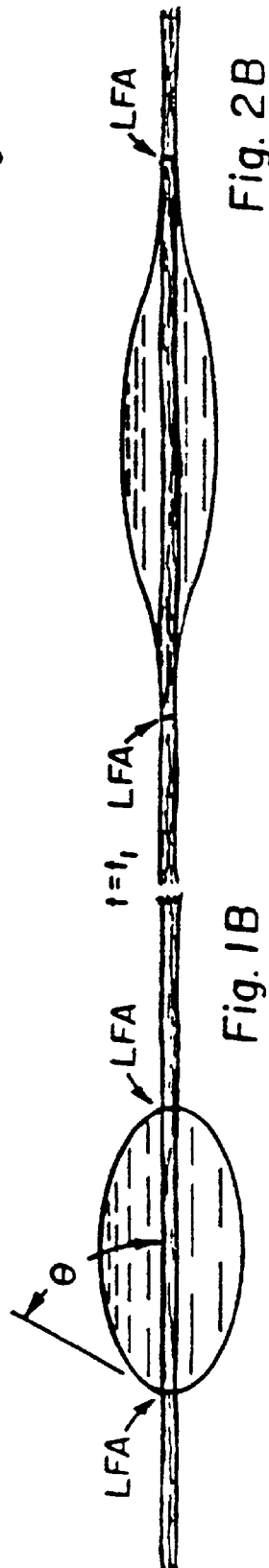
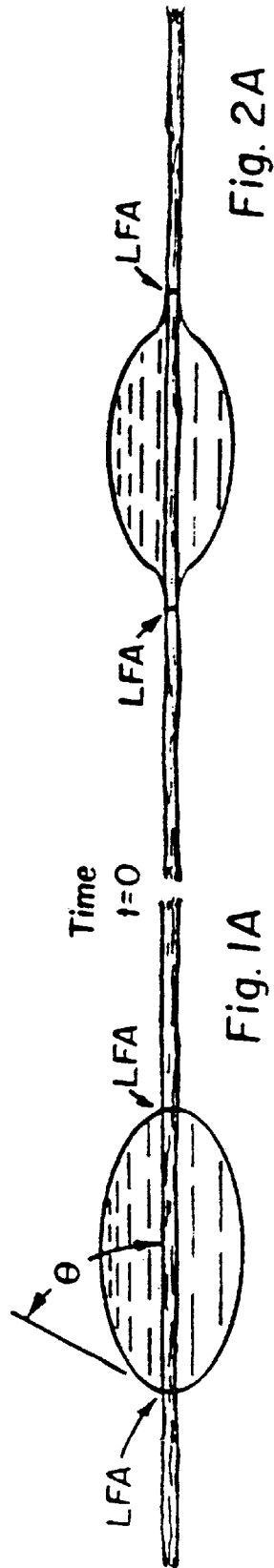
Primary Examiner—James J. Bell

Attorney, Agent, or Firm—Cheryl J. Tubach; Harry J.
Gwinnell

[57] **ABSTRACT**

Disclosed are head bands comprising a sliver of spontane-
ously wettable staple fibers. The fibers are of an irregular,
grooved shape in cross section and are lightly bound
together to permit easy separation into suitable lengths for
head bands.

8 Claims, 39 Drawing Sheets



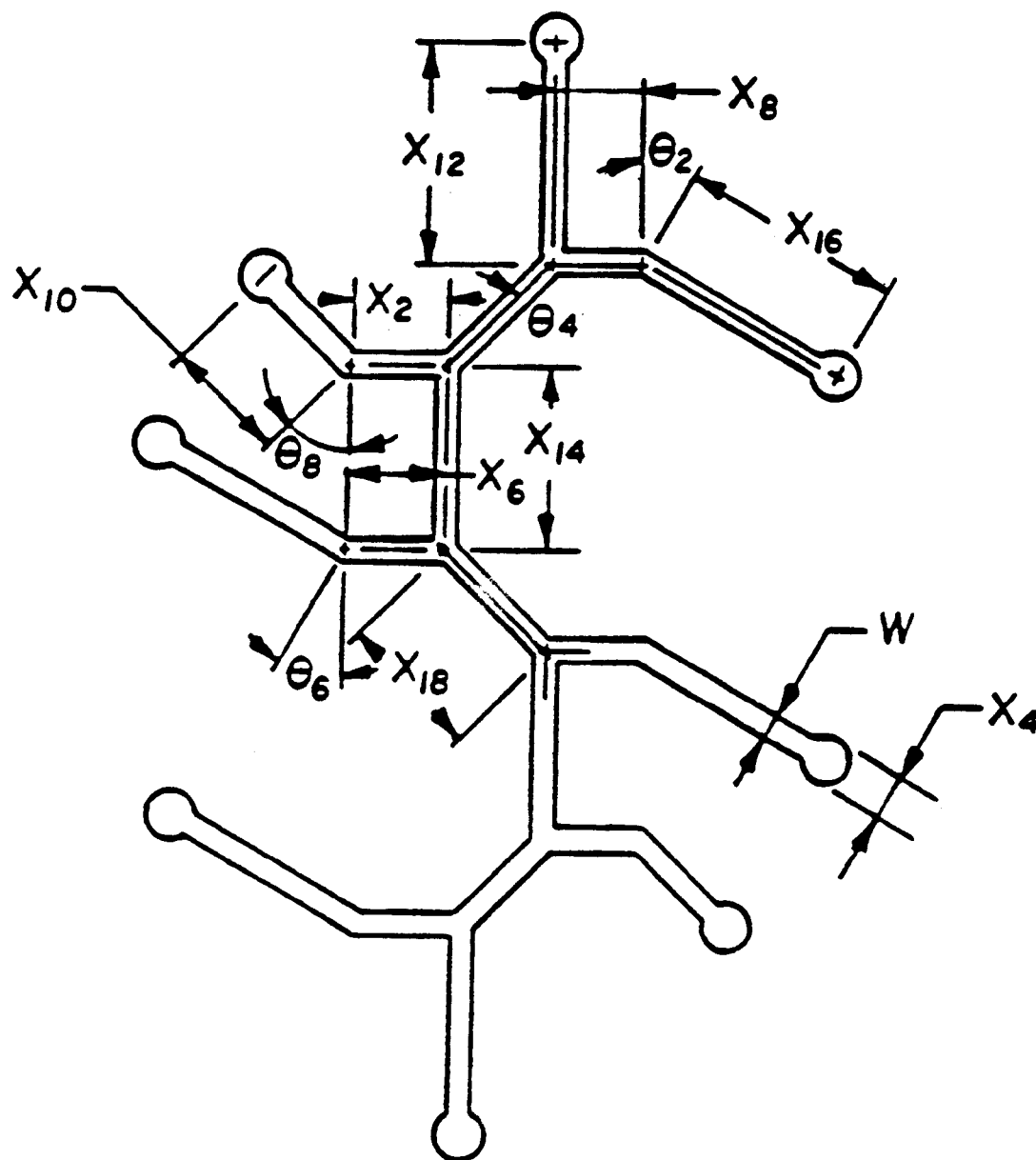


Fig. 3

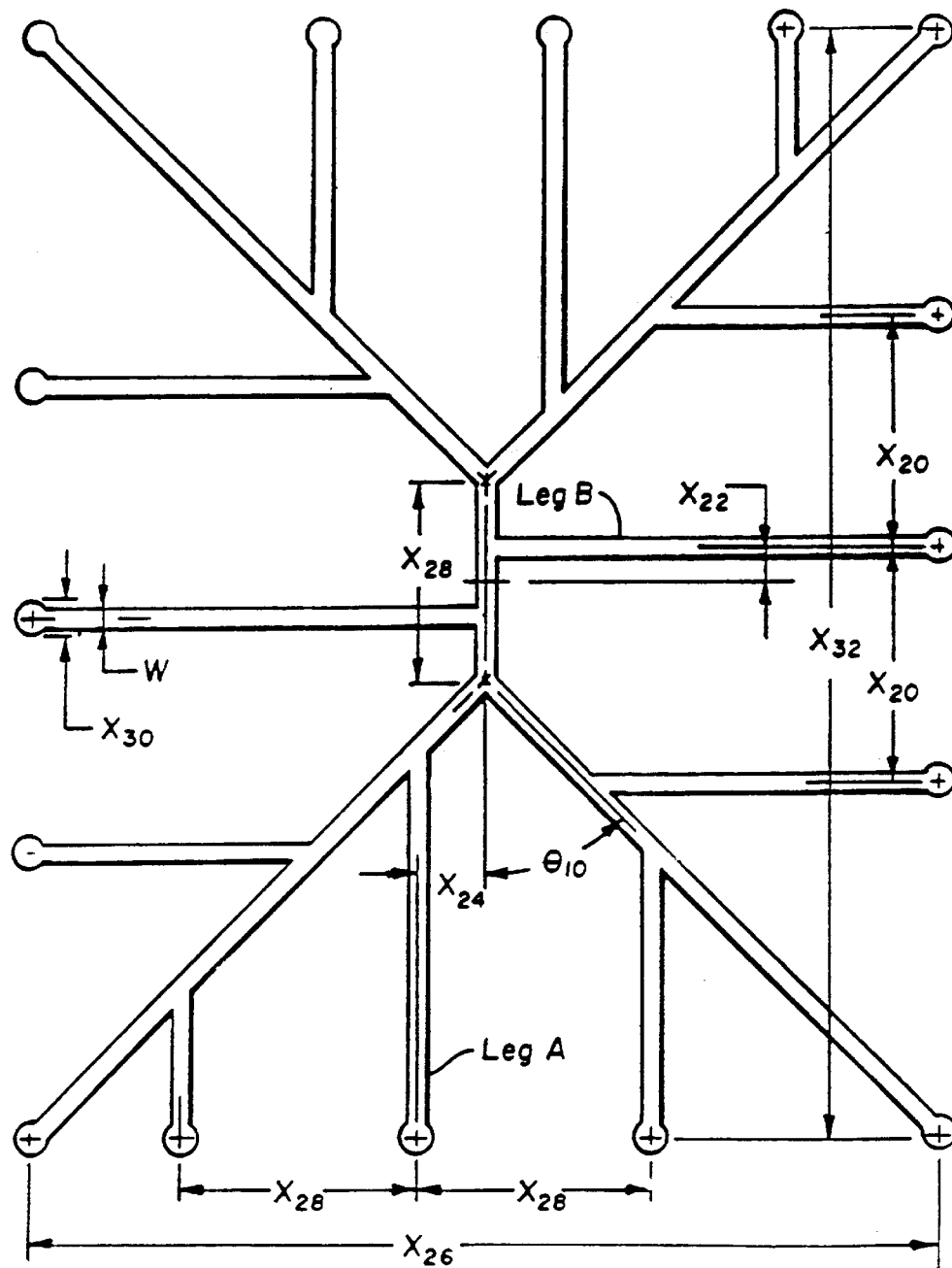


Fig. 4

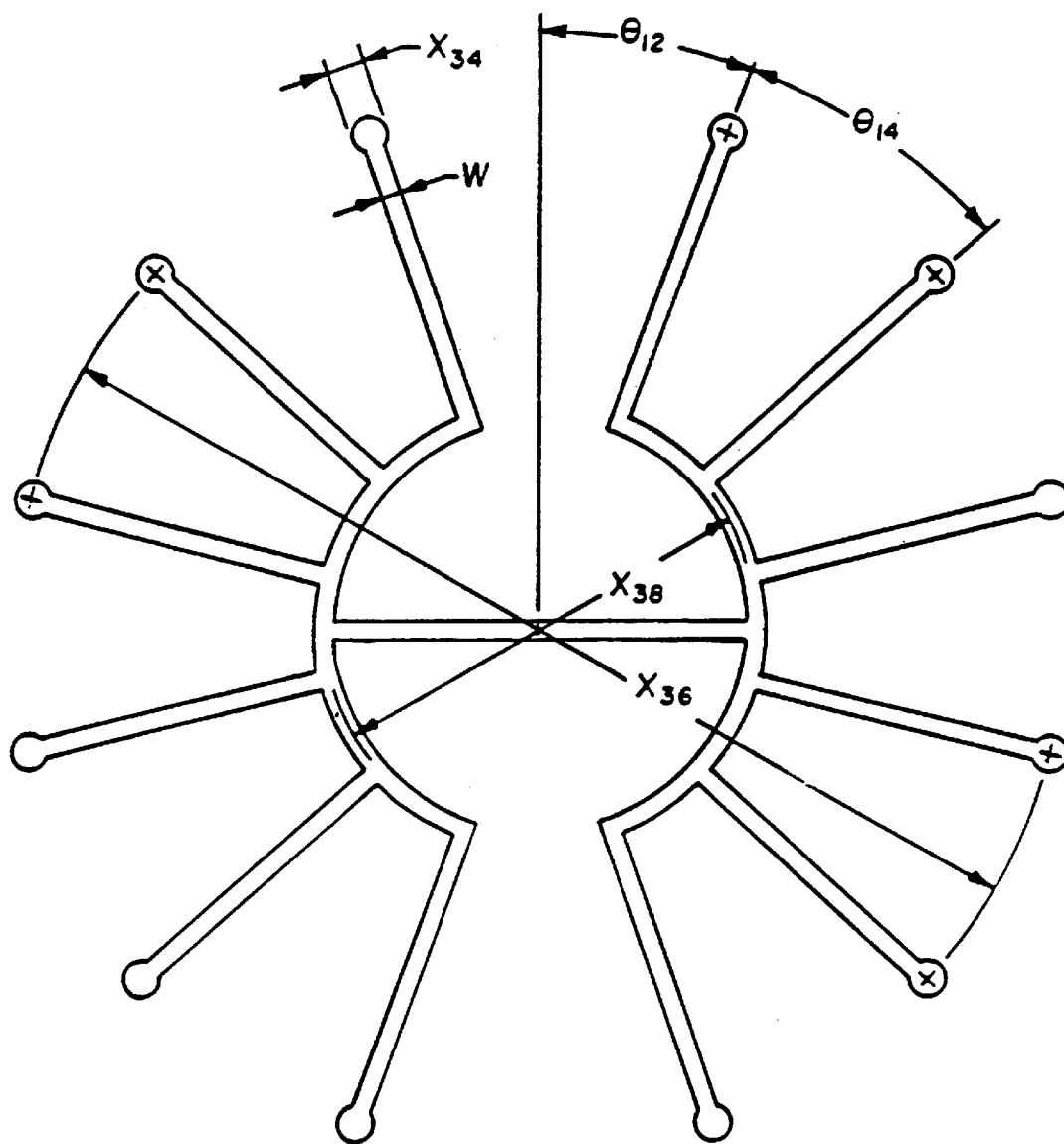


Fig. 5

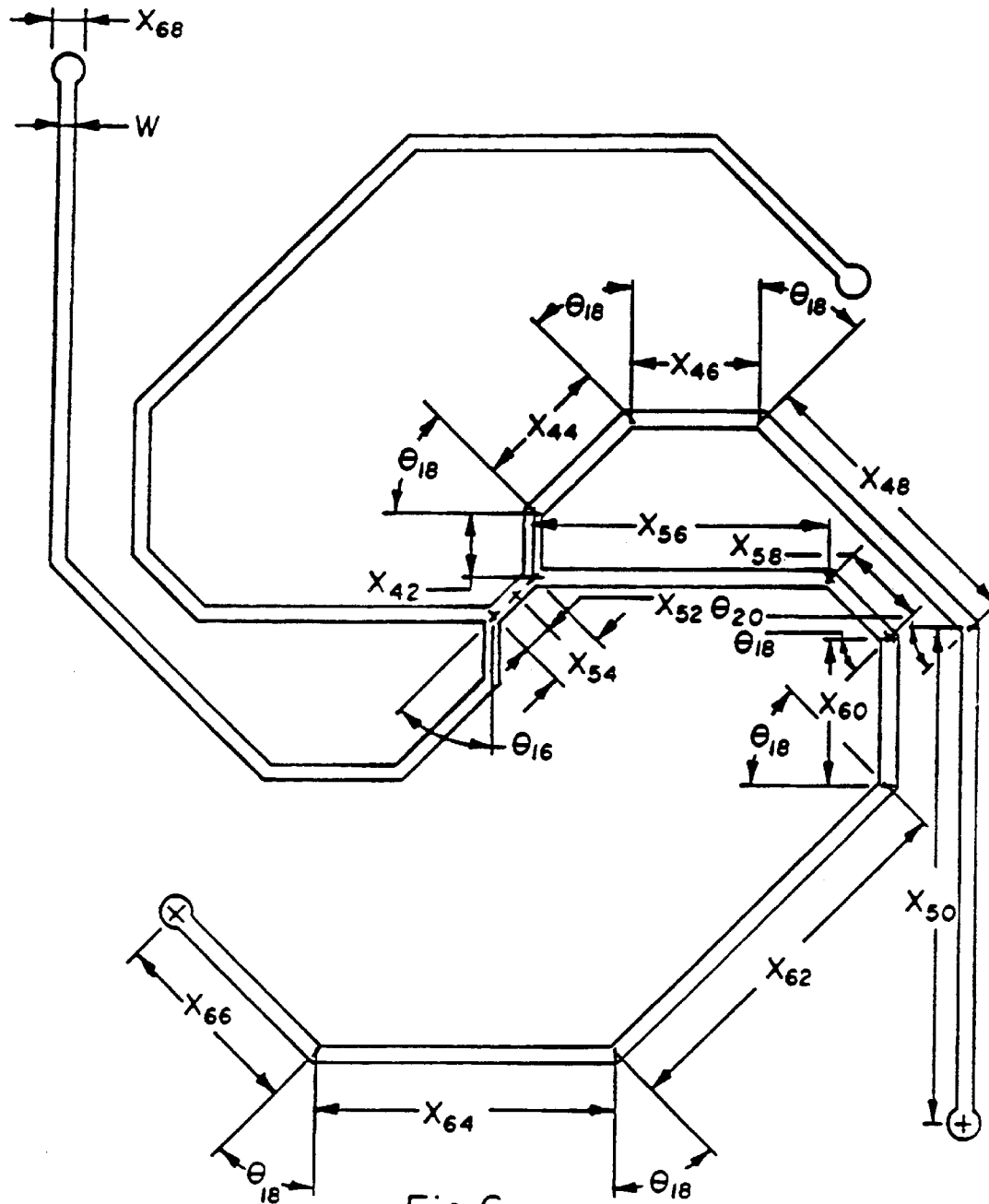


Fig. 6

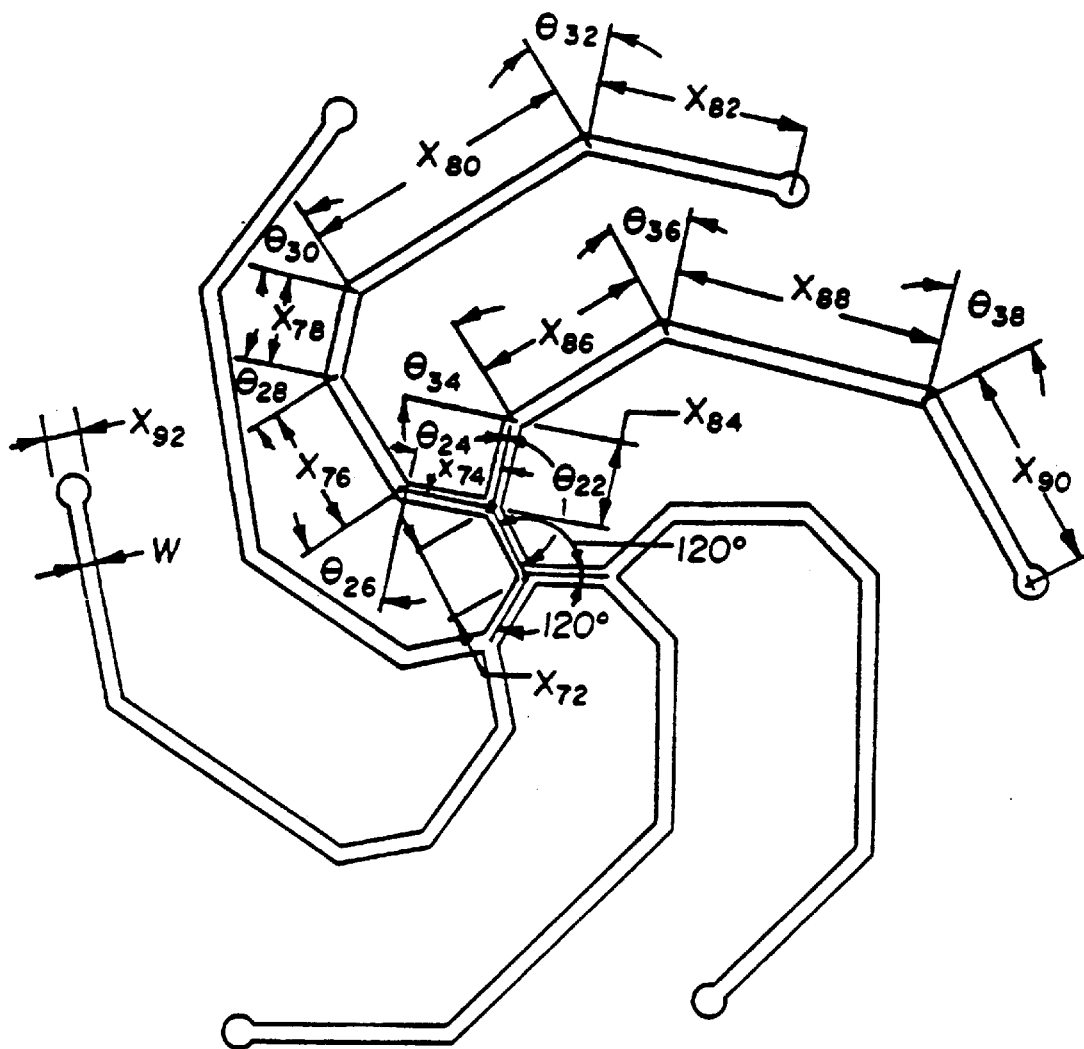


Fig. 6 B

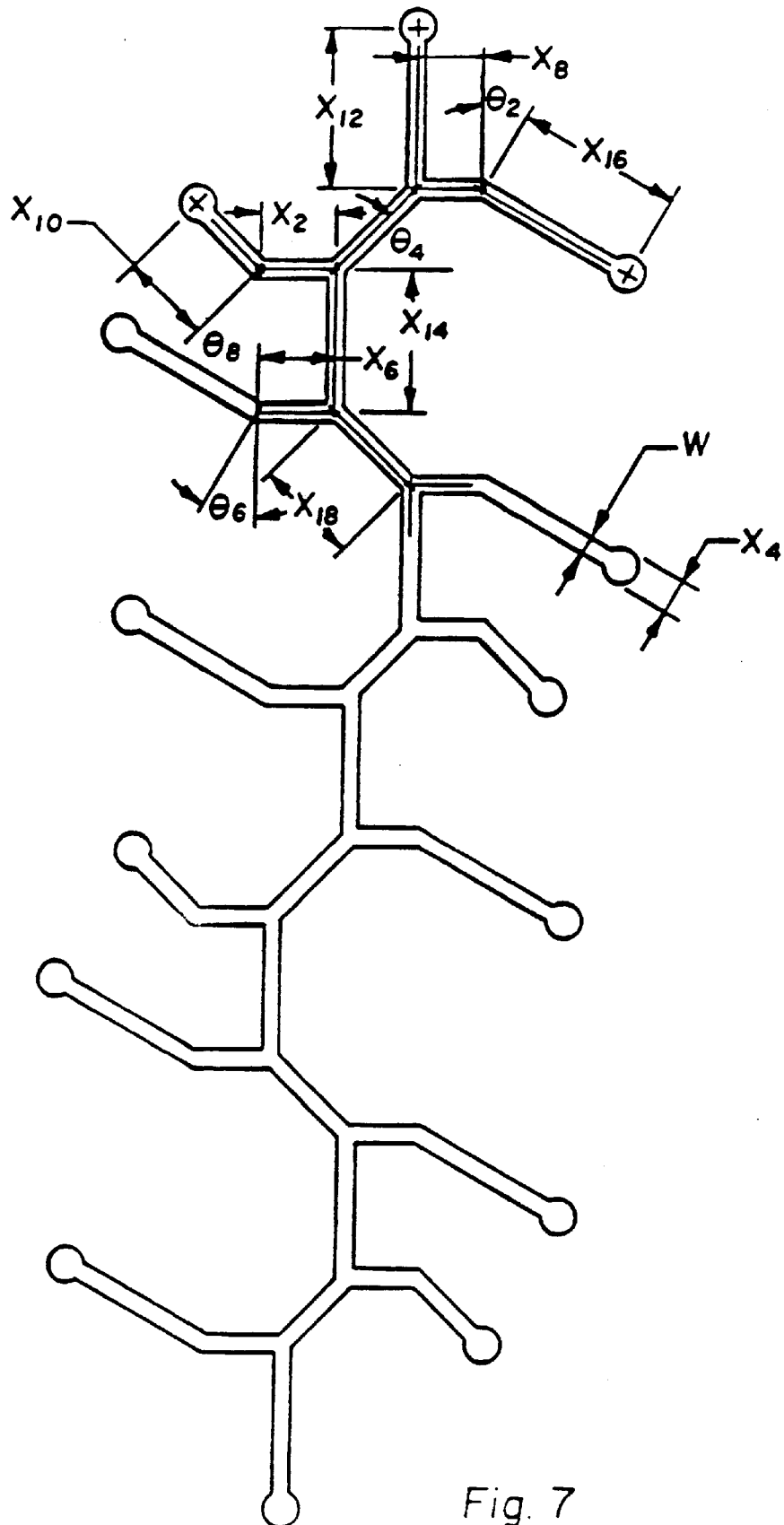


Fig. 7

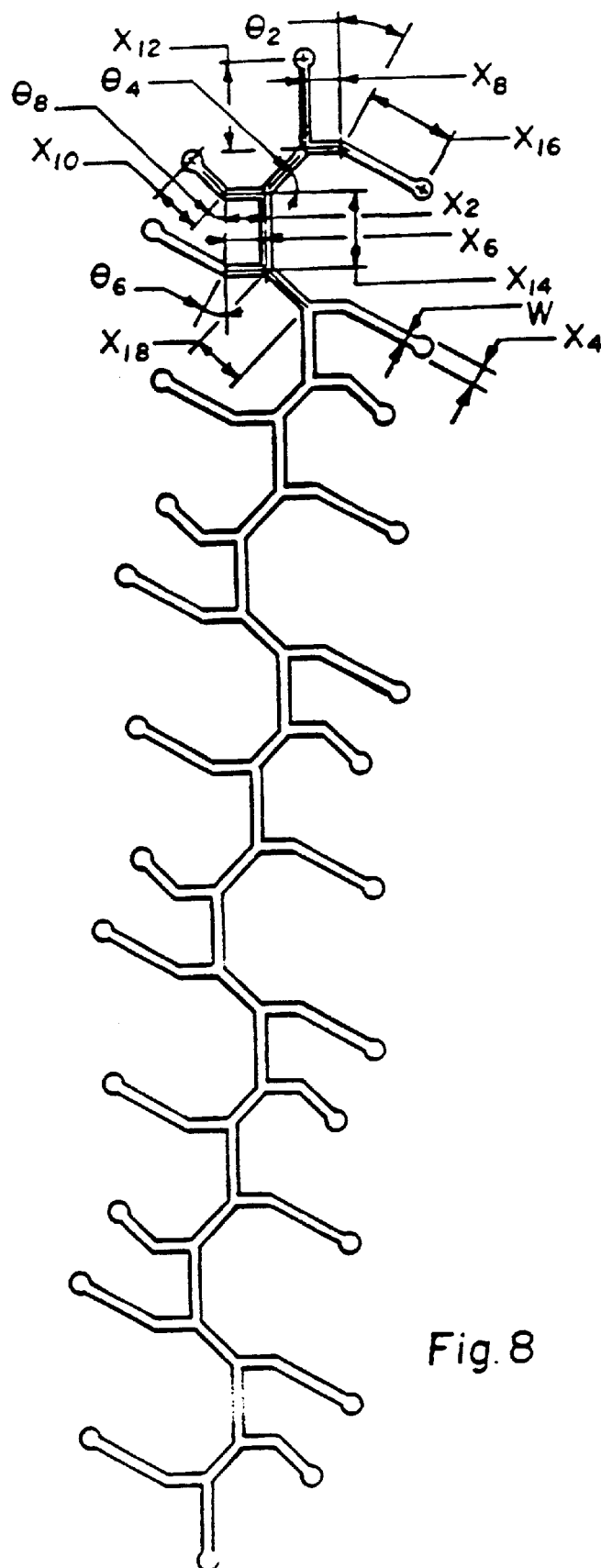


Fig. 8

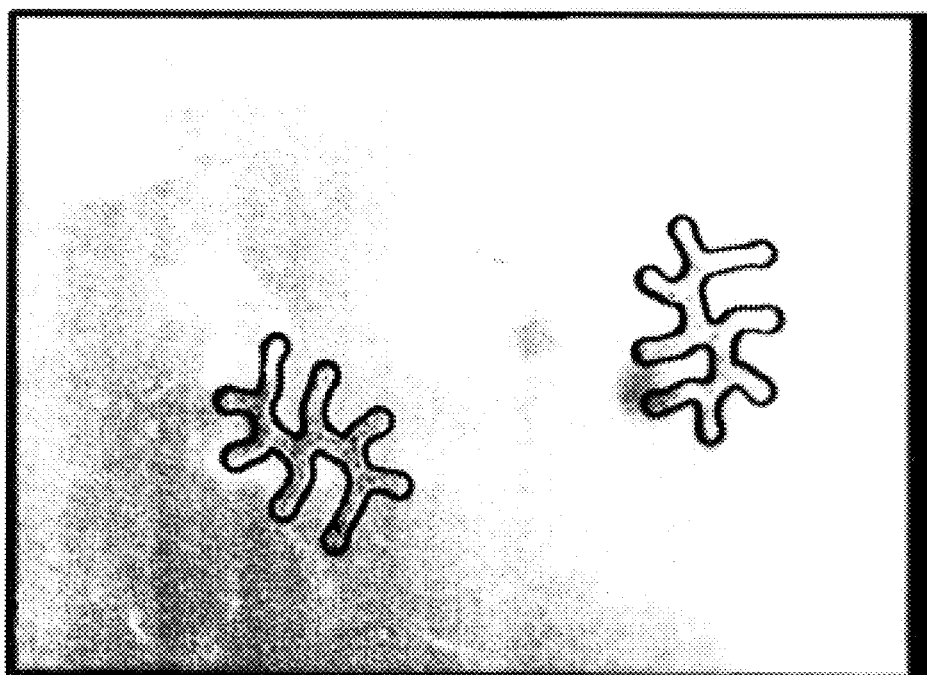


Fig. 9

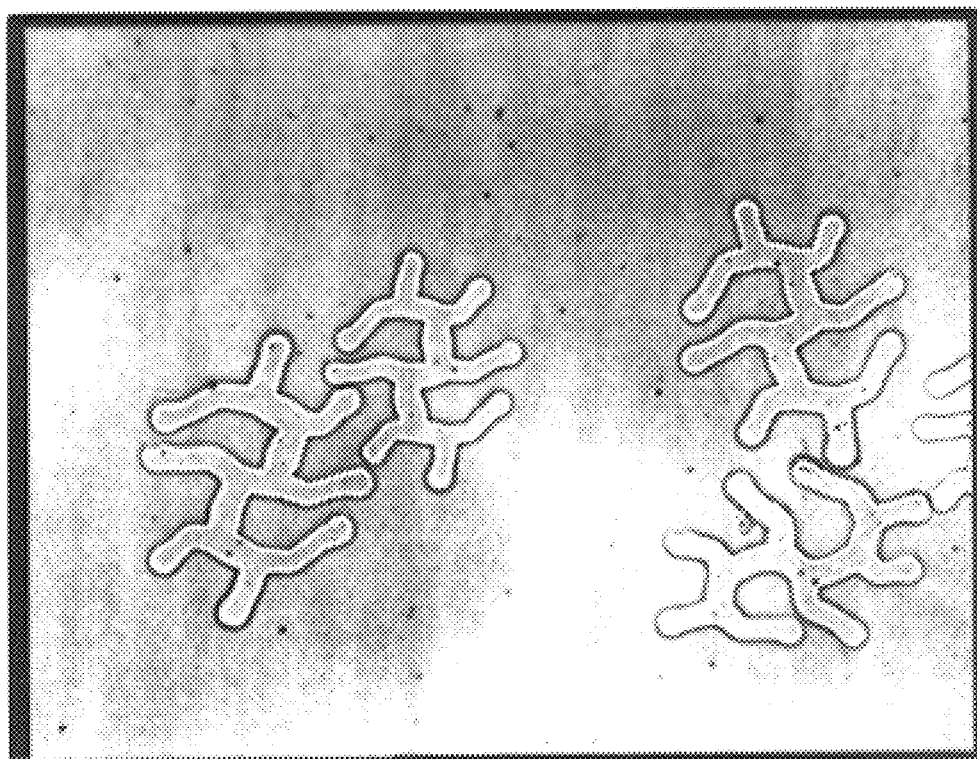


Fig. 10

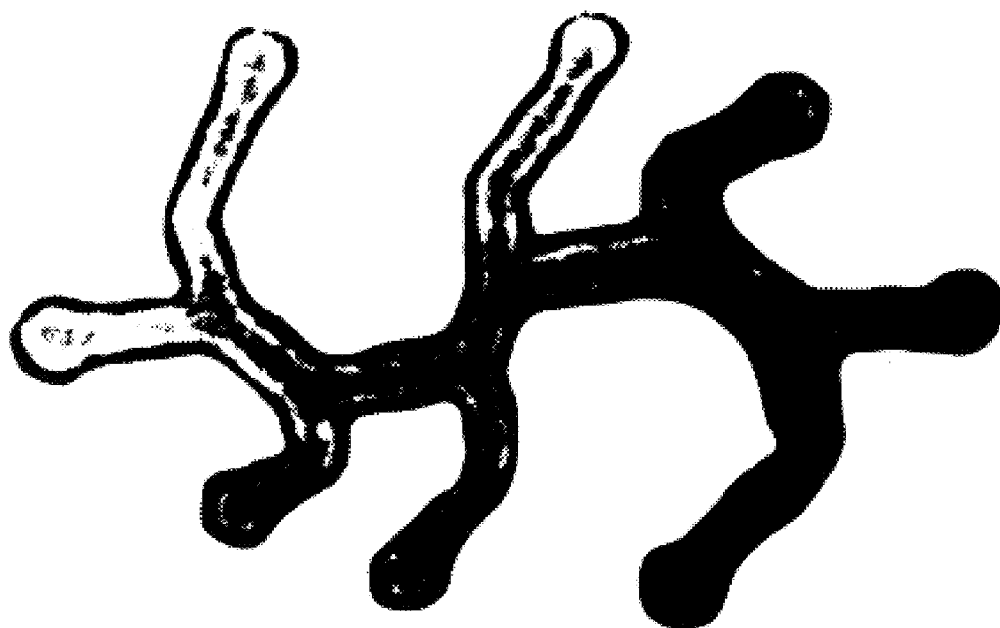


Fig. 11

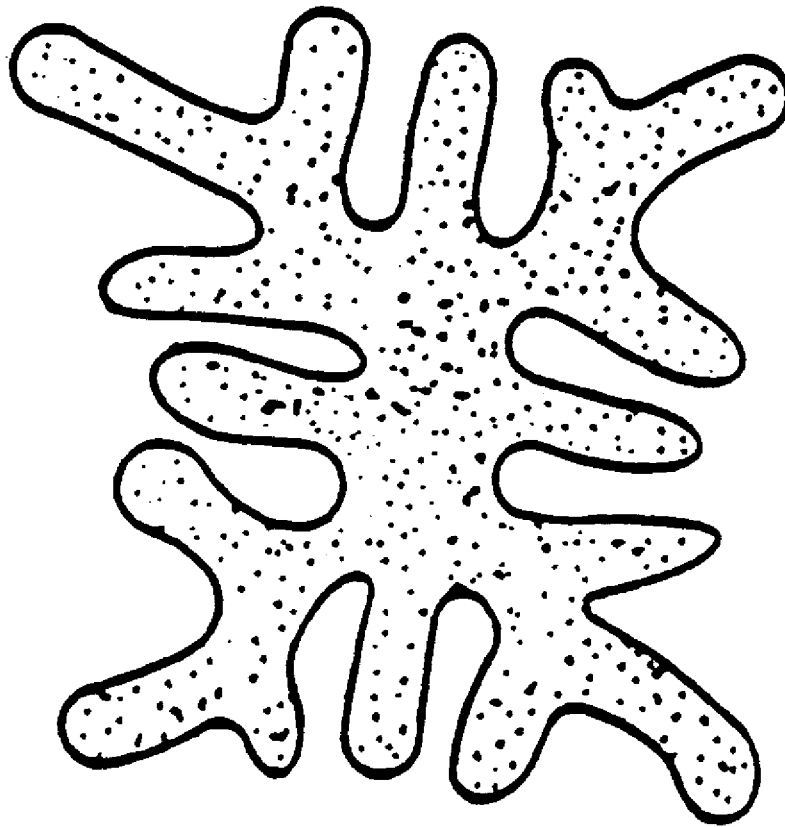


Fig. 12

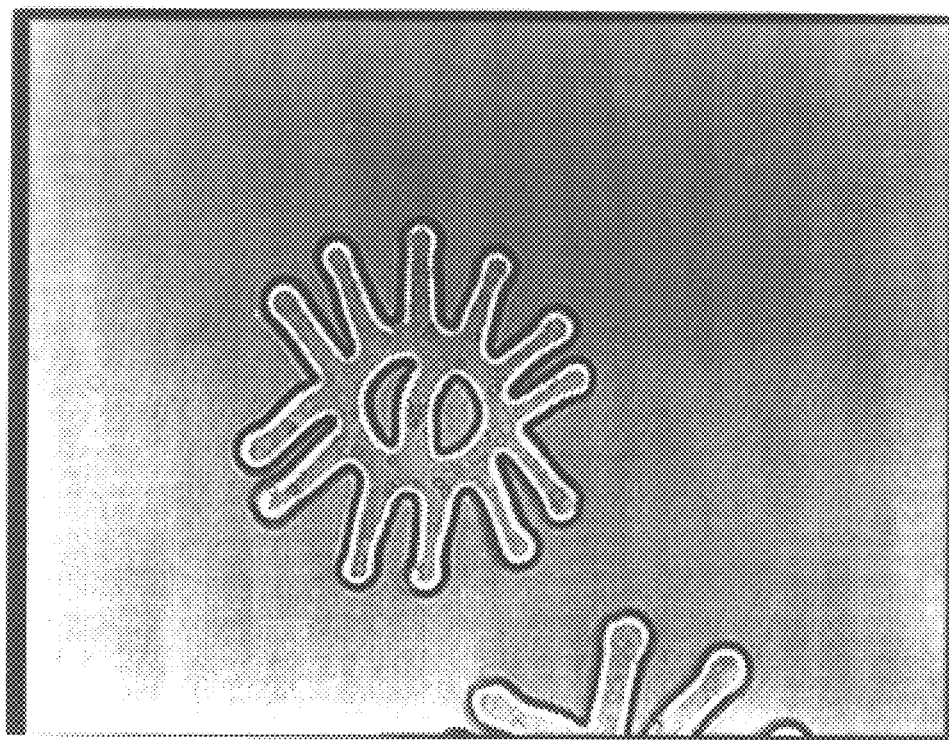


Fig. 13

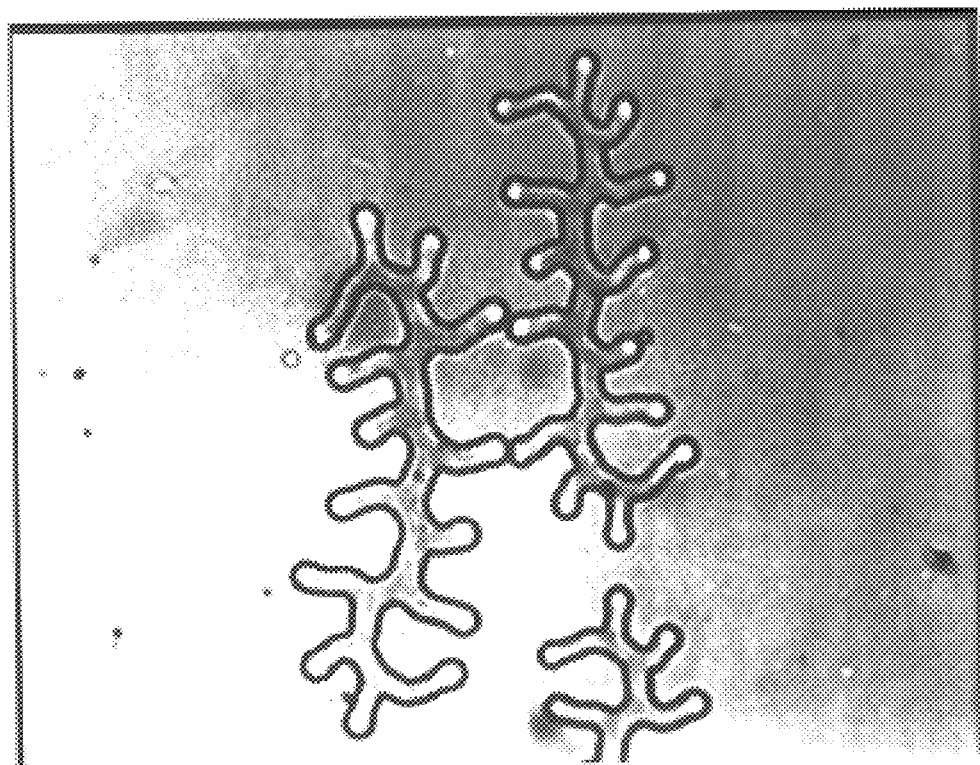


Fig. 14

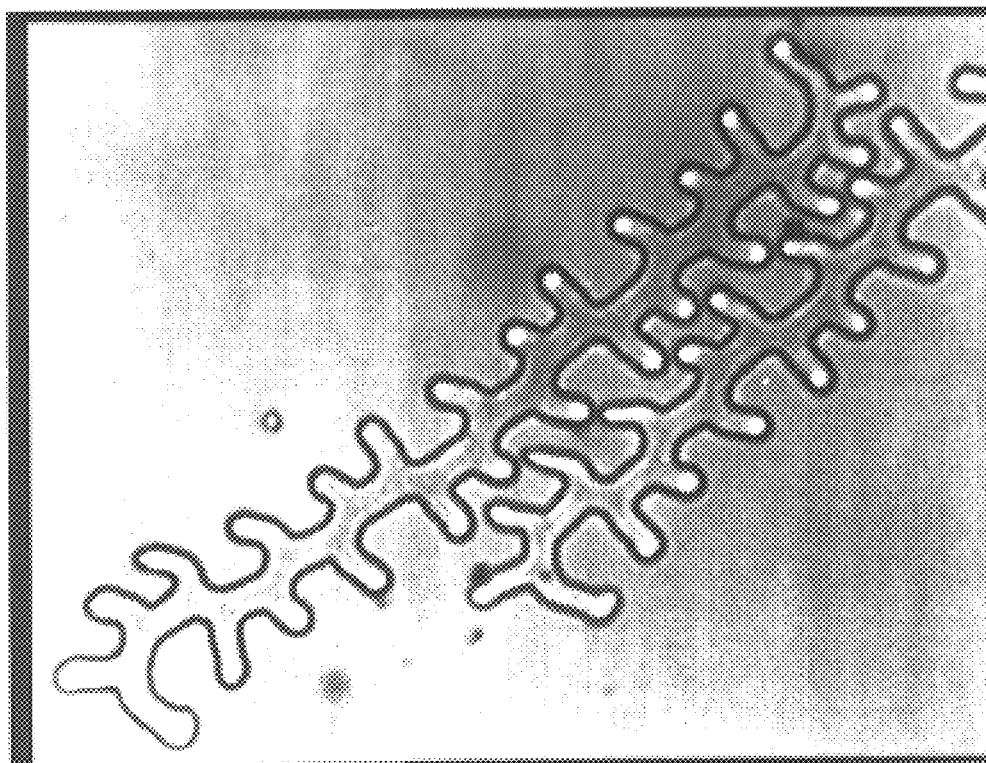


Fig. 15

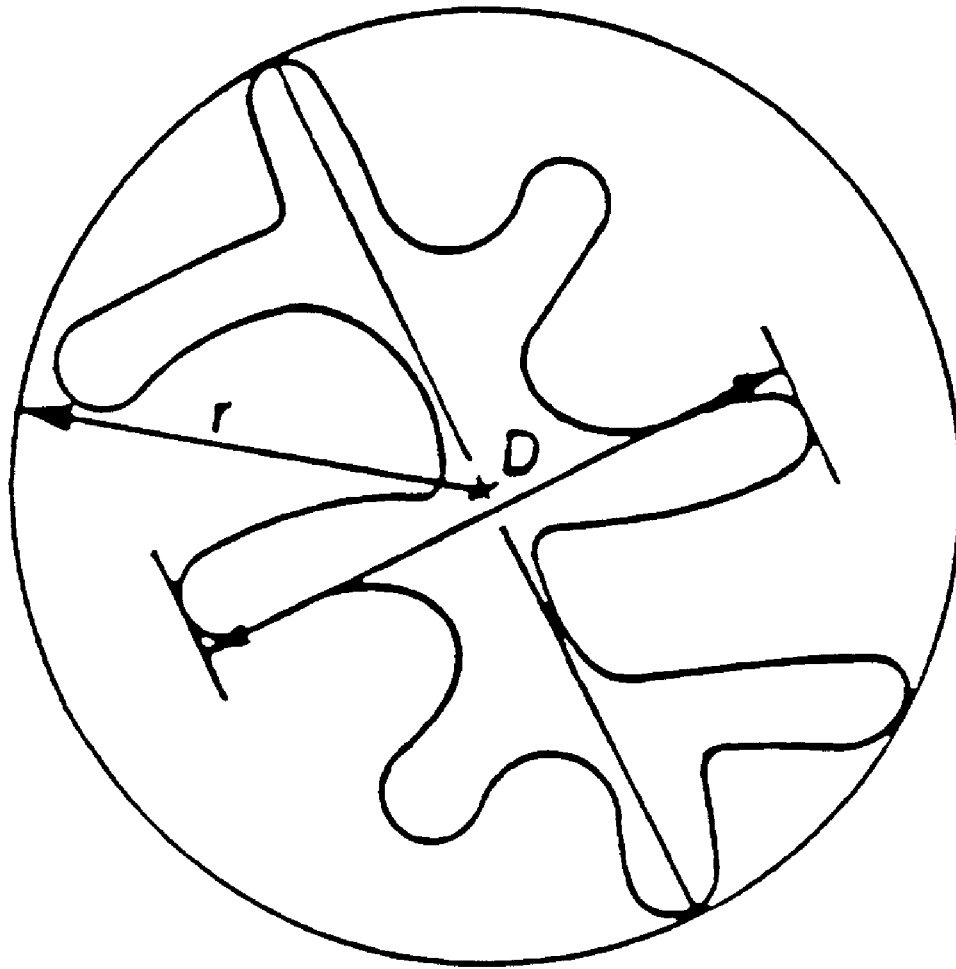


Fig. 16

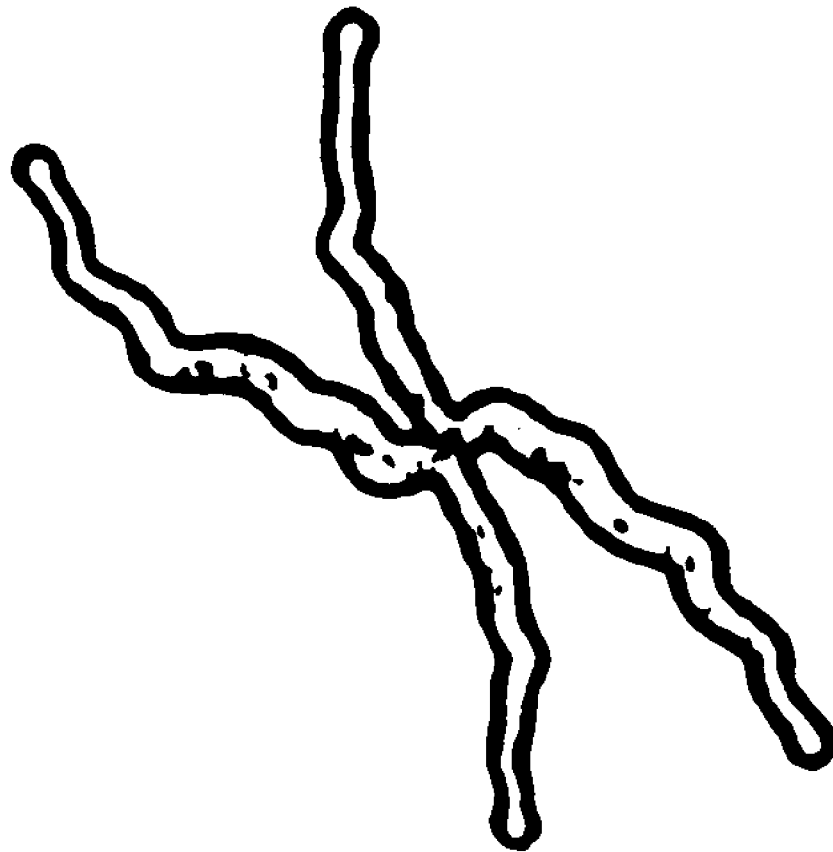


Fig. 17

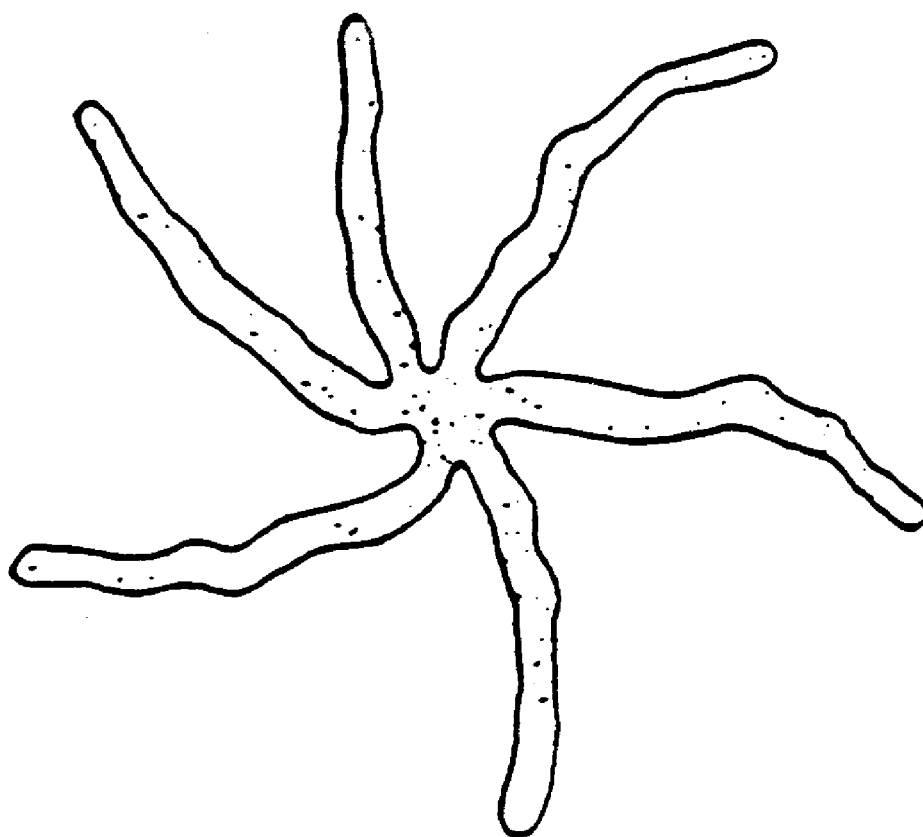


Fig. 17 B

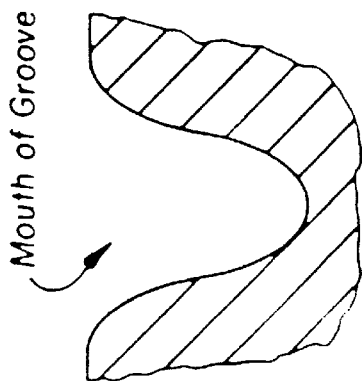


Fig. 18A

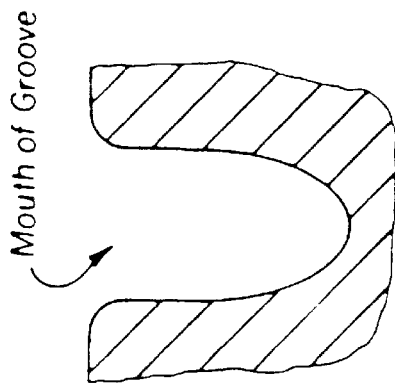


Fig. 18B

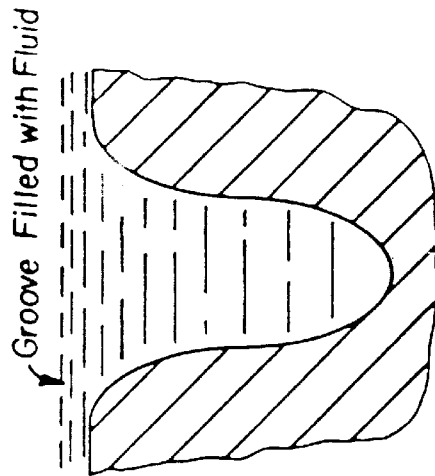


Fig. 18C

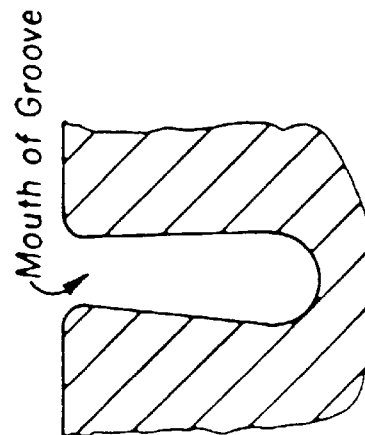


Fig. 19A

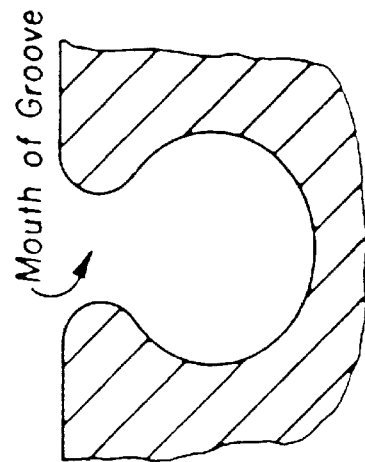


Fig. 19B

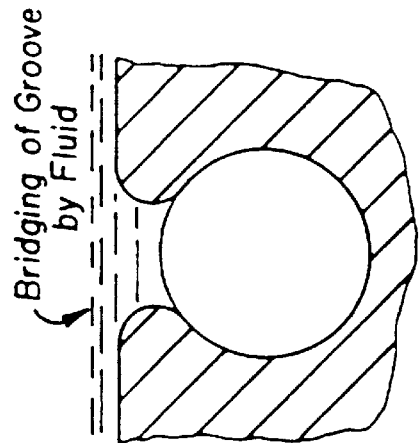


Fig. 19C

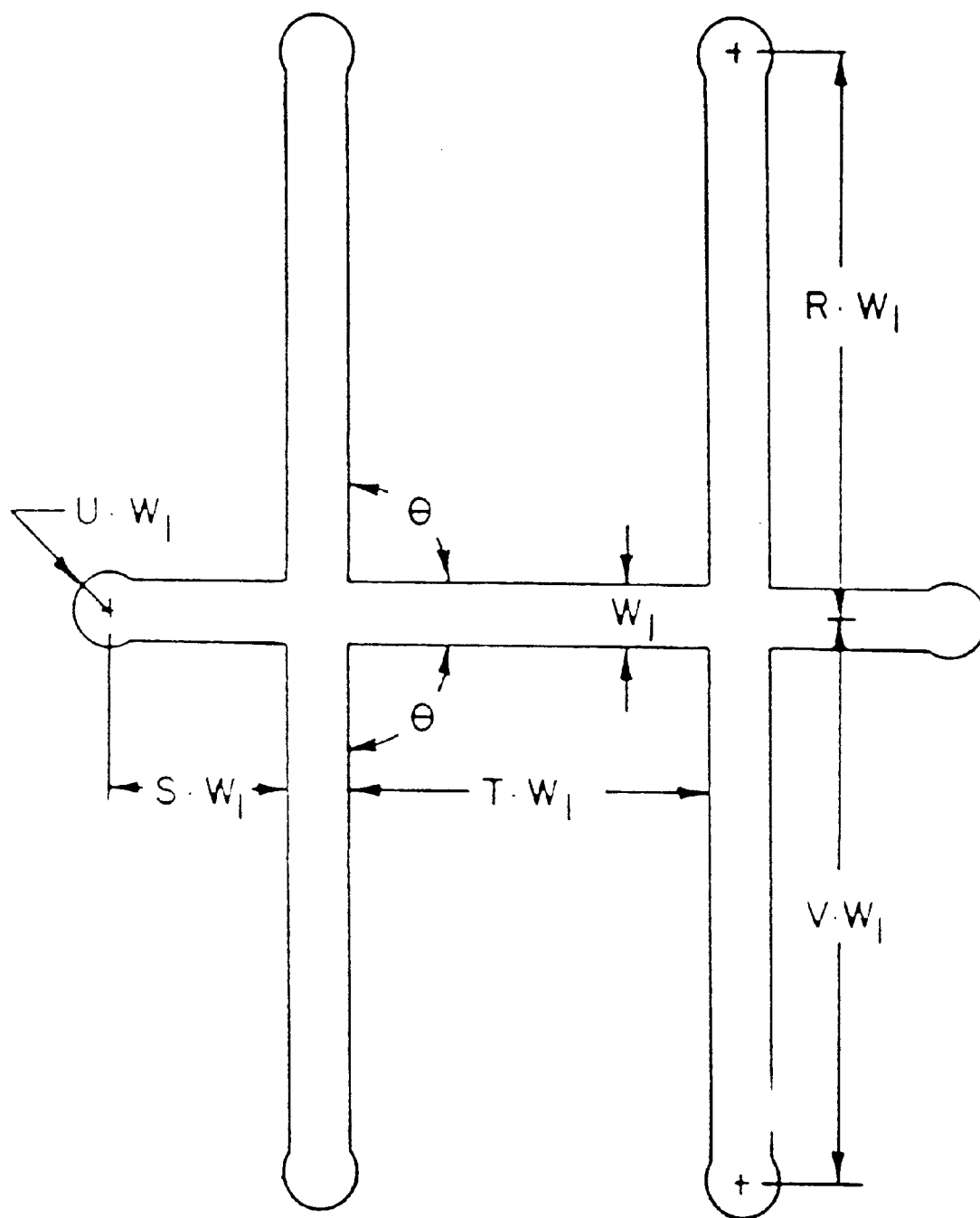


Fig. 20

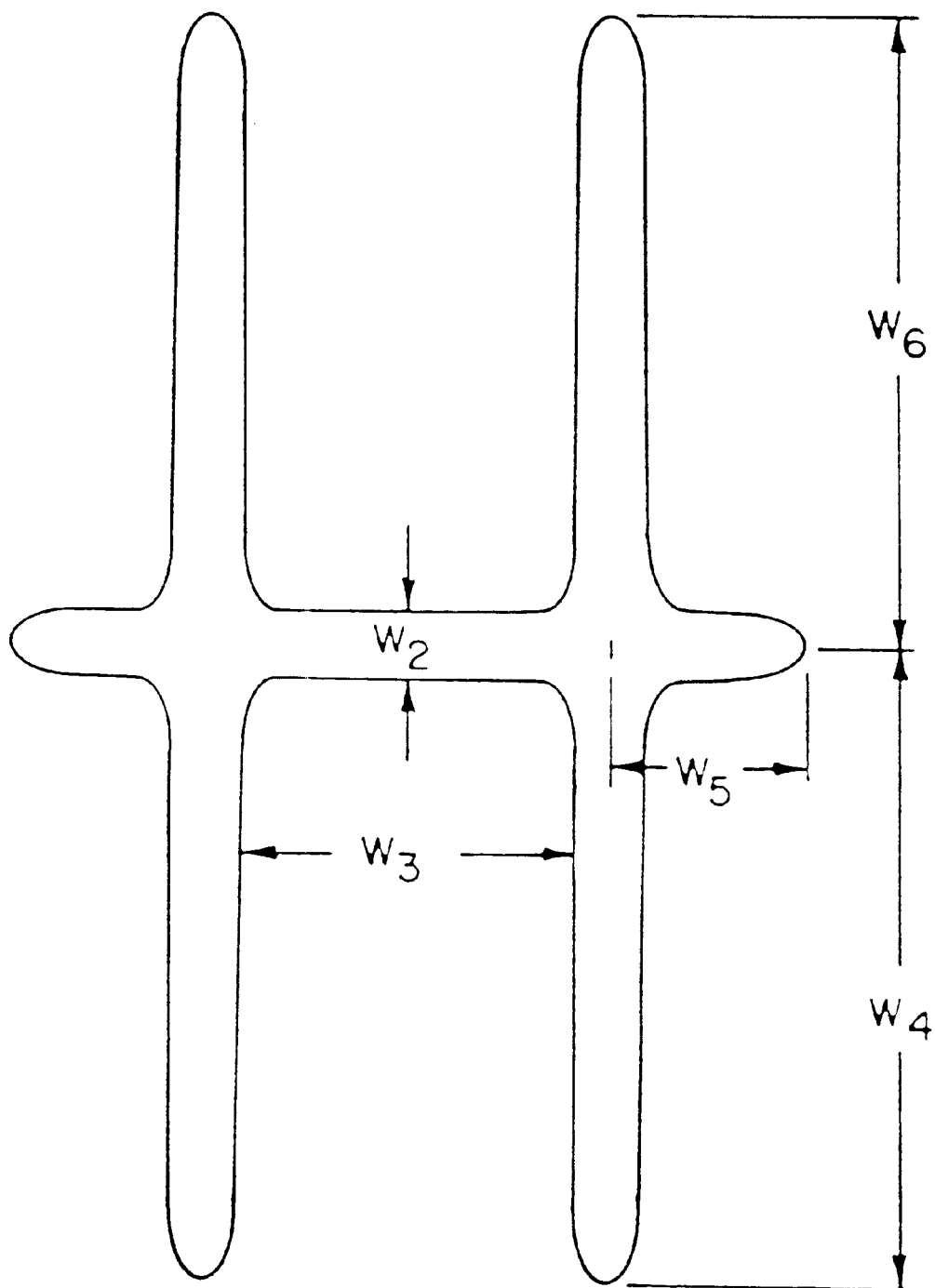
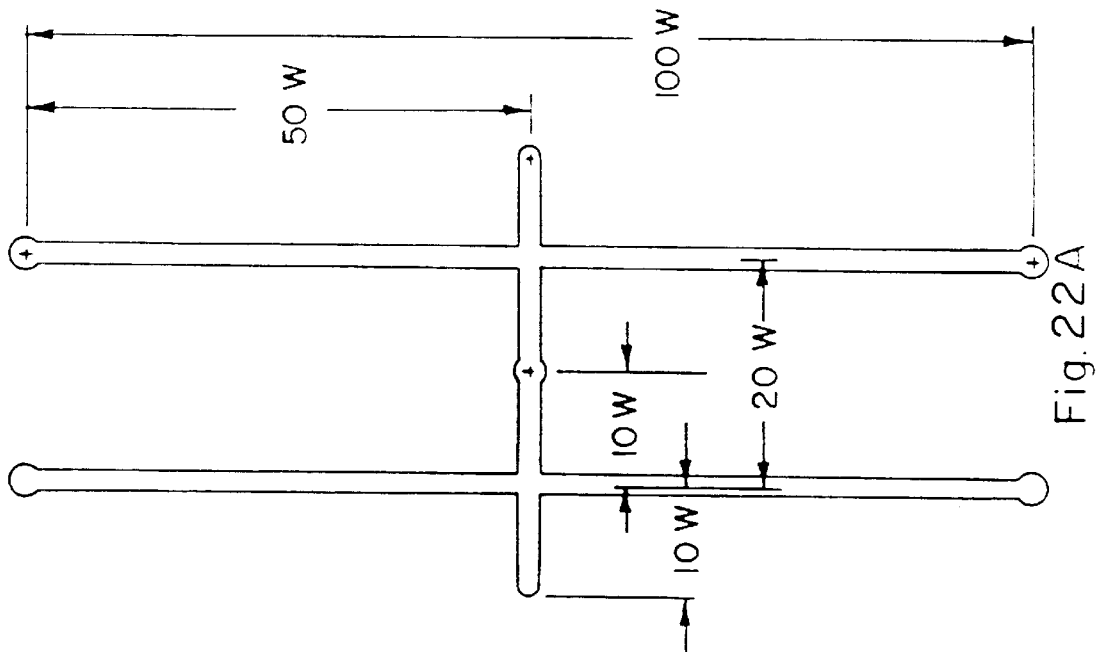
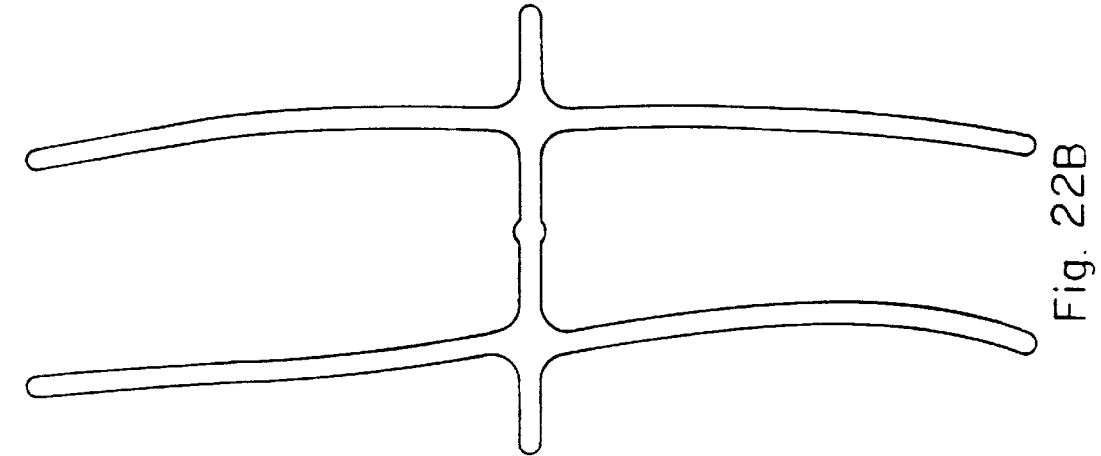


Fig. 21



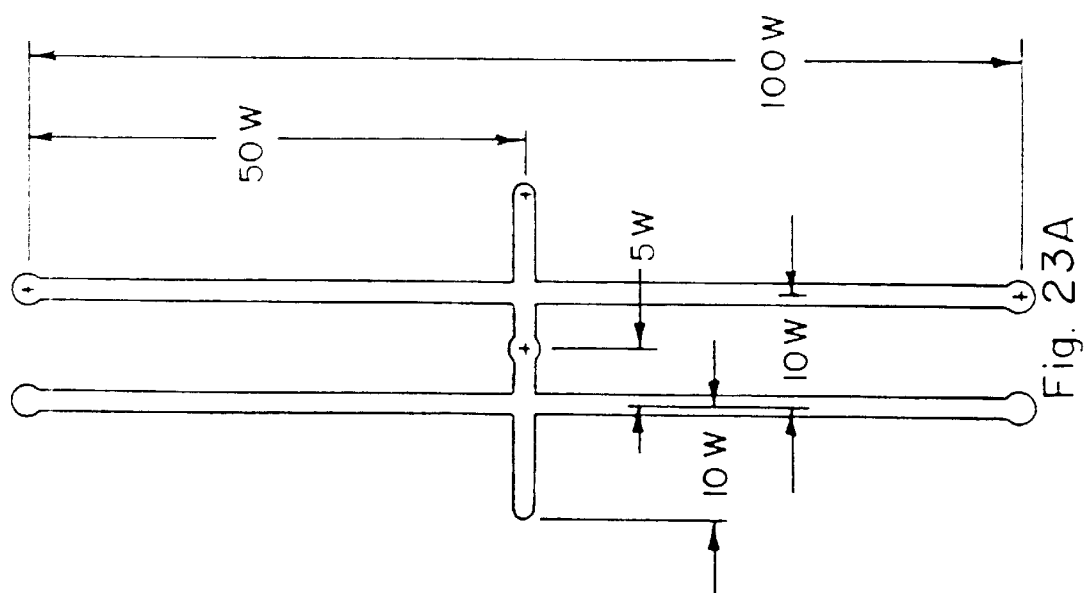
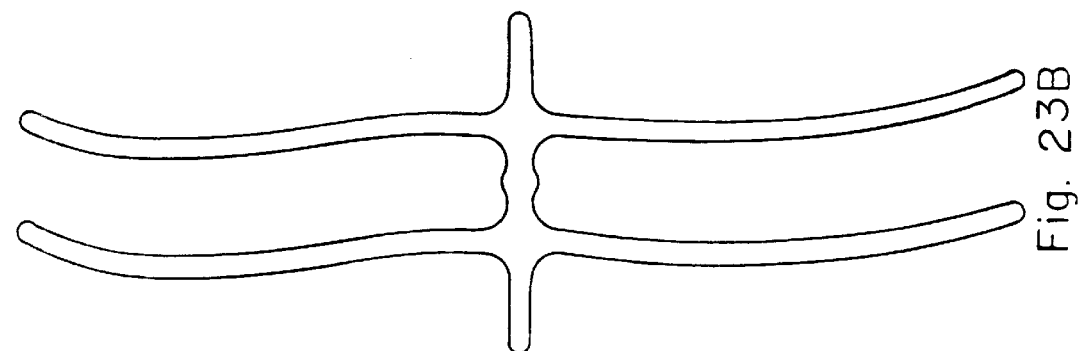
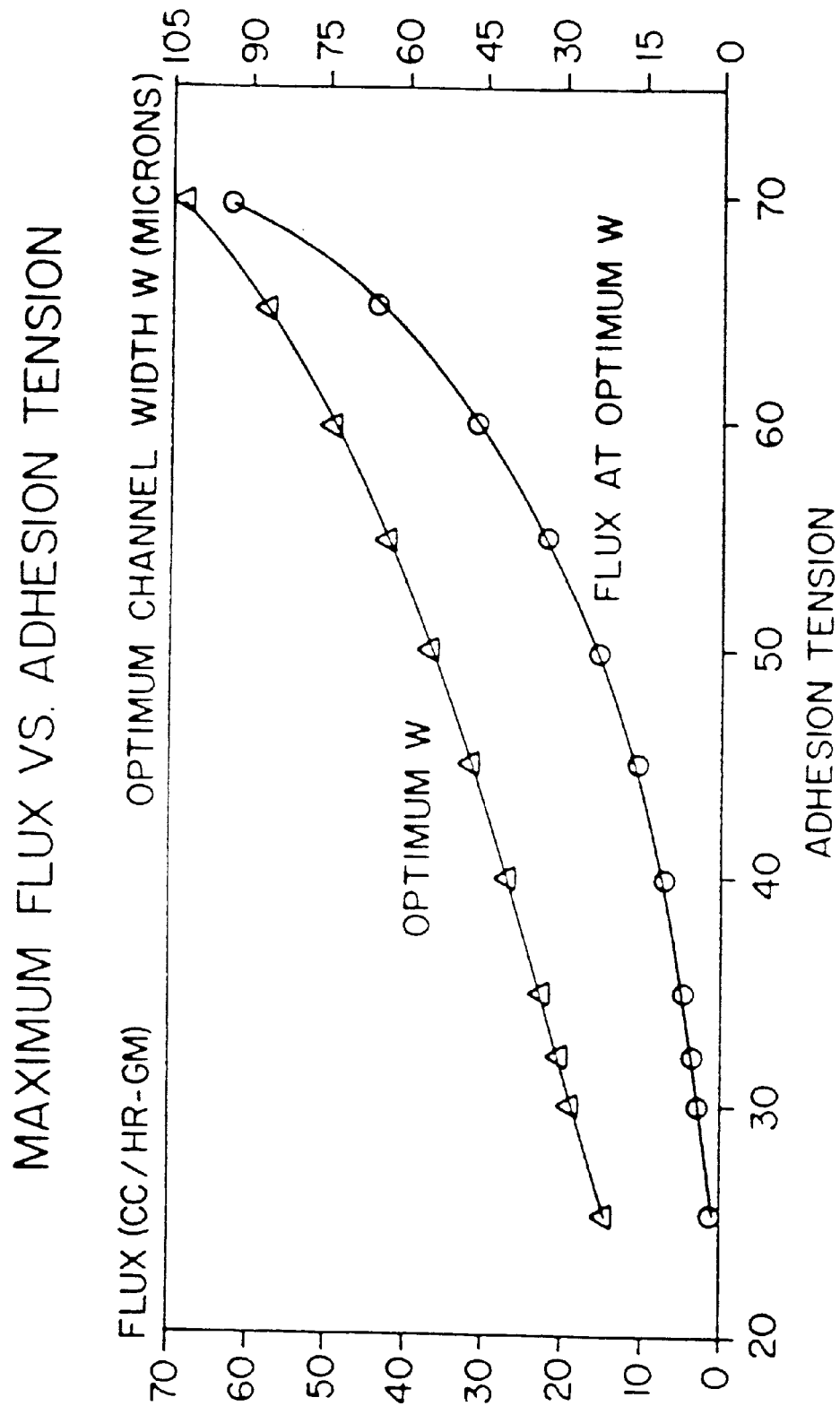


Fig. 24



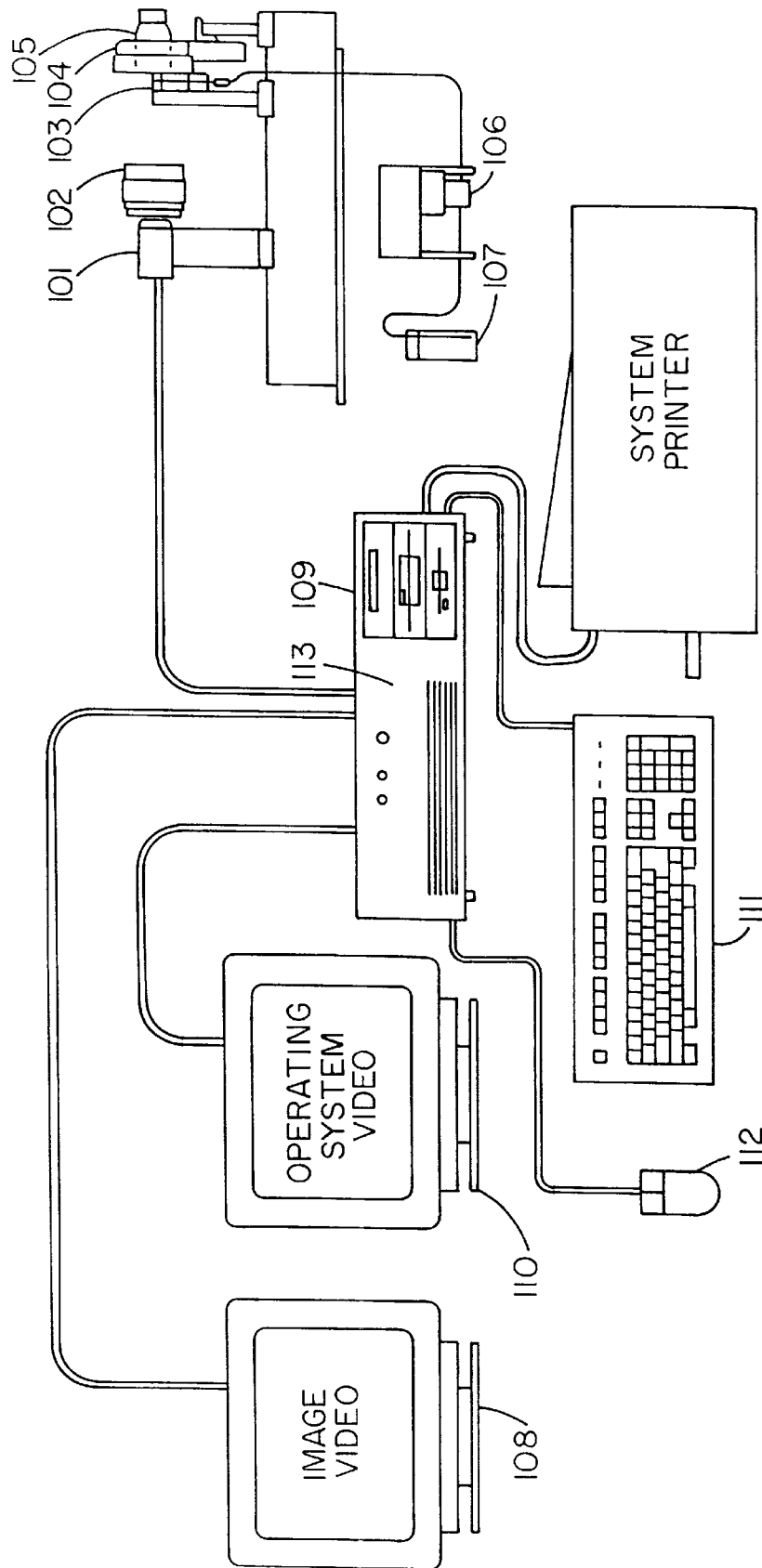


Fig. 25

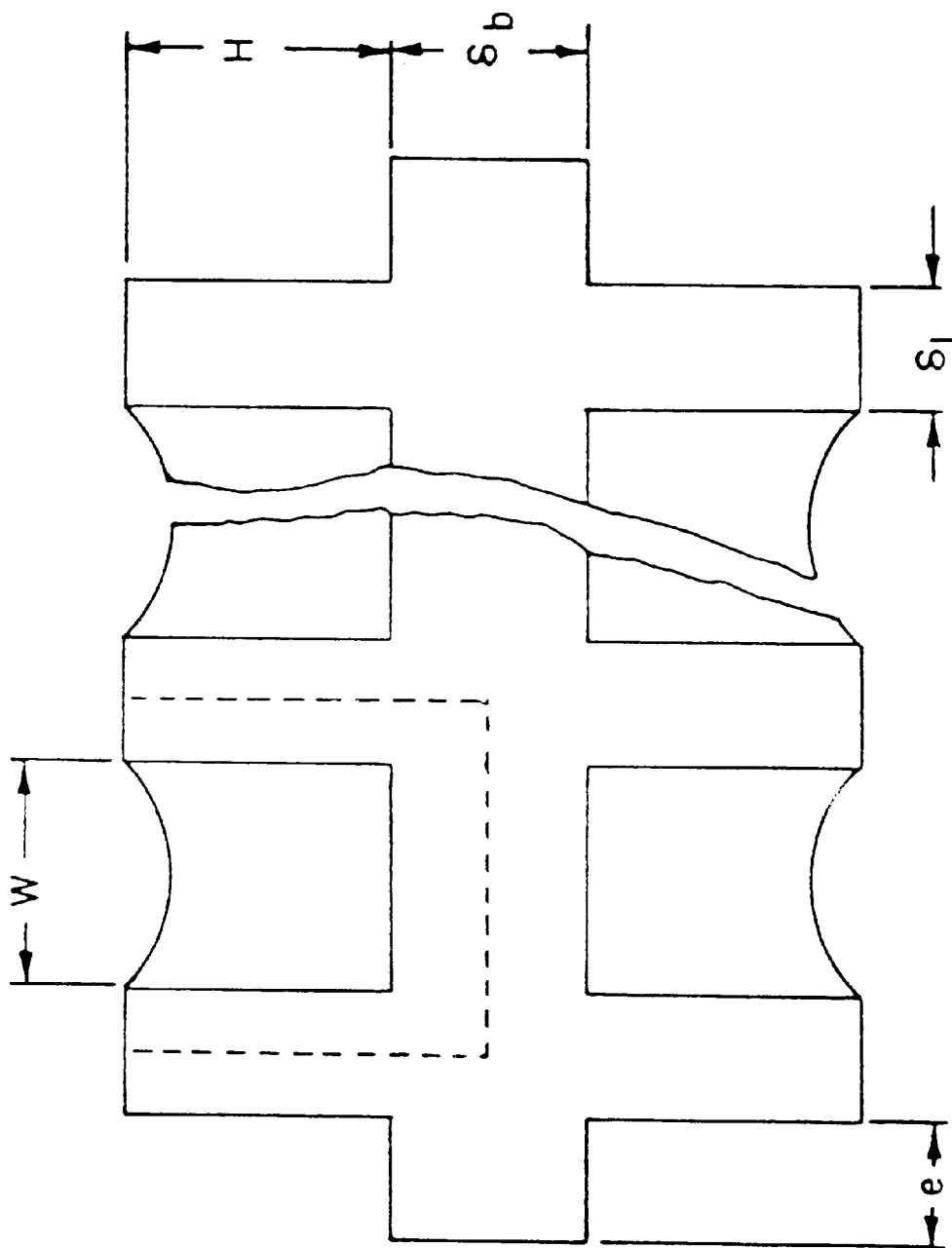


Fig. 26

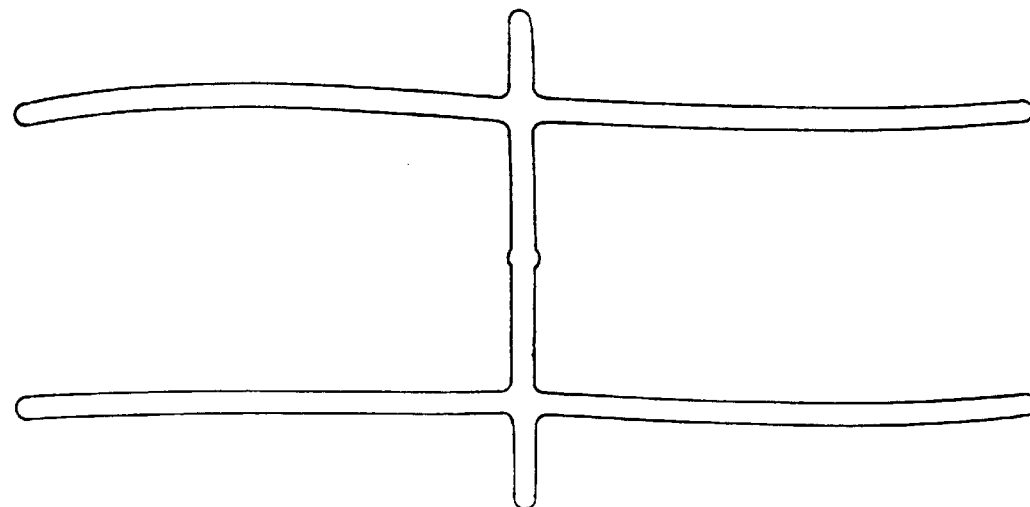


Fig. 27 B

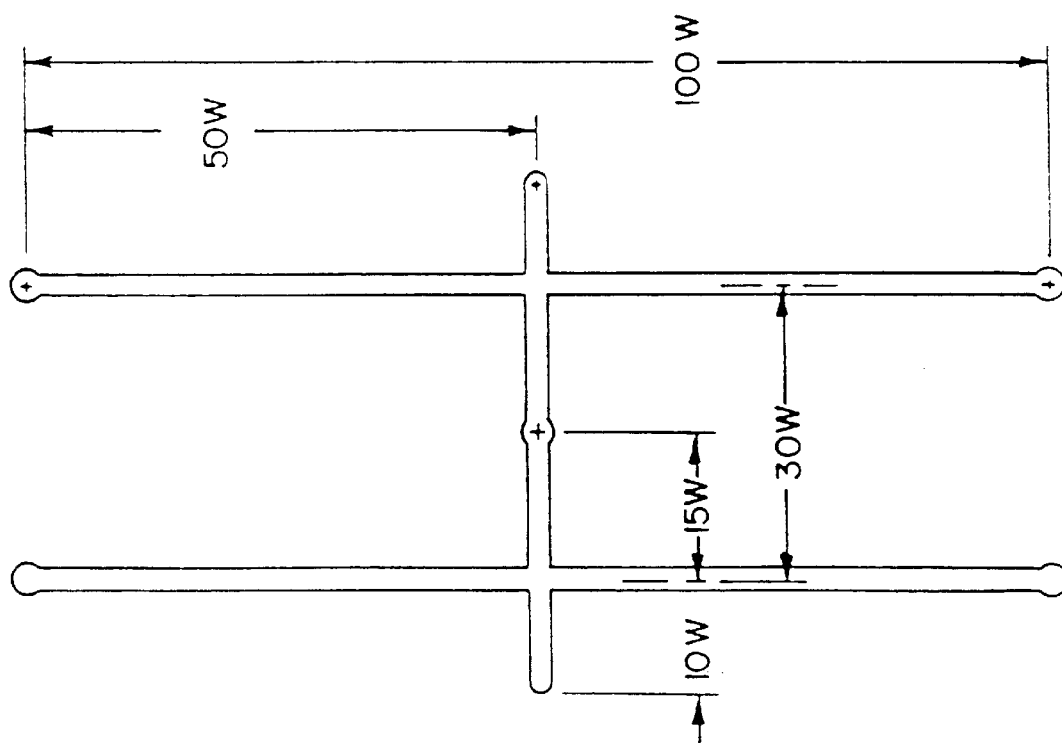
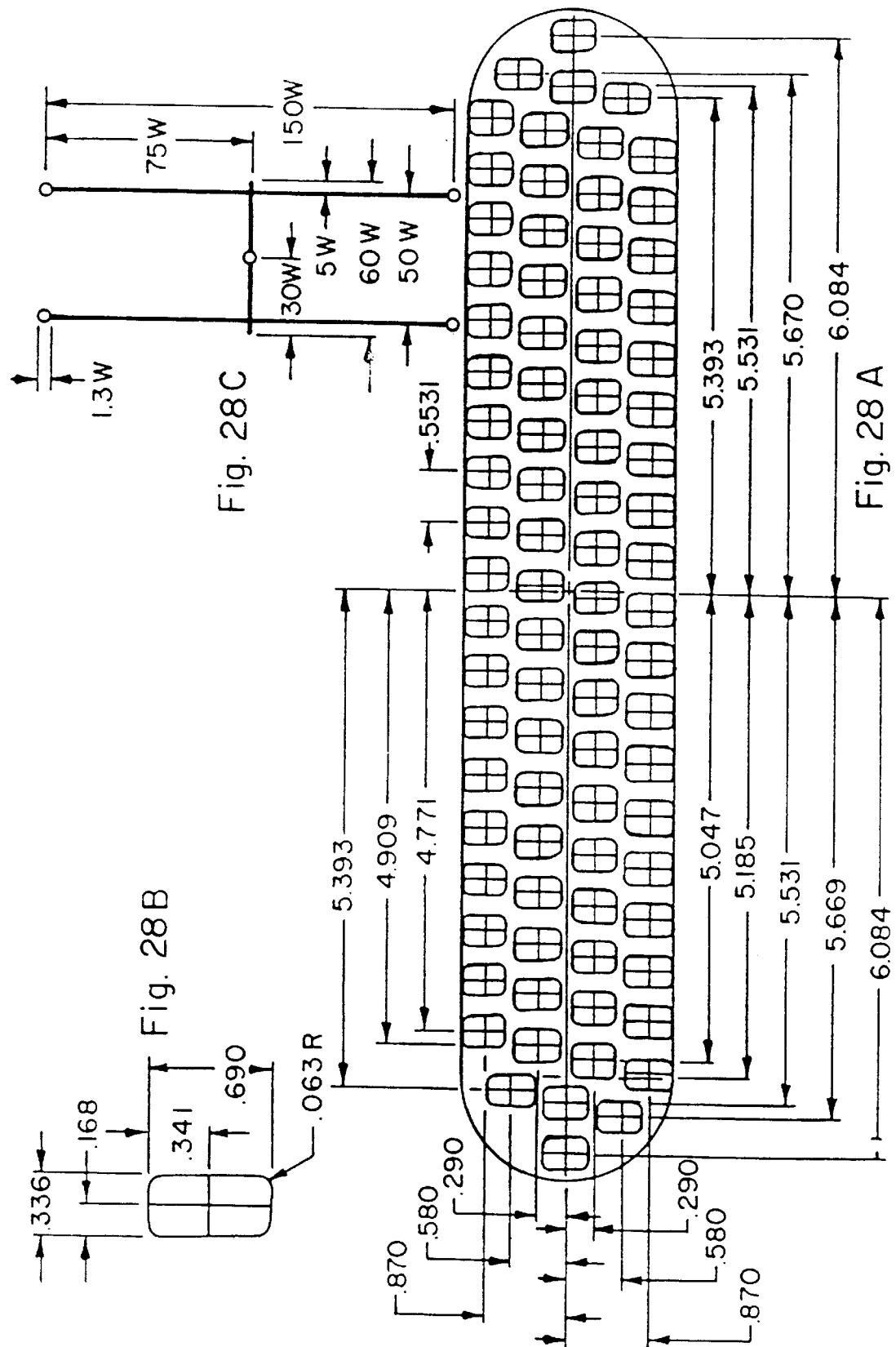


Fig. 27A



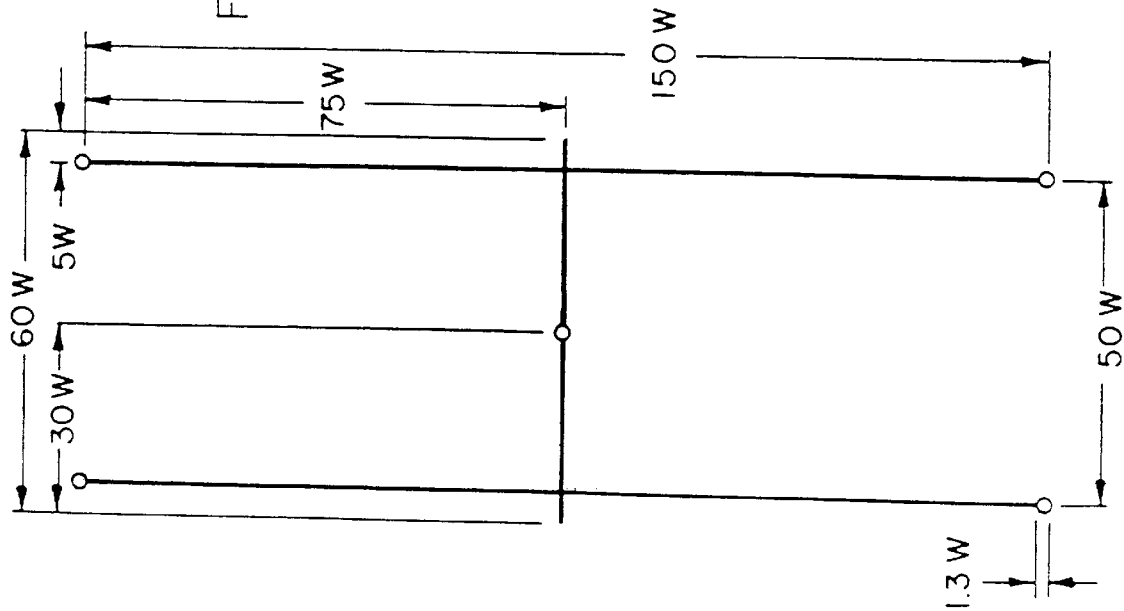


Fig. 29 A

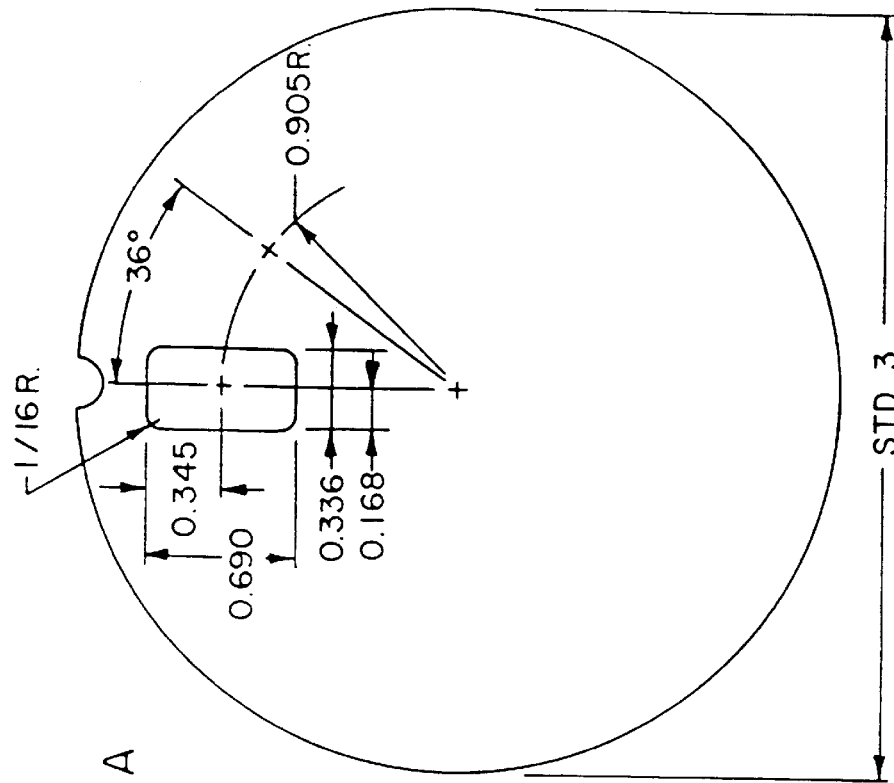


Fig. 29 B

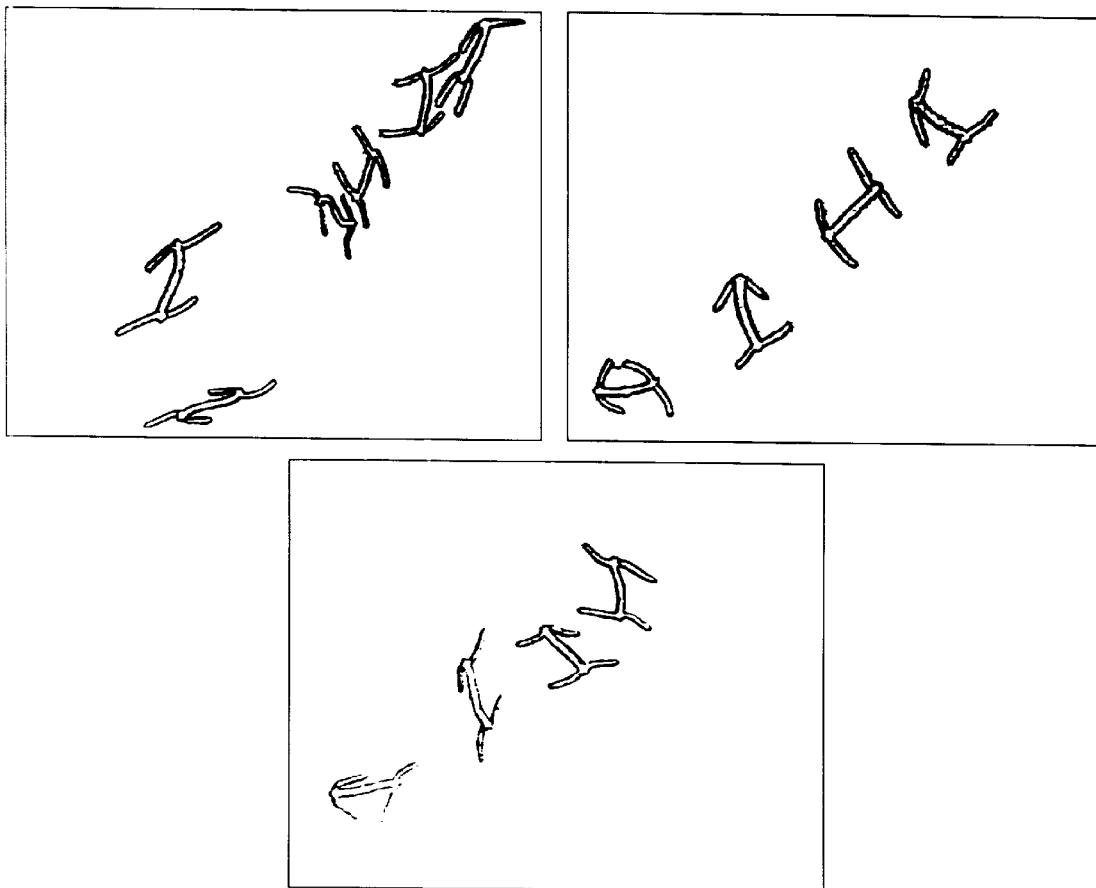


Fig. 30

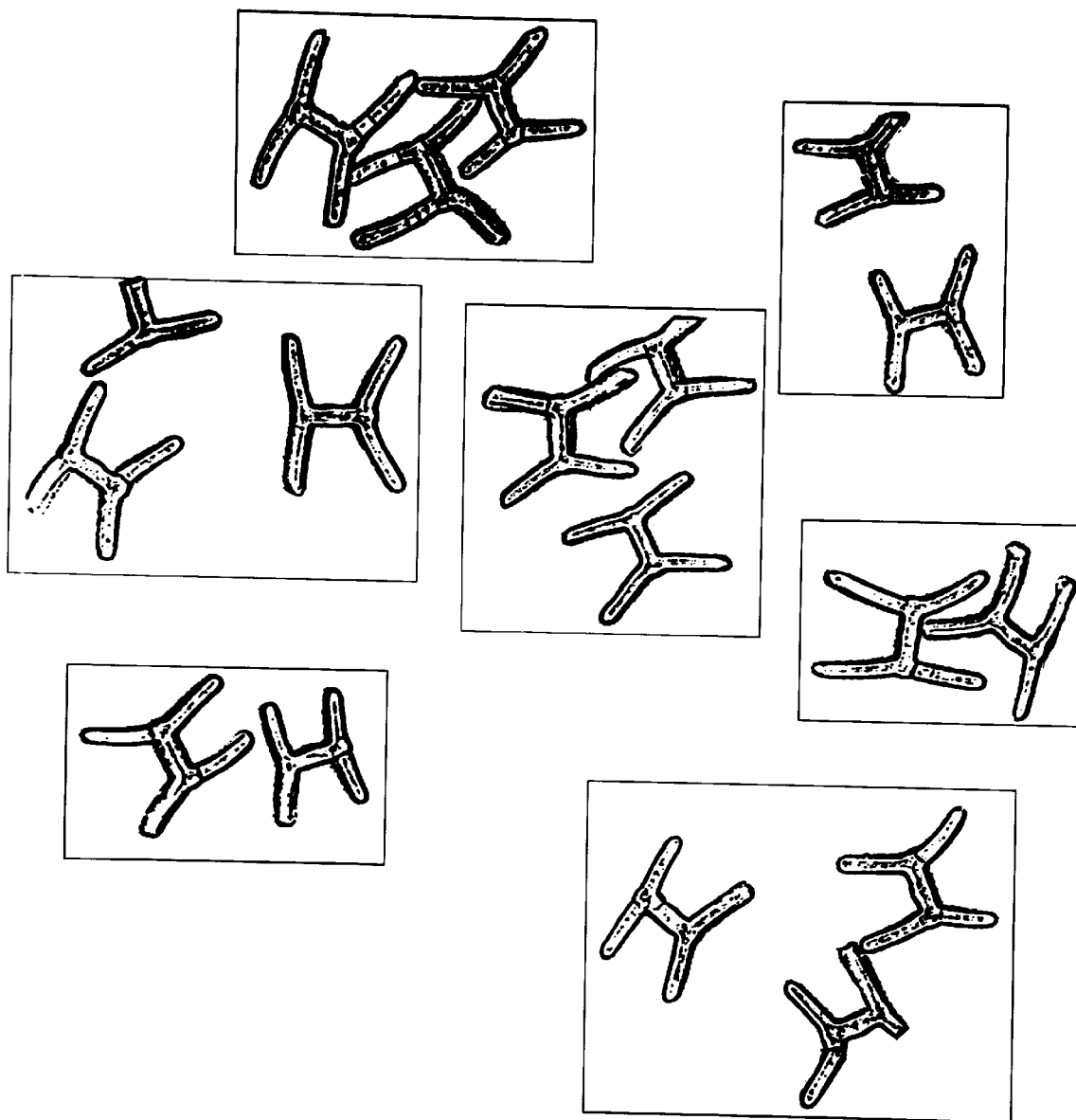


Fig. 31

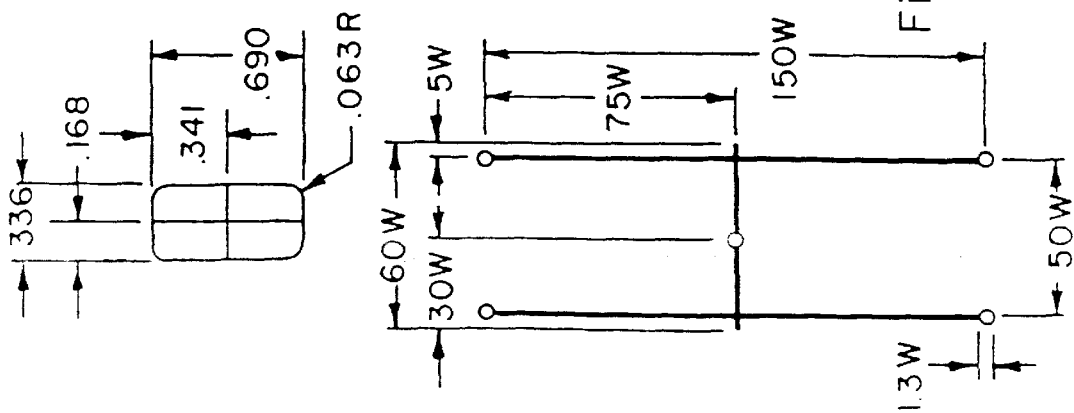
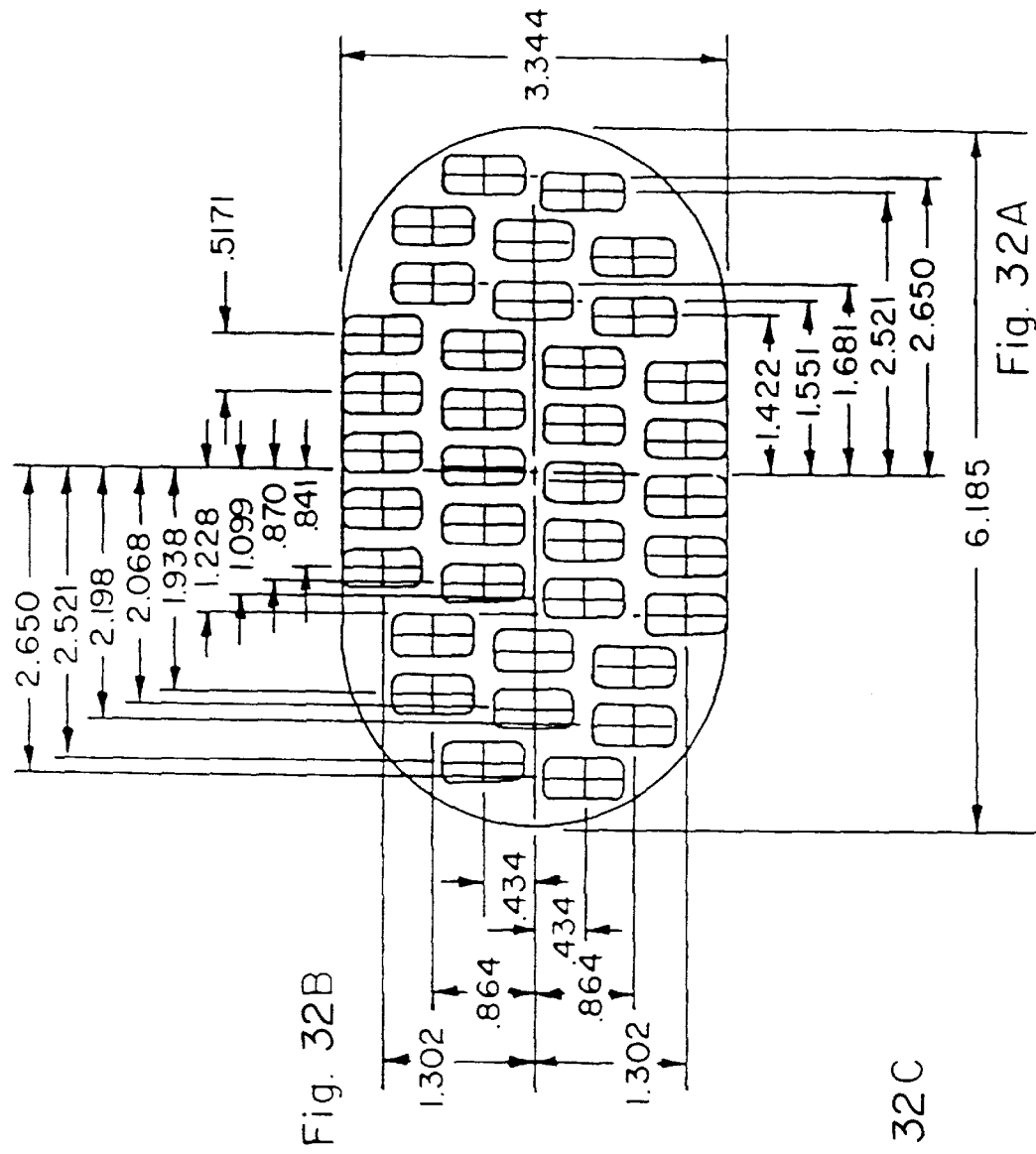
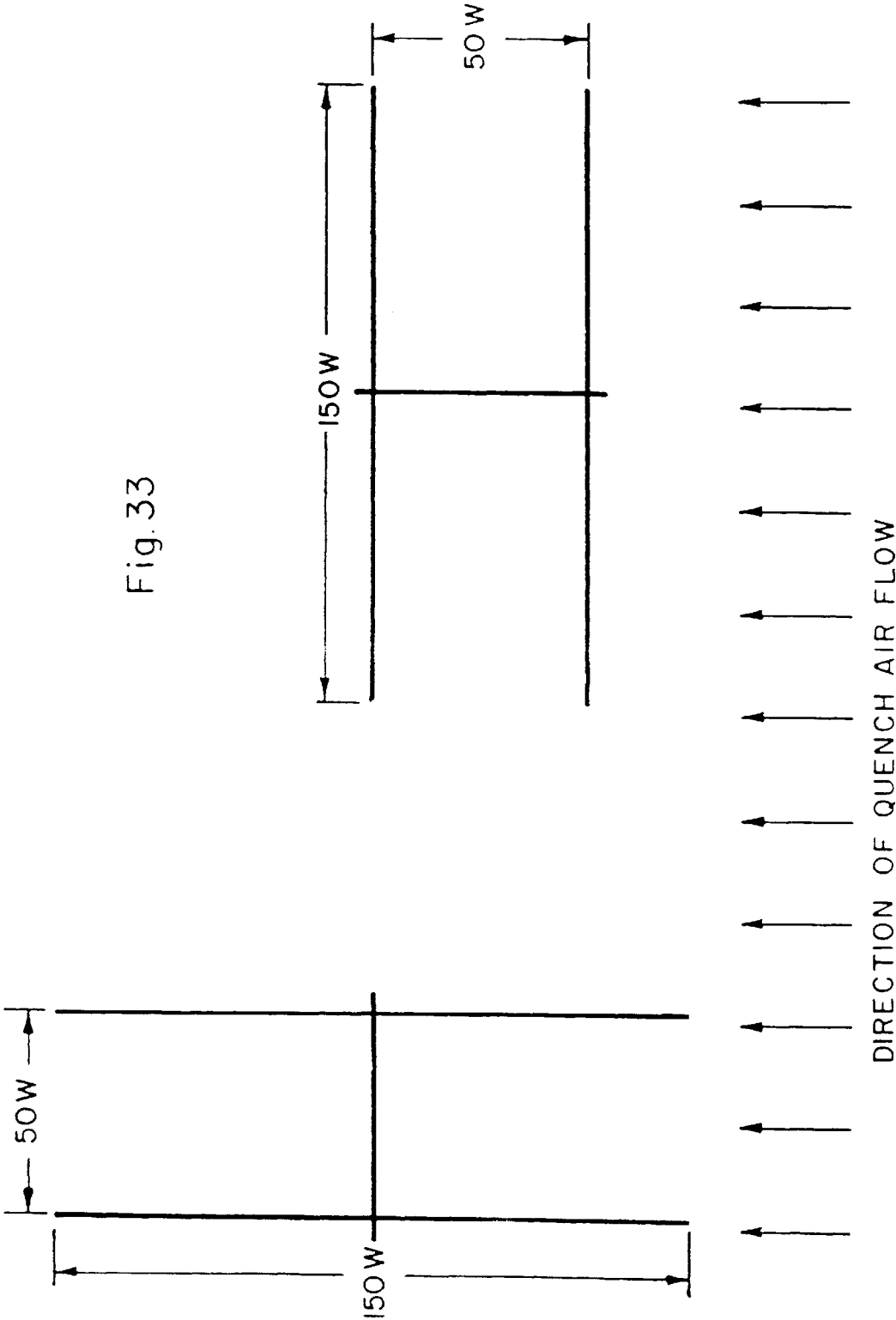
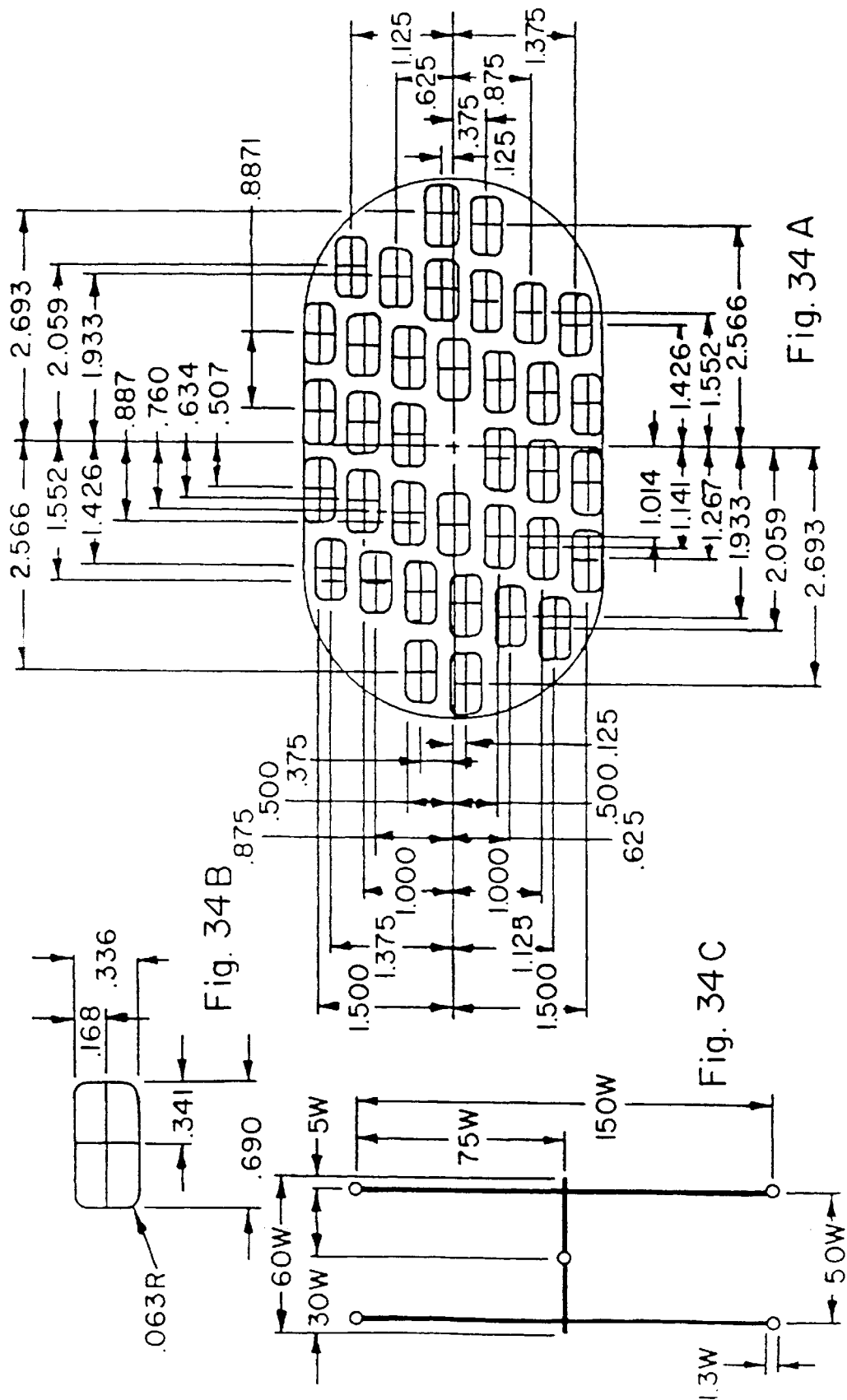


Fig. 33





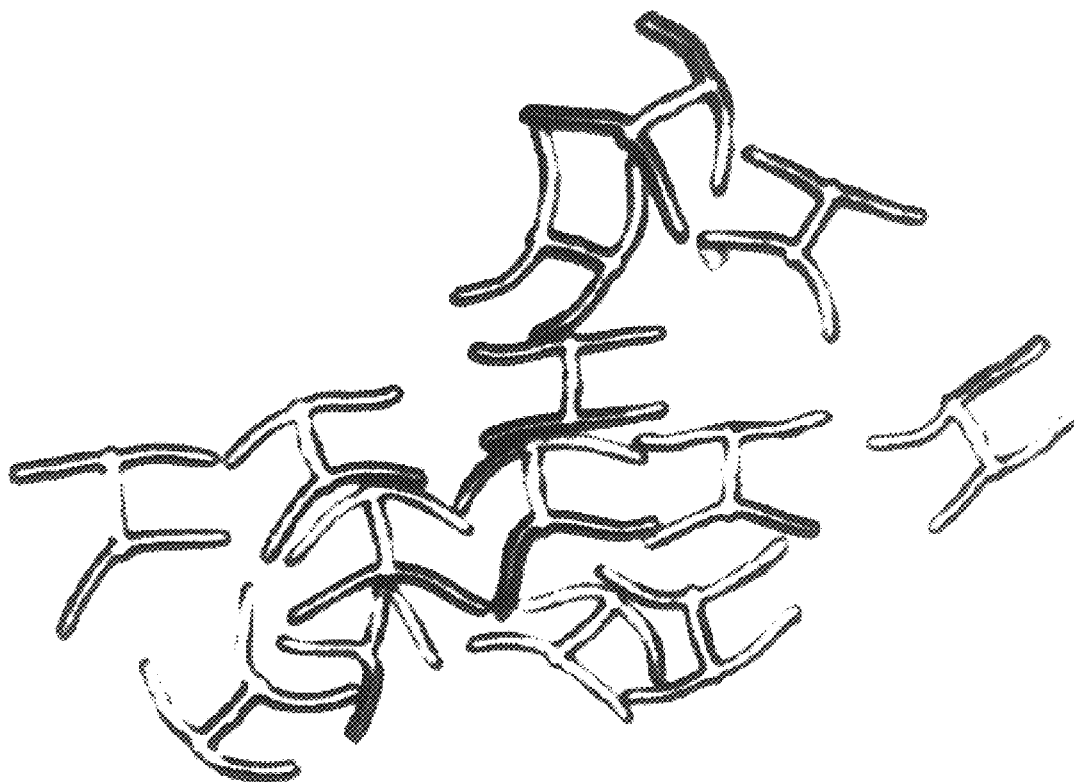


Fig. 35

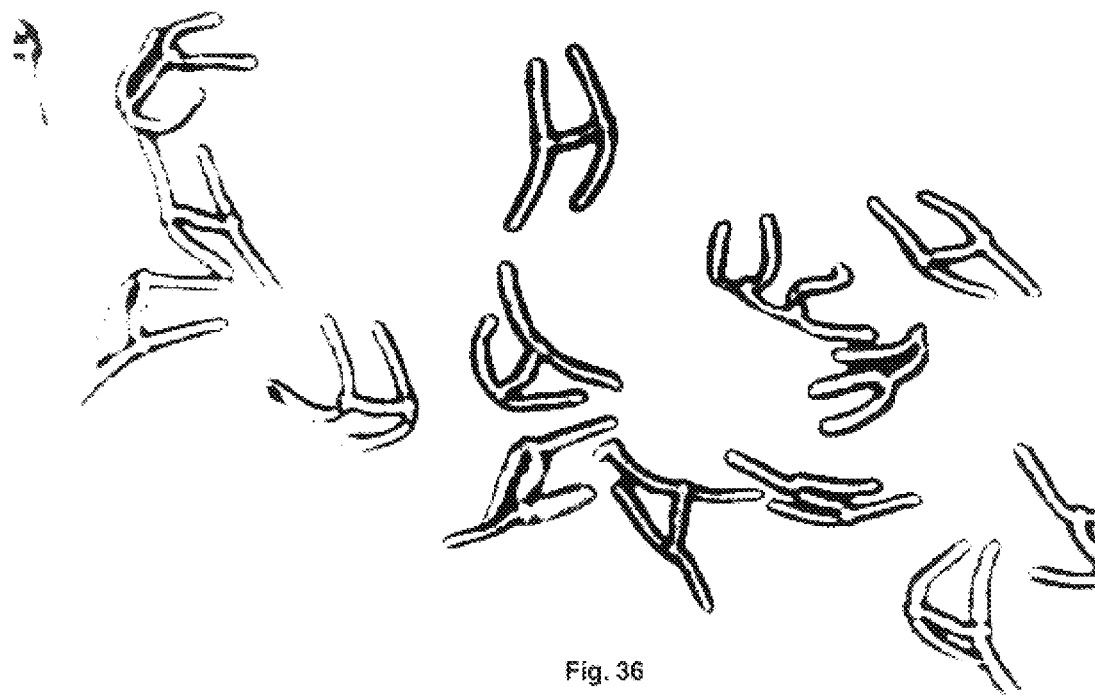


Fig. 36

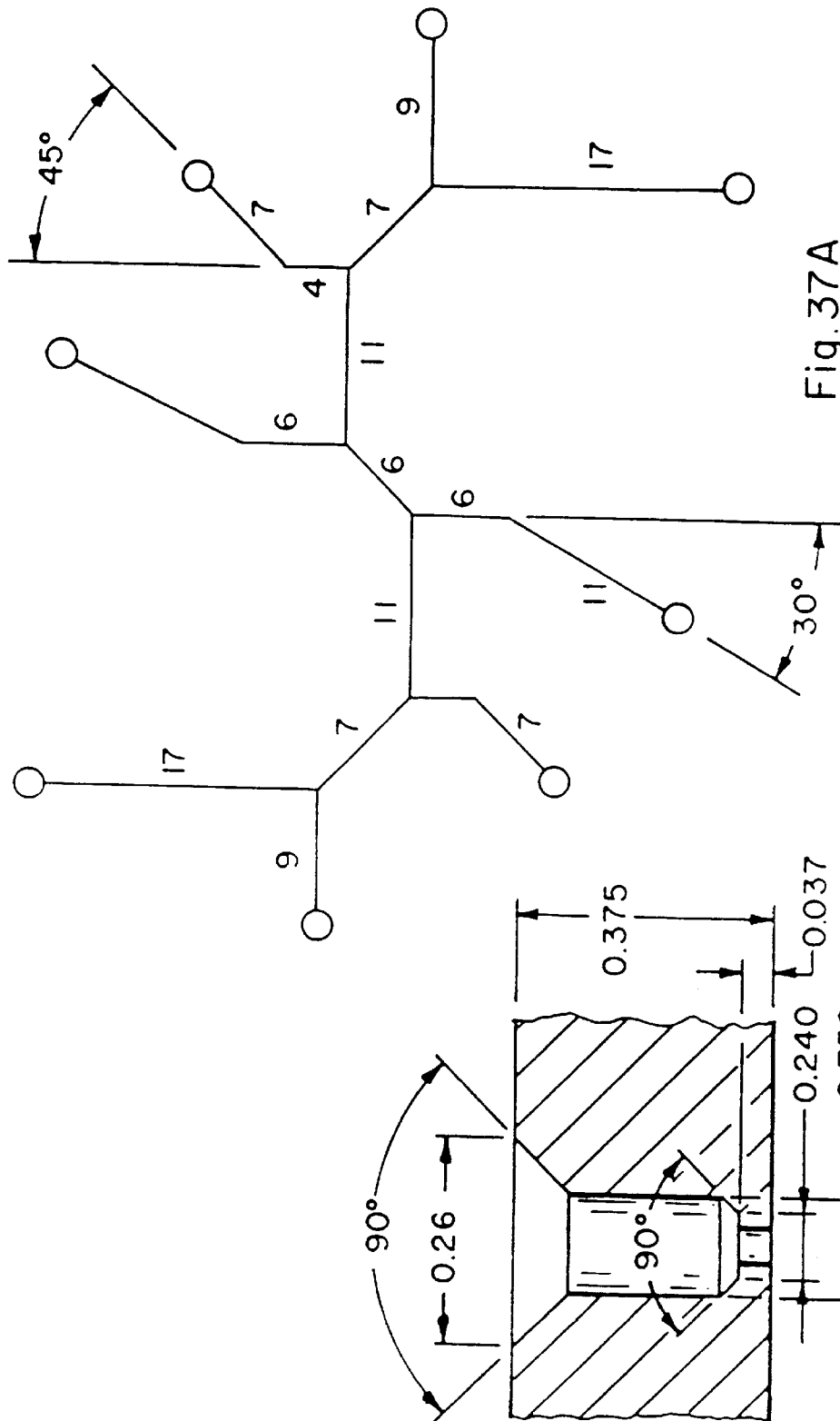


Fig. 37 B

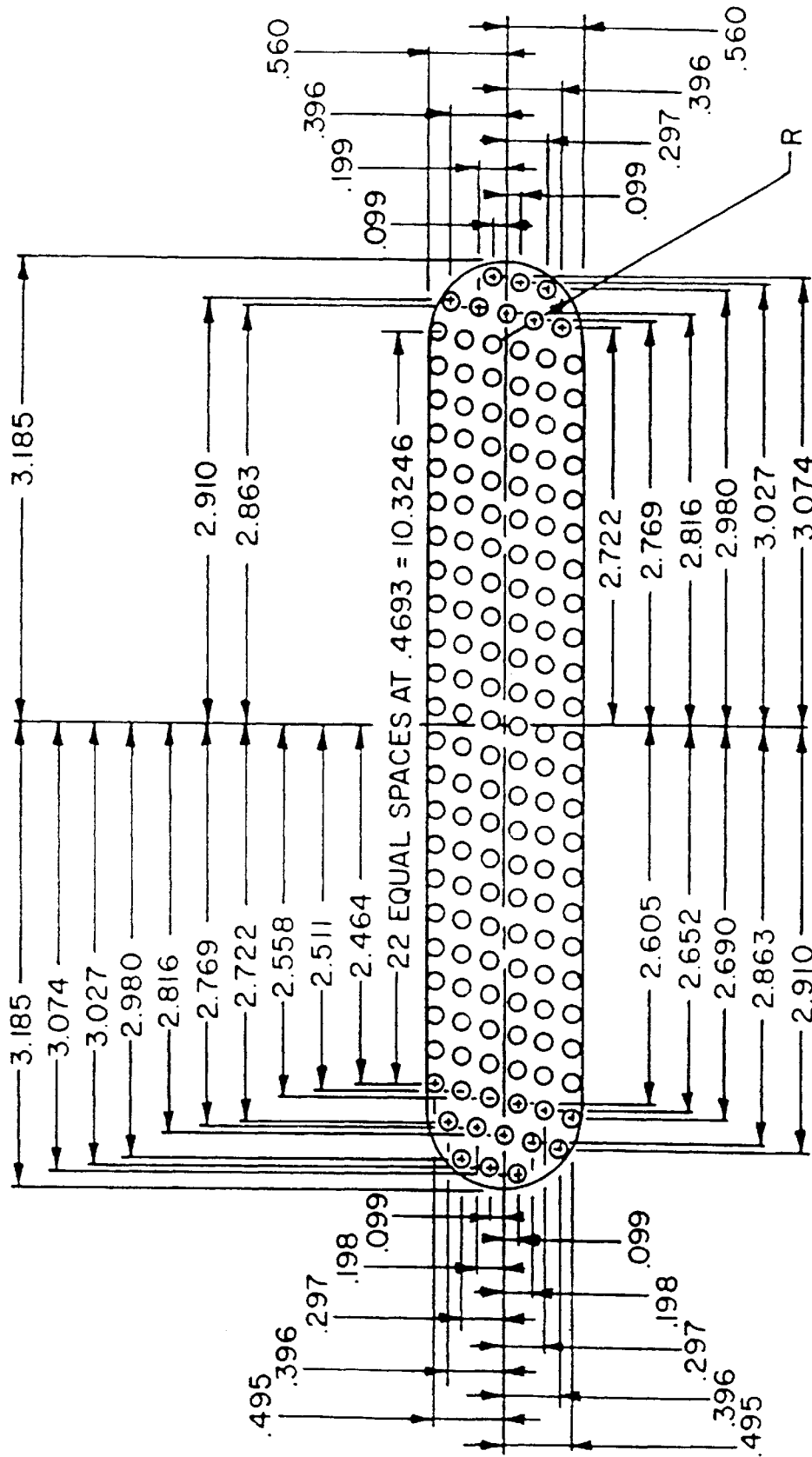
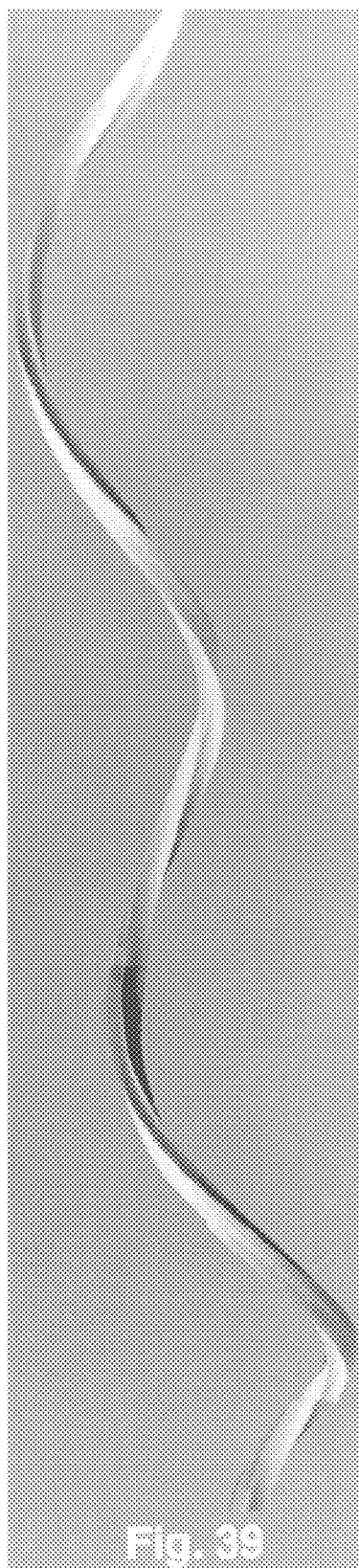


Fig. 38



ABSORBENT HEAD BAND**TECHNICAL FIELD**

The present invention relates to absorbent head bands made of a sliver of spontaneously wettable fibers. The head bands according to this invention are especially useful for protecting human skin and eyes from contact with liquids used in cosmetology.

BACKGROUND OF THE INVENTION

The management of hair involves the use of many fluids which can irritate the eyes and skin. In particular, people may have "permanents" or have their hair colored in some way and these treatments involve the use of potentially irritating fluids. In an attempt to minimize the eye and/or skin irritation from these fluids, absorbent head bands, usually made from cotton or rayon, are wrapped around the head to absorb the excess fluid. These absorbent bands are then discarded after use. Two deficiencies of "cotton" wraps are the fragile nature of band and the inability of the band to remove the fluid from contact with the skin. This invention provides improvements in both of these areas. Current manufactured products are carded cotton sliver which may or may not be reinforced with some means to increase integrity of the sliver.

Patents of interest include U.S. Pat. Nos. 2,023,279; 3,529,308; 4,481,680; 5,133,371; 4,958,385; 4,656,671; 3,015,335 and 5,033,122. None of these patents refer to the use of capillary surface materials in the disclosed inventions.

Fibers useful in the present invention are described in detail in pending U.S. Ser. No. 736,267 filed Jul. 23, 1991; Ser. No. 133,426 filed Oct. 8, 1993, and European Patent No. WO92/00407. Although these documents disclose that the fibers may be used in head bands, they do not disclose the characteristics of the head band now being claimed. Pertinent portions of specifications from these documents are contained in the present specification under the heading "Fibers".

Presently available absorbent articles and the like are generally adequate at absorbing aqueous fluids. However, during typical use such articles become saturated at the impingement zone while other zones removed from the impingement zone will remain dry. As a result, a substantial portion of the total absorbent capabilities of such articles remains unused. Thus, it would be highly desirable to have a means for transporting the aqueous fluids from the impingement zone to other areas of the absorbent article to more fully utilize the article's total absorbent capability. We have discovered such a means by the use of certain fibers that are capable of transporting aqueous fluids on their surfaces.

Liquid transport behavior phenomena in single fibers has been studied to a limited extent in the prior art (see, for example, A. M. Schwartz & F. W. Minor, *J. Coll. Sci.*, 14, 572 (1959)).

There are several factors which influence the flow of liquids in fibrous structures. The geometry of the pore-structure in the fabrics (capillarity), the nature of the solid surface (surface free energy, contact angle), the geometry of the solid surface (surface roughness, grooves, etc.), the

chemical/physical treatment of the solid surface (caustic hydrolysis, plasma treatment, grafting, application of hydrophobic/hydrophilic finishes), and the chemical nature of the fluid all can influence liquid transport phenomena in fibrous structures.

French Patent 955,625, Paul Chevalier, "Improvements in Spinning Artificial Fiber", published Jan. 16, 1950, discloses fibers of synthetic origin with alleged improved capillarity. The fibers are said to have continuous or discontinuous grooves positioned in the longitudinal direction.

Also, the art discloses various H-shapes, for example, in the following U.S. Pat. Nos. 3,121,040; 3,650,659; 870,280; 4,179,259; 3,249,669; 3,623,939; 3,156,607; 3,109,195; 3,383,276; 4,707,409.

U.S. Pat. No. 4,707,409 describes a spinneret having an orifice defined by two intersecting slots and each intersecting slot in turn defined by three quadrilateral sections connected in series.

Further, PCT International Publication No. WO90/12/30, published on Oct. 18, 1990, entitled "Fibers Capable of Spontaneously Transporting Fluids" discloses fibers that are capable of spontaneously transporting water on their surfaces and useful structures made from such fibers.

We have discovered head bands of particular fibers that have a unique combination of properties that allows for spontaneous transport of aqueous fluids such as water on their surfaces.

DESCRIPTION OF THE INVENTION

The present invention provides an absorbent head band for protecting skin and eyes from irritation or other unpleasant sensations caused by contact with liquids used in cosmetology comprising a sliver of spontaneously wettable fibers, the sliver having a size of about 30,000–100,000 denier, the fibers of the sliver being held together by a binder such as to have a tensile strength of between 100 and 2,000 grams, the fibers having a denier per filament (dpf) of about 3–30, a staple length of about 1½–6 inches, a shape factor of about 1.5–5 and a maximum potential flux of at least 75 cc/g/hr when measured using a liquid having a surface tension of about 60–65 dynes/cm and a viscosity of about 1 cp.

Headband Description

The head bands according to the present invention comprise a sliver of spontaneously wettable fibers. By the term "sliver", we mean a continuous length of carded fibers arranged in a generally parallel relationship, the sliver being about 30,000–100,000 denier, and preferably about 40,000–60,000 denier. The fibers have a staple length of about 1½–6 inches, preferably about 2–3, and are lightly bound together by a binder such that the sliver has a tensile strength of about 100–2000 grams, preferably about 100–1000 grams. Tensile strength of the sliver is important in permitting portions of it, of suitable length to form an individual headband, to be pulled apart from a larger length with a minimum of effort.

The binder used in the head bands of this invention may be any of those well known in the art, such as a powder or preferably, a binder fiber. It is relatively low melting, such

that it can be melted or converted to a sticky state well below the melting point of the spontaneously wettable fibers in the head band. It is important that the binder result in a tensile strength as described so that the sliver has the required integrity but, at the same time, can easily be torn by the user from a continuous length at convenient point for particular requirements. Suitable binders include polyester binder fibers used in amounts of about 2–15%, based on the weight of the sliver.

The fibers in the sliver are spontaneously wettable, i.e., they have a shape factor of about 1.5–5 and a maximum potential flux of at least 75 cc/g/hr when measured using a liquid having a surface tension of about 60–65 dynes/cm and a viscosity of about 1 cp. The preferred liquid used for this measurement is an easily visible liquid such as Syllint Poly Red tint solution from Milliken which has a surface tension of about 62 dynes/cm.

Fiber Description

The fibers useful in the present invention satisfy the following equation

$$(1-X \cos \theta_a) < 0,$$

wherein

θ_a is the advancing contact angle of water measured on a flat film made from the same material as the fiber and having the same surface treatment, if any,

X is a shape factor of the fiber cross-section that satisfies the following equation

$$x = \frac{P_w}{4r + (\pi - 2)D}$$

wherein

P_w is the wetted perimeter of the fiber and r is the radius of the circumscribed circle circumscribing the fiber cross-section and D is the minor axis dimension across the fiber cross-section.

The fibers useful in the present invention preferably satisfy the equation

$$(1-X \cos \theta_a) < -0.7,$$

wherein

θ_a is the advancing contact angle of water measured on a flat film made from the same material as the fiber and having the same surface treatment, if any,

X is a shape factor of the fiber cross-section that satisfies the following equation

$$x = \frac{P_w}{4r + (\pi - 2)D}$$

wherein

P_w is the wetted perimeter of the fiber and r is the radius of the circumscribed circle circumscribing the fiber cross-section and D is the minor axis dimension across the fiber cross-section.

The present invention also further provides a head band using synthetic fibers which are capable of spontaneously transporting water on the surface thereof wherein said fiber satisfies the equation

$$(1-X \cos \theta_a) < 0,$$

wherein

θ_a is the advancing contact angle of water measured on a flat film made from the same material as the fiber and having the same surface treatment, if any,

X is a shape factor of the fiber cross-section that satisfies the following equation

$$x = \frac{P_w}{4r + (\pi - 2)D}$$

wherein

P_w is the wetted perimeter of the fiber and r is the radius of the circumscribed circle circumscribing the fiber cross-section and D is the minor axis dimension across the fiber cross-section,

and wherein the maximum potential flux of said fiber is at least 75 cc/g/hr when measured using a liquid having a surface tension of about 60–65 dynes/cm² and a viscosity of about 1 cp.

It is preferred that X is greater than 1.2, preferably between about 1.2 and about 5, most preferably between about 1.5 and about 3.

Further, it is preferred that the fiber has a hydrophilic lubricant coated on the surface thereof.

Fibers useful in the present invention are also described in Thompson U.S. Pat. No. 5,200,248, incorporated herein by reference.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1A—illustration of the behavior of a drop of an aqueous fluid on a conventional fiber that is not spontaneously transportable after the ellipsoidal shape forms ($t=0$). Angle θ illustrates a typical contact angle of a drop of liquid on a fiber. The arrows labelled “LFA” indicate the location of the liquid-fiber-air interface.

FIG. 1B—illustration of the behavior of a drop of an aqueous fluid on a conventional fiber that is not spontaneously transportable at time= t_1 ($t_1>0$). The angle θ remains the same as in FIG. 1A. The arrows labelled “LFA” indicate the location of the liquid-fiber-air interface.

FIG. 1C—illustration of the behavior of a drop of an aqueous fluid on a conventional fiber that is not spontaneously surface transportable at time= t_2 ($t_2>t_1$). The angle θ remains the same as in FIG. 1A. The arrows labelled “LFA” indicate the location of the liquid-fiber-air interface.

FIG. 2A—illustration of the behavior of a drop of an aqueous fluid which has just contacted a fiber that is spontaneously transportable at time= 0 . The arrows labelled “LFA” indicate the location of the liquid-fiber-air interface.

FIG. 2B—illustration of the behavior of a drop of an aqueous fluid on a fiber that is spontaneously transportable at time= t_1 ($t_1>0$). The arrows labelled “LFA” indicate the location of the liquid-fiber-air interface.

FIG. 2C—illustration of the behavior of a drop of an aqueous fluid on a fiber that is spontaneously transportable at time= t_2 ($t_2>t_1$). The arrows labelled “LFA” indicate the location of the liquid-fiber-air interface.

FIG. 3—schematic representation of an orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 4—schematic representation of an orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 5—schematic representation of an orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 6—schematic representation of an orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 6B—schematic representation of an orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 7—schematic representation of an orifice of a spinneret having 2 repeating units, joined end to end, of the orifice as shown in FIG. 3.

FIG. 8—schematic representation of an orifice of a spinneret having 4 repeating units, joined end to end, of the orifice as shown in FIG. 3.

FIG. 9—photomicrograph of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 3.

FIG. 10—photomicrograph of a polypropylene fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 3.

FIG. 11—photomicrograph of a nylon 66 fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 3.

FIG. 12—schematic representation of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 4.

FIG. 13—photomicrograph of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 5.

FIG. 14—photomicrograph of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 7.

FIG. 15—photomicrograph of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 8.

FIG. 16—schematic representation of a fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 3. Exemplified is a typical means of determining the shape factor X.

FIG. 17—photomicrograph of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 6.

FIG. 17B—schematic representation of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 6B.

FIG. 18A—a schematic representation of a desirable groove in a fiber cross-section.

FIG. 18B—a schematic representation of a desirable groove in a fiber cross-section.

FIG. 18C—a schematic representation of a desirable groove in a fiber cross-section illustrating the groove completely filled with fluid.

FIG. 19A—a schematic representation of a groove where bridging is possible in the fiber cross-section.

FIG. 19B—a schematic representation of a groove where bridging is possible in the fiber cross-section.

FIG. 19C—a schematic representation of a groove illustrating bridging of the groove by a fluid.

FIG. 20—a schematic representation of a preferred “H” shape orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 21—a schematic representation of a poly(ethylene terephthalate) fiber cross-section made using a spinneret having an orifice as illustrated in FIG. 20.

FIGS. 22A and 22B—a schematic representation of a preferred “H” shape orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIGS. 23A and 23B—a schematic representation of a preferred “H” shape orifice of a spinneret useful for producing a spontaneously transportable fiber.

FIG. 24—graph of maximum flux in cc/hr/g vs. adhesion tension for a poly(ethylene terephthalate) having an “H” shape cross-section with two unit cells or channels wherein each channel depth is 143μ and the leg thickness of each channel is 10.9μ .

FIG. 25—a schematic representation of the apparatus used to determine maximum potential flux.

FIG. 26—a schematic representation depicting a unit cell.

FIGS. 27A and 27B—a schematic representation of a spinneret having dimensions as specified.

FIGS. 28A and 28B—a schematic representation of Spinneret I1045 wherein the spinneret holes are oriented such that the cross-flow quench air is directed toward the open end of the H. All dimensions are in units of inches except those containing the letter “W”.

FIGS. 29A and 29B—a schematic representation of Spinneret I1039 wherein the spinneret holes are oriented in a radial pattern on the face of the spinneret. All dimensions are in units of inches except those containing the letter “W”.

FIG. 30—a photomicrograph of stuffer box crimped fiber having a distorted cross-section.

FIG. 31—a photomicrograph of a cross-section of a helically crimped fiber formed by the process of helically crimping a fiber of this invention wherein the fiber cross-section is not distorted.

FIGS. 32A, 32B and 32C—a schematic representation of Spinneret I 1046 wherein the spinneret holes are oriented such that the cross-flow quench air is directed toward the open end of the H.

FIG. 33—a schematic representation of quench air direction relative to the spinneret holes.

FIGS. 34A, 34B and 34C—a schematic representation of Spinneret 1047 wherein spinneret holes are oriented such that the cross-flow quench air was directed toward one side of the H.

FIG. 35—a photomicrograph of helically crimped fibers of the invention without a distorted cross-section.

FIG. 36—a photomicrograph of stuffer box crimped fiber having a distorted cross-section.

FIGS. 37A, 37B and 38—a schematic representation of a spinneret wherein the spinneret holes are oriented in a diagonal pattern on the face of the spinneret with cross-flow quenching directed toward the fiber bundle.

FIG. 39—a photomicrograph of a helically crimped fiber prepared by the process of the invention.

The three important variables fundamental to the liquid transport behavior are (a) wettability or the contact angle of the liquid with the solid, (b) surface tension of the liquid, and (c) the geometry of the solid surface.

Typically, the wettability of a solid surface by a liquid can be characterized by the contact angle that the liquid surface (gas-liquid interface) makes with the solid surface (gas-solid interface). Typically, a drop of liquid placed on a solid surface makes a contact angle, θ , with the solid surface, as seen in FIG. 1A. If this contact angle is less than 90° , then the solid is considered to be wet by the liquid. However, if the contact angle is greater than 90° , such as with water on Teflon surface, the solid is not wet by the liquid. Thus, it is desired to have a minimum contact angle for enhanced wetting, but definitely, it must be less than 90° . However, the contact angle also depends on surface inhomogeneities (chemical and physical, such as roughness), contamination, chemical/physical treatment of the solid surface, as well as the nature of the liquid surface and its contamination. Surface free energy of the solid also influences the wetting behavior. The lower the surface energy of the solid, the more difficult it is to wet the solid by liquids having high surface tension. Thus, for example, Teflon, which has low surface energy does not wet with water. (Contact angle for Teflon-water system is 112° .) However, it is possible to treat the surface of Teflon with a monomolecular film of protein, which significantly enhances the wetting behavior. Thus, it is possible to modify the surface energy of fiber surfaces by appropriate lubricants/finishes to enhance liquid transport. The contact angle of polyethylene terephthalate (PET), Nylon 66, and polypropylene with water is 80° , 71° , and 108° , respectively. Thus, Nylon 66 is more wettable than PET. However, for polypropylene, the contact angle is $>90^\circ$, and thus is non-wettable with water.

Another property of fundamental importance to the phenomena of liquid transport is the geometry of the solid surface. Although it is known that grooves enhance fluid transport in general, we have discovered particular geometries and arrangements of deep and narrow grooves on fibers and treatments thereof which allow for the spontaneous surface transport of aqueous fluids in single fibers. Thus we have discovered fibers with a combination of properties wherein an individual fiber is capable of spontaneously transporting water on its surface.

The particular geometry of the deep and narrow grooves is very important. For example, as shown in FIGS. 18A, 18B and 18C, grooves which have the feature that the width of the groove at any depth is equal to or less than the width of the groove at the mouth of the groove are preferred over those grooves which do not meet this criterion (e.g., grooves as shown in FIGS. 19A, 19B and 19C). If the preferred groove is not achieved, "bridging" of the liquid across the restriction is possible and thereby the effective wetted perimeter (Pw) is reduced. Accordingly, it is preferred that Pw is substantially equal to the geometric perimeter.

"Spontaneously transportable" and derivative terms thereof refer to the behavior of a fluid in general and in particular a drop of fluid, typically water, when it is brought into contact with a single fiber such that the drop spreads

along the fiber. Such behavior is contrasted with the normal behavior of the drop which forms a static ellipsoidal shape with a unique contact angle at the intersection of the liquid and the solid fiber. It is obvious that the formation of the ellipsoidal drop takes a very short time but remains stationary thereafter. FIGS. 1A–1C and 2A–2C illustrate the fundamental difference in these two behaviors. Particularly, FIGS. 2A, 2B, and 2C illustrate spontaneous fluid transport on a fiber surface. The key factor is the movement of the location of the air, liquid, solid interface with time. If such interface moves just after contact of the liquid with the fiber, then the fiber is spontaneously transportable; if such interface is stationary, the fiber is not spontaneously transportable. The spontaneously transportable phenomenon is easily visible to the naked eye for large filaments [>20 denier per filament (dpf)] but a microscope may be necessary to view the fibers if they are less than 20 dpf. Colored fluids are more easily seen but the spontaneously transportable phenomenon is not dependent on the color. It is possible to have sections of the circumference of the fiber on which the fluid moves faster than other sections. In such case the air, liquid, solid interface actually extends over a length of the fiber. Thus, such fibers are also spontaneously transportable in that the air, liquid, solid interface is moving as opposed to stationary.

Spontaneous transportability is basically a surface phenomenon; that is the movement of the fluid occurs on the surface of the fiber. However, it is possible and may in some cases be desirable to have the spontaneously transportable phenomenon occur in conjunction with absorption of the fluid into the fiber. The behavior visible to the naked eye will depend on the relative rate of absorption vs. spontaneous transportability. For example, if the relative rate of absorption is large such that most of the fluid is absorbed into the fiber, the liquid drop will disappear with very little movement of the air, liquid, solid interface along the fiber surface whereas if the rate of absorption is small compared to the rate of spontaneous transportability the observed behavior will be like that depicted in FIGS. 2A through 2C. In FIG. 2A, a drop of aqueous fluid is just placed on the fiber (time=0). In FIG. 2B, a time interval has elapsed (time= t_1) and the fluid starts to be spontaneously transported. In FIG. 2C, a second time interval has passed (time= t_2) and the fluid has been spontaneously transported along the fiber surface further than at time= t_1 .

It has also been discovered that for a given vertical distance and linear distance to move the fluid, a given channel depth and a given adhesion tension, there is an optimum channel width which maximizes the uphill flux of the liquid being transported.

A fiber of the invention can be characterized as having one or more "channels" or "unit cells". For example, the fiber cross-section shown in FIG. 26 depicts a unit cell. A unit cell is the smallest effective transporting unit contained within a fiber. For fibers with all grooves identical, the total fiber is the sum of all unit cells. In FIG. 26 each unit cell has a height, H, and a width, W. S_l is the leg thickness and S_b is the backbone thickness. In addition to the specific dimensions of W and H, the other dimensional parameters of the cross-section are important for obtaining the desired type of spontaneous transportability. For example, it has been found that the number of channels and the thickness of the areas

between unit cells, among other things, are important for optimizing the maximum potential flux of the fiber. For obtaining a fiber cross-section of desirable or optimal fluid movement properties the following equations are useful:

$$q = \frac{W^2}{K\mu M_f} \cdot \frac{1}{l} \left(\alpha \gamma p \cos \theta - \beta \gamma \omega - \frac{\rho g h}{g_c} A \right) \times 3600$$

$$M_f = \rho_f A_f L_f; K = 12$$

$$A_f = \frac{1}{n} \left\{ \left[(2H + S_b) \frac{S_l}{2} + W \frac{S_b}{2} \right] n + 2 \left[(2H + S_b) \frac{S_l}{2} + e \cdot S_b \right] \right\}$$

$$p = 2H + W$$

$$\omega = \frac{\pi(90 - \theta)}{180 \sin(90 - \theta)} \cdot W$$

$$h = l \sin \theta$$

$$A = H \cdot W - \frac{W^2}{4 \sin(90 - \theta)} \left[\frac{\pi(90 - \theta)}{180 \sin(90 - \theta)} - \cos(90 - \theta) \right]$$

$$dpf = \rho_f A_f \cdot n \cdot (9000)(100)$$

wherein:

q=flux (cm³/hr-gm)
W=channel width (cm)
μ=fluid viscosity (gm/cm-sec)
M_f=fiber mass per channel (gm)
ρ_f=fiber density (gm/cm³)
A_f=fiber cross-sectional area per channel (cm²)
L_f=total fiber length (cm)
l=distance front has advanced along fiber (cm)
α=adhesion tension correction factor (surface) (d' less)
γ=fluid surface tension (dynes/cm-gm/sec²)
p=wetted channel perimeter (cm)
H=channel depth (cm)
θ=contact angle (degrees)
β=adhesion tension correction factor (bulk) (d' less)
K=constant (d' less)
ω=arc length along meniscus (cm)
ρ=fluid density (gm/cm³)
g=acceleration of gravity (cm/sec²)
h=vertical distance (cm)
g_c=gravitational constant (d' less)
A=fluid cross-sectional area per channel (cm²)
n=number of channels (d' less)
S_b=fiber body or backbone thickness (cm)
S_f=fiber leg thickness (cm)
e=backbone extension (cm)
ø=fiber horizontal inclination angle (degrees)
dpf=denier per filament (gm/9000 m)

The equation for q is useful for predicting flux for a channeled fiber horizontally inclined at an angle ø. This equation contains all the important variables related to fiber geometry, fiber physical properties, physical properties of the fluid being transported, the effects of gravity, and surface properties related to the three-way interaction of the surfactant, the material from which the fiber is made, and the transported fluid. The equations for M_f, A_f, p, ω, h, and A can be substituted into the equation for q to obtain a single functional equation containing all the important system variables, or, for mathematical calculations, the equations

can be used individually to calculate the necessary quantities for flux prediction.

The equation for q (including the additional equations mentioned above) is particularly useful for determining the optimum channel width to maximize uphill flux (fluid movement against the adverse effects of gravity; sin ø>0 in the equation for h). The equation for q is also useful for calculating values for downhill flux (fluid movement enhanced by gravity; sin ø<0 in the equation for h) for which there is no optimum channel width. Obviously, horizontal flux can also be calculated (no gravity effects; sin ø=0). The equation for q and the equations for p, A, and A_f were derived for a fiber containing one or more rectangularly-shaped channels, but the basic principles used to derive these equations could be applied to channels having a wide variety of geometries.

A fiber of the present invention is capable of spontaneously transporting water on the surface thereof. Distilled water can be employed to test the spontaneous transportability phenomenon; however, it is often desirable to incorporate a minor amount of a colorant into the water to better visualize the spontaneous transport of the water, so long as the water with colorant behaves substantially the same as pure water under test conditions. We have found aqueous Syllint Poly Red solution from Milliken Chemicals to be a useful solution to test the spontaneous transportability phenomenon. The Syllint Poly Red solution can be used undiluted or diluted significantly, e.g., up to about 50x with water.

In addition to being capable of transporting water, fibers used in the present invention are also capable of spontaneously transporting a multitude of other fluids. Preferred aqueous fluids are body fluids, especially human body fluids. Such preferred fluids include, but are not limited to, blood, perspiration, and the like. Fluids commonly used in hair styling are also of interest.

In addition to being able to transport aqueous fluids, fibers useful in the present invention are also capable of transporting an alcoholic fluid on its surface. Alcoholic fluids are those fluids comprising greater than about 50% by weight of an alcoholic compound of the formula



wherein R is an aliphatic or aromatic group containing up to 12 carbon atoms. It is preferred that R is an alkyl group of 1 to 6 carbon atoms, more preferred is 1 to 4 carbon atoms. Examples of alcohols include methanol, ethanol, n-propanol and isopropanol. Preferred alcoholic fluids comprise about 70% or more by weight of a suitable alcohol. Preferred alcoholic fluids include antimicrobial agents, such as disinfectants, and alcohol-based inks.

The fibers used in the present invention can be comprised of any material known in the art capable of having a cross-section of the desired geometry and capable of being coated or treated so as to reduce the contact angle to an acceptable level. Preferred materials for use in the present invention are polyesters.

The preferred polyester materials useful in the present invention are polyesters or copolyesters that are well known in the art and can be prepared using standard techniques, such as, by polymerizing dicarboxylic acids or esters thereof and glycols. The dicarboxylic acid compounds used in the

production of polyesters and copolyesters are well known to those skilled in the art and illustratively include terephthalic acid, isophthalic acid, p,p'-diphenyldicarboxylic acid, p,p'-dicarboxydiphenylethane, p,p'-dicarboxydiphenylhexane, p,p'-dicarboxydiphenyl ether, p,p'-dicarboxyphenoxyethane, and the like, and the dialkylesters thereof that contain from 1 to about 5 carbon atoms in the alkyl groups thereof.

Suitable aliphatic glycols for the production of polyesters and copolyesters are the acyclic and alicyclic aliphatic glycols having from 2 to 10 carbon atoms, especially those represented by the general formula $\text{HO}(\text{CH}_2)_p\text{OH}$, wherein p is an integer having a value of from 2 to about 10, such as ethylene glycol, trimethylene glycol, tetramethylene glycol, and pentamethylene glycol, decamethylene glycol, and the like.

Other known suitable aliphatic glycols include 1,4-cyclohexanedimethanol, 3-ethyl-1,5-pentanediol, 1,4-xylylene glycol, 2,2,4,4-tetramethyl-1,3-cyclobutanediol, and the like. One can also have present a hydroxylcarboxyl compound such as 4-hydroxybenzoic acid, 4-hydroxyethoxybenzoic acid, or any of the other hydroxylcarboxyl compounds known as useful to those skilled in the art.

It is also known that mixtures of the above dicarboxylic acid compounds or mixtures of the aliphatic glycols can be used and that a minor amount of the dicarboxylic acid component, generally up to about 10 mole percent, can be replaced by other acids or modifiers such as adipic acid, sebacic acid, or the esters thereof, or with modifiers that impart improved dyeability to the polymers. In addition one can also include pigments, delusterants or optical brighteners by the known procedures and in the known amounts.

The most preferred polyester for use in preparing the fibers of the present invention is poly(ethylene terephthalate) (PET).

Other materials that can be used to make the fibers of the present invention include polyamides such as a nylon, e.g., nylon 66 or nylon 6; polypropylene; polyethylene; and cellulose esters such as cellulose triacetate or cellulose diacetate.

A single fiber of the present invention preferably has a denier of between about 3 and about 30, more preferred is between about 4 and about 15.

Fiber shape and fiber/fluid interface variables can be manipulated to increase fluid transport rate per unit weight of fiber (flux) by accomplishing the following:

- using less polymer by making the fiber cross-sectional area smaller (thinner legs, walls, backbones, etc., which form the channeled structure);
- moderately increasing channel depth-to-width ratio;
- changing (increasing or decreasing) channel width to the optimum width, and
- increasing adhesion tension, $\alpha \cos \theta$, at the channel wall by the proper selection of a lubricant for the fiber surface (which results primarily in a decrease in the contact angle at the wall without a significant lowering of the fluid surface tension at the wall).

The fibers useful in the present invention preferably have a surface treatment applied thereto. Such surface treatment may or may not be critical to obtain the required spontaneous transportability property. The nature and criticality of such surface treatment for any given fiber can be determined

by a skilled artisan through routine experimentation using techniques known in the art and/or disclosed herein. A preferred surface treatment is a coating of a hydrophilic lubricant on the surface of the fiber. Such coating is typically uniformly applied at about a level of at least 0.05 weight percent, with about 0.1 to about 2 weight percent being preferred. Preferred hydrophilic lubricants include polyoxyethylene lauryl ether, polyoxyethylene oleyl ether, polyoxylene-polyoxypropylene-sorbitan linoleic phthalic ester, Milease T, and a potassium lauryl phosphate based lubricant comprising about 70 weight percent poly(ethylene glycol) 600 monolaurate. Many surfactants provide very good wetting of surfaces by lowering fluid surface tension and decreasing contact angle and thereby yield low adhesion tension at the surface. Therefore, it is important that the surfactant possess some attraction for the polyester surface (hydrophobic) and also for water (hydrophilic). It is also preferred that the surfactant bind tightly to the polyester surface and at the same time present high hydrophilicity to the water side of the interface. Another surface treatment is to subject the fibers to oxygen plasma treatment, as taught in, for example, *Plastics Finishing and Decoration*, Chapter 4, Ed. Don Satas, Van Nostrand Reinhold Company (1986).

Typical surfactants are listed in the following table:

SYMBOL	SURFACTANT DESCRIPTION
BRIJ35	Polyoxyethylene (23) lauryl ether (ICI) HLB = 16.9
BRIJ99	Polyoxyethylene (20) oleyl ether (ICI) HLB = 15.3
BRIJ700	Polyoxyethylene (100) stearyl ether (ICI) HLB = 18.8
G1300	G-1300 Polyoxyethylene glyceride ester (ICI) Nionic surfactant HLB = 18.1
G1350	"ATLAS" G-1350 (ICI) Polyoxyethylene-polyoxypropylene-sorbitan linoleic phthalic ester
G-1441	G-1441 (ICI) Polyoxyethylene (40) sorbitol, lanolin alcoholysis product
HPMA109	Hypermer A109 (ICI) Modified Polyester Surfactant (98%)/Xylene (2%) HLB = 13-15
IL2535L1	IL-2535 "Xylene-free/TMA free" Hypermer A109 (ICI) Modified polyester surfactant (HA = high acid no.)
IL2535L2	IL-2535 "Xylene-free/TMA free" Hypermer A109 (ICI) Modified polyester surfactant (LA = low acid no.)
1L2535L3	IL-2535 "Xylene-free/TMA free" Hypermer A109 (ICI) Modified polyester surfactant (LA = low acid no.)
1L2535L4	IL-2535 "Xylene-free/TMA free" Hypermer A109 (ICI) Modified polyester surfactant (LA = low acid no.)
MIL T	MILEASE T (ICI) Polyester/water/other ingredients
RX20 RENEX 20	(ICI) Polyoxyethylene (16) tall oil (100%) (CAS-61791-002) HLB = 13.8
RX30 RENEX 30	(ICI) Polyoxyethylene (12) tridecyl alcohol (100%) (CAS 24938-91-8) HLB = 14.5
RX31 RENEX 31	(ICI) Polyoxyethylene (12) tridecyl alcohol (100%) (CAS 24938-91-8) HLB = 15.4
TL-1674	TL-1674 (ICI) Polyoxyethylene (36) castor oil (100%) (CAS 61791-12-6)
TL-1914	TL-1914 (ICI) Cocoamidopropyl Betaine (CAS-61789-40-0)
TW60 TWEEN 60	(ICI) Polyoxyethylene (20) sorbitan monostearate HLB = 14.9

The novel spinnerets of the present invention must have a specific geometry in order to produce fibers that will spontaneously transport aqueous fluids.

13

In FIG. 3, W is between 0.064 millimeters (mm) and 0.12 mm. X_2 is $4W_{-1W}^{+4W}$; X_4 is $2W \pm 0.5W$; X_6 is $6W_{-2W}^{+4W}$; X_8 is $6W_{-2W}^{+5W}$; X_{10} is $7W_{-2W}^{+5W}$; X_{12} is $9W_{-1W}^{+5W}$; X_{14} is $10W_{-2W}^{+5W}$; X_{16} is $11W_{-2W}^{+5W}$; X_{18} is $6W_{-2W}^{+5W}$; θ_2 is $30^\circ \pm 30^\circ$; θ_4 is $45^\circ \pm 45^\circ$; θ_6 is $30^\circ \pm 30^\circ$; and θ_8 is $45^\circ \pm 45^\circ$.

In FIG. 4, W is between 0.064 mm and 0.12 mm; X_{20} is $17W_{-2W}^{+5W}$; X_{22} is $3W \pm W$; X_{24} is $4W \pm 2W$; X_{26} is $60W_{-4W}^{+8W}$; X_{28} is $17W_{-2W}^{+5W}$; X_{30} is $2W \pm 0.5W$; X_{32} is $72W_{-5W}^{+10W}$; and θ_{10} is $45^\circ \pm 15^\circ$. In addition, each Leg B can vary in length from 0 to

$$\frac{X_{26}}{2};$$

and each Leg A can vary in length from 0 to

$$\tan(90 - \theta_{10}) \left[\frac{X_{26}}{2} - X_{24} \right].$$

In FIG. 5, W is between 0.064 mm and 0.12 mm; X_{34} is $2W \pm 0.5W$; X_{36} is $58W_{-10W}^{+20W}$; X_{38} is $24W_{-6W}^{+20W}$; θ_{12} is $20^\circ_{-10^\circ}^{+15^\circ}$;

$$\theta_{14} \text{ is } \frac{180^\circ - 2\theta_{12}}{n - 1};$$

and n=number of legs per $180^\circ=2$ to 6.

In FIG. 6, W is between 0.064 mm and 0.12 mm; X_{42} is $6W_{-2W}^{+4W}$; X_{44} is $11W \pm 5W$; X_{46} is $11W \pm 5W$; X_{48} is $24W \pm 10W$; X_{50} is $38W \pm 13W$; X_{52} is $3W_{-1W}^{+3W}$; X_{54} is $6W_{-2W}^{+6W}$; X_{56} is $11W \pm 5W$; X_{58} is $7W \pm 5W$; X_{60} is $17W \pm 7W$; X_{62} is $28W \pm 11W$; X_{64} is $24W \pm 10W$; X_{66} is $17W \pm 7W$; X_{68} is $2W \pm 0.5W$; θ_{16} is $45^\circ_{-15^\circ}^{+30^\circ}$; θ_{18} is $45^\circ \pm 15^\circ$; and θ_{20} is $45^\circ \pm 15^\circ$.

In FIG. 6B, W is between 0.064 mm and 0.12 mm, X_{72} is $8W_{-2W}^{+4W}$; X_{74} is $8W_{-2W}^{+4W}$; X_{76} is $12W \pm 4W$; X_{78} is $8W \pm 4W$; X_{80} is $24W \pm 12W$; X_{82} is $18W \pm 6W$; X_{84} is $8W_{-2W}^{+4W}$; X_{86} is $16W \pm 6W$; X_{88} is $24W \pm 12W$; X_{90} is $18W \pm 6W$; X_{92} is $2W \pm 0.5W$; θ_{22} is $135^\circ \pm 30^\circ$; θ_{24} is $90^\circ_{-30^\circ}^{+45^\circ}$; θ_{26} is $45^\circ \pm 15^\circ$; θ_{28} is $45^\circ \pm 15^\circ$; θ_{30} is $45^\circ \pm 15^\circ$; θ_{32} is $45^\circ \pm 15^\circ$; θ_{34} is $45^\circ \pm 15^\circ$; θ_{36} is $45^\circ \pm 15^\circ$; and θ_{38} is $45^\circ \pm 15^\circ$.

In FIG. 7, the depicted spinneret orifice contains two repeat units of the spinneret orifice depicted in FIG. 3, therefore, the same dimensions for FIG. 3 apply to FIG. 7. Likewise, in FIG. 8, the depicted spinneret orifice contains four repeat units of the spinneret orifice depicted in FIG. 3, therefore, the same dimension for FIG. 3 applies to FIG. 8.

FIG. 20 depicts a preferred "H" shape spinneret orifice of the invention. In FIG. 20 W_1 is between 60 and 150μ , θ is between 80° and 120° , S is between 1 and 20, R is between 10 and 100, T is between 10 and 300, U is between 1 and 25, and V is between 10 and 100. In FIG. 20 it is more preferred that W_1 is between 65 and 100μ , θ is between 900 and 1100, S is between 5 and 10, R is between 30 and 75, T is between 30 and 80, U is between 1.5 and 2, and V is between 30 and 75.

FIG. 21 depicts a poly(ethylene terephthalate fiber cross-section made from the spinneret orifice of FIG. 20. In FIG. 21 W_2 is less than 20μ , W_3 is between 10 and 300μ , W_4 is between 20 and 200μ , W_5 is between 5 and 50μ , and W_6 is between 20 and 200μ . In FIG. 21 it is more preferred that W_2

14

is less than 10μ , W_3 is between 20 and 100μ , W_4 is between 20 and 100μ , and W_5 is between 5 and 20μ .

FIG. 16 illustrates the method for determining the shape factor, X, of the fiber cross-section. In FIG. 16, $r=37.5$ mm, $P_w=355.1$ mm, $D=49.6$ mm; thus, for the fiber cross-section of FIG. 16:

$$X = \frac{355.1}{4 \times 37.5 + (\pi - 2)49.6} = 1.72.$$

The fibers useful in the present invention can be in the form of crimped or uncrimped staple fibers.

The fibers of the headband can be substantially parallel to the major axis thereof.

The absorbent headbands of the present invention can be made by use of techniques known in the art, for example in U.S. Pat. Nos. 4,573,986; 3,938,522; 4,102,340; 4,044,768; 4,282,874; 4,285,342; 4,333,463; 4,731,066; 4,681,577; 4,685,914; and 4,654,040; and/or by techniques disclosed herein.

Maximum Potential Flux Test

This method describes a single filament wetting test instrument that will aid the process of designing new fibers by providing detailed experimental data which can be used to evaluate design changes or to test theoretical relationships. This measurement system is based on computer image analysis. A video camera coupled to a computer automatically senses when fluid is provided to the filament and then follows the advance of the fluid interface over a period of time. The fluid interface position vs. time is recorded for subsequent plotting and further analysis. Consistent fluid delivery is achieved by use of a metering pump. The image analysis based spontaneous wetting test instrument includes a light source, a video camera, a metered fluid delivery system, an image monitor, a computer with an image processing board, application specific software, a video graphic printer, and precision mounting hardware (FIG. 25). The fluorescent ring light provides uniform bright illumination of the fiber while providing a viewing path for the camera. The metered pump consistently delivers the proper amount of fluid to the fiber at the press of a button. The imaging board within the computer captures an image from the video camera for processing and display. The computer analyzes the digital image to extract the fluid interface vs. time information which is the primary raw output of this device. This, and other information, is displayed graphically on the image monitor. The system components illustrated in FIG. 25 are as follows:

- 101 NEC TI-324A CCD camera
- 102 AF Micro Nikon 60 mm lens with 62 mm dark green filter
- 103 Fluid dispensing tip
- 104 Fluorescent light ring with opal diffusing glass
- 105 Light diffuser
- 106 FMI pump
- 107 Fluid reservoir
- 108 NEC/multisync II image monitor
- 109 Gateway 2000 486/33C computer,
- 110 Monitor
- 111 Keyboard

15

112 Mouse

113 Matrox IP8 imaging board

Maximum potential flux is one characterization of single filaments which exhibit spontaneous wetting behavior. The method used for calculating maximum potential flux employs the use of values from: 1) fiber geometry (cross sectional area of fluid-moving channels in square centimeters), 2) mass of 20 cm of filament in grams (which is proportional to denier per filament and 3) initial fluid velocity in cm per hour. The maximum potential flux is defined as the product of area for flow times initial velocity divided by the mass of a 20 cm length of fiber, i.e.,

$$\text{mpf} = (\text{C1} \times \text{velocity} \times \text{area for flow}) + \text{denier of fiber}$$
 expressed as cc/gm of fiber/hr where C1 is a conversion factor.

The single filament wettability test is used to determine the initial fluid velocity of spontaneously wettable fibers. The computer controlled test is initiated by the operator. A drop of colored fluid is presented from beneath the filament through a specially designed tip by a metered pump. A video camera in front of the fiber sends the signal to the computer and the fluid movement is displayed on the imaging monitor. The fluid front position vs. time curve is determined over a 4 second interval and the slope of the curve calculated for the first 30 data points collected. From the average slopes, average fluid velocity and flux can be calculated.

The possible sources of error are as follows:

1. Stretch filament.
2. Insufficient crimp pulled out of filament.
3. Wetting fluid has separated in the pumping system.
4. Room temperature and relative humidity are not in normal range.
5. Computer calibration is not correct.
6. Fiber imperfections cannot be resolved with contrast adjustment resulting in incorrect detection of fluid movement.
7. Image background if fiber moves during the test time.
8. Insufficient or excessive fluid volume presented to filament.
9. Contamination by body oils, work surface oils and dirt etc.

Calibration should be done any time a change has been made in the camera or lighting system, such as camera position, focus or parts using the following procedure:

1. Turn on imaging system and open the wetting program. The Single Filament Wetting window will appear.
2. Open the Calibration window by opening the file drop down menu and selecting calibration from the list.

16

3. Place the ruler in the upright position in the sample holder, adjusting the external light source so that the ruler divisions are clearly visible. Ensure that 10 millimeters is in the field of view.

4. Position the markers to enclose the 10 millimeters.

5. Point to the calculate button and click on it. The number of pixels/mm will be calculated and should be between 480 and 492.

6. Point to the OK button and click on it. The data will be saved and used in calculating the distances from the wetting routine.

7. Return to the Single Filament Wetting window.

The calibration should be confirmed daily merely by placing the ruler in the sample holder and observing that the field of view is 10 millimeters.

Procedure

1. From the single filament wetting window file menu, create a file from the Open/Create file window.
2. Place a single filament which has weights on both ends sufficient to cause tension but not stretch the filament across the mounting stand.
3. Set marker position, marker size and fluid start location.
4. Open the Data and Fit window. Adjust the lighting so that the filament is slightly darker than the background and confirm this by generating a histogram and establishing the threshold. Return to the Single Filament Wetting window.
5. Dispense a drop of fluid, point to the Do Wet button and click on it. The first 3 snaps of the test will be displayed at the bottom of the imaging screen and the real time at the top.
6. At the end of the test, the position vs. time curve (red) will be displayed along with the fitted curve (blue) and the regression curve (green) on the Data and Fit window.
7. Return to the Single Filament Wetting window and continue testing as described moving the filament to another location or changing filaments.
8. When all data has been collected, open the Microsoft Excel spreadsheet, update the curves, enter the cross-sectional channel area which is determined by adding all channel areas obtained from microscopic measurements of channel width and depth at 25× magnification and the denier per filament which is the weight in grams of 9000 meters of fiber divided by the number of filaments in the strand or bundle. The flux value will be calculated automatically.
9. Print a report and return to the SF Wetting window.

- 32 -

Documentation for the Windows Single Filament Wetting Instrument (SFW).

Computer Setup

The Matrox IP8 board uses the address range D000-DFFF for frame memory. It also uses some of the C000 space for writing to registers. So config.sys must contain the following line:

```
device=c:\windows\emm386.exe noems x=D000-DFFF
```

Also, system.ini must have EMMEXCLUDE=D000-DFFF under the [386Enh] section.

These areas must also be set as NONcachable, and 8 bit IO. On the Gateway machines do a Ctrl-Alt-Esc sequence to get into setup. For the video IO setting run install from the video directory (Ultra, Mach32, or whatever.). Config.sys also needs to load the IP8 driver:

```
device=c:\ip8\util\ip8drv.sys
```

The directory tree should include:

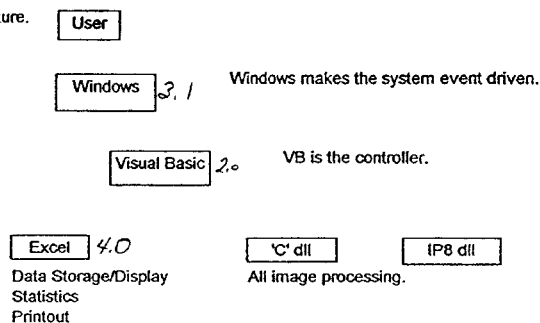
```
C:\
IP8 dll's and CMDIALOG.VBX
PROJECTS
  WETTING
    DATA
    CONTROL
    (with VBRUN200.DLL in SYSTEM)
WINDOWS
EXCEL      (include in Path)
```

Run IPinit.exe (p3-3 IP8 Installation/Interface Guide); set camera to mono, and buffer size to 32K. Be sure to save settings to Power Up.

Recommended order for understanding SFW instrument.

- Run Program c:\projects\wetting\wet.exe.
- Look at Visual Basic (VB) code WITHIN VB (run wet.mak).
- Look at Excel XWET.XLM, and XWET.XLT; read imbedded notes.
- Look at cwet.c program.

Basic Operating Structure.



Comments about navigating through code:

Within VB, make frequent use of selecting menu item or double-clicking button to jump to related code, Shift-F2 to jump to routine, and Ctrl-F to find text. An example of using find to help map out communications would be searching for .Poke or .LinkExecute.

A quick way to see what 'C' routines are exported is to look at ~~cross~~ *wet*.def.

- 33 -

```

/* WET.C

Single Filament Spontaneous Fiber Wetting test.
Author: Wayne Culberson, 1/89.
11/92: Windows version with Matrox IP8, Horizontal camera, back light.

*/

#define WIN30
#include <ip.h>

#include <windows.h>
#include <math.h>
#include <stdlib.h>
#include <time.h>
#include <string.h>

#define dT .03333333333 // 1/(Snaps/sec)
#define SNAPS 121 // Tmax*(Snaps/sec)+1 [4*30+1]; VB Arrays dim at 128

double xPixPerMM ; // Used in cDoMet() only, set in cSetPixPerMM()
int MarkerPosition, MarkerSize, MarkerCol ; // VB insures that MarkerSize is even

int FAR PASCAL LibMain(HANDLE hModule, WORD wDataSeg, WORD cbHeapSize, LPSTR lpszCmdLine)
{
    return TRUE;
}

void FAR PASCAL
cShowThreshold( int Threshold )
{
    int i, j ;
    unsigned char LUTcolor[3*257];

    for ( i=1,j=0 ; i<255 ; i++,j+=3 ) {
        if ( i<Threshold ) { // make below Threshold shade of red
            LUTcolor[j]=min(255,(int)i*100); LUTcolor[j+1]=0;
        }
        else LUTcolor[j]=LUTcolor[j+1]=LUTcolor[j+2]=1 ;
        LUTcolor[j+2]=0;
        LUTcolor[j]=0; LUTcolor[j+1]=0; LUTcolor[j+2]=255; // Bright(255)=blue
        VG_SetLUT( OUT_LUT,LUTcolor,255,1 );
    }
}

int FAR PASCAL
cInitIP(void)
{
    int ErrorCode ;
    unsigned char color=255;

    if ( (ErrorCode=(int)VG_InitLib())!=0 && ErrorCode!=-5 && ErrorCode!=-6 ) return
    ErrorCode ;
    if ( (ErrorCode=(int)VG_Reset(YES)) ) return ErrorCode ;
    VG_SetFrameBufConfig( QUAD );
    VG_SetAccessBufSt( ON ); // _VG_AcsBufSize set by IP8init 2-32K
    VG_SetGrabRegUpd( DIRECT );

    cShowThreshold( 0 );
    VG_SetKeyColor( &color ); // 255 = Overlay Key Color

    return 0 ;
}

void FAR PASCAL
cQuitIP(void)
{
    VG_QuitLib(); // Free up IP8 dll's
}

void FAR PASCAL
cSetPixPerMM( LPSTR PathName )
{
    static char Value[32] ;

```

- 34 -

```

GetPrivateProfileString( "Defaults","xPixPerM","", (LPSTR)Value,32,PathName );
xPixPerM = atof(Value);
}

void FAR PASCAL
cCalibrate( char FAR *Name, int l, int r )
{
    static int ol, or ;
    unsigned char color=0 ;

    if ( !_fstrcmp( Name,"Startup" ) ) {
        VG_ClearScreen( &color );
        color = 255;
        VG_SetPenColor( &color );
        VG_MoveTo( l,0 );      VG_LineTo( l,120 ); // draw new
        VG_MoveTo( r,0 );      VG_LineTo( r,120 );
    }
    else if ( !_fstrcmp( Name,"Scroll" ) ) {
        VG_SetPenColor( &color );
        VG_MoveTo( ol,0 );      VG_LineTo( ol,120 ); // erase
        VG_MoveTo( or,0 );      VG_LineTo( or,120 );
        color = 255;
        VG_SetPenColor( &color );
        VG_MoveTo( l,0 );      VG_LineTo( l,120 ); // new
        VG_MoveTo( r,0 );      VG_LineTo( r,120 );
    }
    ol = l ;      // save for erase
    or = r ;
}

void FAR PASCAL
cLiveImage( int Position, int Size, int Col )
{
    unsigned char color=0 ;

    VG_SetKeyComp( MEMORY );
    VG_SetKeyOut( LIVE );
    VG_SetKeyType( SPECIAL ); // always live for PROGRESSIVE Grab

    VG_SetGrabSourcePos( 0,0,512,480 ); // clear whole frame buf
    VG_SetGrabDestPos( 0,0 );
    VG_SetGrabColor( &color ); // Fast clear of Frame Buf
    VG_SetGrabColorSt( ON );
    VG_SingleGrab(); while ( VG_GetGrabSt() );
    VG_SetGrabColorSt( OFF );
    VG_SetGrabSourcePos( 0,0,512,120 ); // normal grab position; top 1/4 of screen
    VG_SetGrabDestPos( 0,0 );

    VG_SetKeyOut( MEMORY ); // Overlay memory when KeyColor=memory
    VG_SetKeyType( EQUAL );
    VG_SetDispType( KEY_VIDEO ); // SetKey Comp,Out,Type=[MEM,MEM,=]p6-241

    color = 255;
    VG_SetPenColor( &color );
    VG_MoveTo( 10,Position-Size/2 ); // draw 2 horz., 1 vert line
    VG_LineTo( 501,Position-Size/2 );
    VG_MoveTo( 10,Position+Size/2 );
    VG_LineTo( 501,Position+Size/2 );
    VG_MoveTo( Col,Position-30 );
    VG_LineTo( Col,Position+30 );

    MarkerPosition = Position ; // save for others
    MarkerSize = Size ; // VB insures that this is even
    MarkerCol = Col ;
}

int FAR PASCAL
cGetThreshold( unsigned long far Dry[], unsigned long far Back[], unsigned long far *max )
{
    int i ; // note: max is for VB plot scaling.

    VG_SetDispType( MEMORY_VIDEO ); // SetObjectColor(4low,4high) (default)
    VG_SetKeyComp( MEMORY );

```

- 35 -

```

    VG_SetKeyOut( LIVE ); // Must make Keyer output LIVE for
    PROGRESSIVE Grab
    VG_SetKeyType( SPECIAL );
    VG_SetGrabDestPos( 0,0 );
    VG_SingleGrab(); while ( VG_GetGrabSt() ); // wait for Grab
    VG_SetImageSourcePos( 0,MarkerCol,MarkerPosition-3*MarkerSize/2-1,512-
MarkerCol,MarkerSize+1 );
    VG_CalcHisto( Back );
    VG_SetImageSourcePos( 0,MarkerCol,MarkerPosition-MarkerSize/2,512-
MarkerCol,MarkerSize+1 );
    VG_CalcHisto( Dry );
    for ( i=64; *max=0 ; i<255 ; i++ ) if ( Back[i]>*max ) *max=Back[i] ;
    for ( i=0 ; i<256 && Back[i]==0 && Dry[i]==0 ; i++ ) ;
    return i-5 ; // Threshold: 1 is lowest gray level
}

double
GetSlope( double FAR L[], int NumFitPts )
{
    // Least squares Regression; L*L = Slope*i (T=i*dT)
    int i ;
    double Sumi=0., SumiLL=0., maxL ;

    maxL = (510-MarkerCol)/xPixPerMM ; // Don't include points off screen
    if ( L[1]>maxL ) return 0. ; // Avoid blow-up if cursor jumped to edge
    for ( i=0 ; i<NumFitPts && L[i]<maxL ; i++ ) {
        SumiLL += i*L[i]*L[i] ;
        Sumi += i*i ;
    }
    return SumiLL/(Sumi*dT) ; // return Slope with 0 intercept
}

int
Dark( unsigned char far *ptr, unsigned char Threshold )
{
    // Check MarkerSize vertical line; If fluid (dark) advancing, return 1
    int y ;

    for ( y=0 ; y<MarkerSize ; y++,ptr+=512 )
        if ( *ptr < Threshold ) return 1 ;
    return 0 ;
}

void
DrawMarker( unsigned char far *ptr )
{
    // Draw vertical fluid interface marker
    int y ;

    for ( y=0 ; y<MarkerSize ; y++,ptr+=512 )
        *ptr = 255 ;
}

struct Ktype {
    unsigned short int rows ;
    unsigned short int cols ;
    double nums[64] ;
} ;

struct Ktype FAR Ldata ;

struct Ktype FAR * FAR PASCAL // called by Excel
cToXL(void)
{
    return &Ldata ;
}

double FAR PASCAL
cDoWet( double FAR L[], int Threshold, double FAR *Slope, int NumFitPts )
{
    // Wait for fluid, then start sampling @ 30 samples/sec till SNAPS.
    // Get L[i]'s.
    // Returns RunTime.

    int i ;
    long StartTime ;
    unsigned char FB=0 ;
    unsigned char far *ptr ;

```

- 36 -

```

unsigned char far *ptr0 ;
unsigned char far *end ;
double Tc ;

VG_SetCPUFrameBuf( FB );
VG_SetGrabFrameBuf( FB );

VG_SetWinType( 1, LINE_PTR );
VG_SetLineWidth( 1, WIDTH512 );
VG_SetWinOrig( 1, 0, MarkerPosition-MarkerSize/2+360 );

ptr = ptr0 + _VG_AcsBufAdd[1] + MarkerCol; // Pixels from left edge of image
end = _VG_AcsBufAdd[1] + 511 ;

VG_SetGrabRegUpd( DIRECT );
VG_SetDispType( MEMORY_VIDEO );
VG_SetKeyComp( MEMORY );
VG_SetKeyOut( LIVE ); // Must make Keyer output LIVE for PROGRESSIVE Grab
VG_SetKeyType( SPECIAL );
VG_SetGrabDestPos( 0, 360 );

StartTime = GetCurrentTime();
do {
    // ***** Wait for fluid loop
    VG_SingleGrab();
    if ( GetCurrentTime()-StartTime > 4000 ) { // Time Out, No Wet
        while ( VG_GetGrabSt() ); // wait for end of Grab
        for ( i=0 ; i<SNAPS ; i++ ) L[i]=0.;
        goto EndWet ;
    }
    while ( VG_GetGrabSt() ); // wait for end of Grab
} while ( !Dark(ptr, (unsigned char)Threshold) );

StartTime = GetCurrentTime(); // ***** Now follow fluid
for ( i=0 ; i<SNAPS ; i++ ) {
    loc if ( i<3 ) VG_SetGrabDestPos( 0, 240-i*120 ); // next grab in new
        else {
            VG_SetGrabFrameBuf( (FB^=FB) ); // Toggle Frame Buffers
            VG_SetCPUFrameBuf( (FB^=FB) );
        }
        VG_SingleGrab(); // start next grab, then analyze previous below
    front while ( ptr<end && Dark(ptr, (unsigned char)Threshold) ) { // find fluid
        ++ptr ;
        DrawMarker( ptr );
        L[i] = (ptr-ptr0)/xPixPerMM ; // At i'th time slot
    Grab while ( VG_GetGrabSt() ); // wait for end of
        if ( i<3 ) VG_SetWinOrig( 1, 0, MarkerPosition-MarkerSize/2+240-i*120 );
    }
    EndWet : // Time Out (No Wet) jumped here.
    Tc = (GetCurrentTime()-StartTime)/1000. ;
    VG_SetGrabFrameBuf( 0 ); // Make sure these are set to FB 0
    VG_SetCPUFrameBuf( 0 );

    *Slope = GetSlope( L, NumFitPts );

    Ldata.rows = SNAPS/4+1 ; // Copy data to structure for cCtoXL, 0:30 (31pts)
    Ldata.cols = 1 ; // Be sure to get Excel arrayCtoXL matched
    up. for ( i=0 ; i<SNAPS/4 ; i++ ) Ldata.nums[i] = L[4*i] ; // copy every other

    if ( Tc>(int)(1+(SNAPS+1)*dT*18.2)/18.2 || Tc<(int)(-1+(SNAPS-1)*dT*18.2)/18.2 )
        return Tc ;
    else return Tc ;
}

```

- 37 -

cwet.def

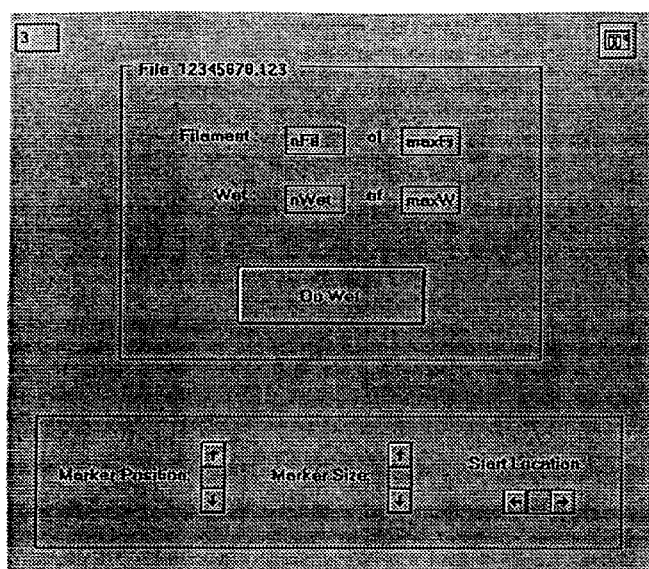
```
LIBRARY      CWET
EXETYPE      WINDOWS

CODE         PRELOAD MOVEABLE DISCARDABLE
DATA         PRELOAD SINGLE
SEGMENTS     'WEP_TEXT' FIXED PRELOAD

HEAPSIZE     4096

EXPORTS
  WEP @1 RESIDENTNAME
  cInitIP @2
  cSetPixPerMM @3
  cLiveImage @4
  cDoWet @5
  cCtoXL @6
  cQuitIP @7
  cGetThreshold @8
  cShowThreshold @9
  cCalibrate @10
```

- 38 -



- 39 -

```

MAIN.FRM - 1

VERSION 2.00
Begin Form M
  Caption           = "Single Filament Wetting"
  ControlBox       = 0 'False
  Height           = 6552
  Left             = 12
  LinkMode         = 1 'Source
  LinkTopic        = "M"
  MaxButton        = 0 'False
  MinButton        = 0 'False
  ScaleHeight      = 484
  ScaleMode        = 3 'Pixel
  ScaleWidth       = 561
  Top             = 12
  Width           = 6828
  Begin CommonDialog OpenDialog
    Left           = 6120
    Top            = 120
  End
End
Begin Frame MarkerFrame
  Height          = 1452
  Left            = 360
  TabIndex        = 11
  Top            = 4080
  Visible         = 0 'False
  Width          = 6012
  Begin HScrollBar StartCol
    Height        = 252
    Left          = 4800
    Max           = 300
    TabIndex      = 17
    Top           = 840
    Width         = 732
  End
  Begin VScrollBar MarkerSize
    Height        = 732
    Left          = 3600
    Max           = 26
    Min           = 4
    SmallChange   = 2
    TabIndex      = 15
    Top           = 360
    Value         = 10
    Width         = 252
  End
  Begin VScrollBar MarkerPosition
    Height        = 732
    Left          = 1680
    Max           = 105
    Min           = 15
    TabIndex      = 14
    Top           = 360
    Value         = 105
    Width         = 252
  End
End
Begin Label Label6
  Caption        = "Marker Size:"
  Height        = 252
  Left          = 2400
  TabIndex      = 13
  Top           = 600

```

- 40 -

MAIN.FRM - 2

```

        Width           = 1092
    End
    Begin Label Label5
        Caption           = "Marker Position:"
        Height            = 252
        Left              = 240
        TabIndex          = 12
        Top               = 600
        Width             = 1452
    End
    Begin Label Label7
        Caption           = "Start Location:"
        Height            = 252
        Left              = 4440
        TabIndex          = 16
        Top               = 480
        Width             = 1332
    End
End
Begin Frame FileFrame
    Caption              = " File 12345678.123 "
    Height               = 3132
    Left                = 1200
    TabIndex            = 1
    Top                 = 480
    Visible              = 0 'False
    Width               = 4332
    Begin CommandButton DoWetButton
        Caption          = "Do Wet"
        Height           = 612
        Left             = 1200
        TabIndex         = 10
        Top              = 2160
        Width            = 1932
    End
    Begin TextBox maxWet
        Height           = 288
        Left             = 2880
        TabIndex         = 9
        Text              = "maxWet"
        Top              = 1320
        Width            = 612
    End
    Begin TextBox nWet
        Height           = 288
        Left             = 1680
        TabIndex         = 8
        Text              = "nWet"
        Top              = 1320
        Width            = 612
    End
    Begin TextBox maxFil
        Height           = 288
        Left             = 2880
        TabIndex         = 7
        Text              = "maxFil"
        Top              = 720
        Width            = 612
    End
    Begin TextBox nFil
        Height           = 288

```

- 41 -

MAIN.FRM - 3

```

        Left      = 1680
        TabIndex  = 6
        Text      = "nFil"
        Top       = 720
        Width     = 612
    End
    Begin Label Label4
        Caption    = "of"
        Height     = 252
        Left       = 2520
        TabIndex   = 5
        Top        = 1320
        Width      = 252
    End
    Begin Label Label3
        Caption    = "Wet :"
        Height     = 255
        Left       = 960
        TabIndex   = 4
        Top        = 1320
        Width      = 615
    End
    Begin Label Label2
        Caption    = "of"
        Height     = 252
        Left       = 2520
        TabIndex   = 3
        Top        = 720
        Width      = 252
    End
    Begin Label Label1
        Caption    = "Filament :"
        Height     = 255
        Left       = 600
        TabIndex   = 2
        Top        = 720
        Width      = 975
    End
End
Begin TextBox x
    Height      = 300
    Left        = 120
    LinkTimeout = -1
    TabIndex    = 0
    Text        = "3 "
    Top         = 120
    Visible     = 0 'False
    Width       = 450
End
Begin Menu mFile
    Caption    = "File"
    Begin Menu mOpen
        Caption = "Open File"
    End
    Begin Menu mView
        Caption = "View File"
    End
    Begin Menu mCalibrate
        Caption = "Calibrate"
    End
    Begin Menu mExit

```

- 42 -

```
MAIN.FRM - 4
      Caption      = "Exit Wetting"
      End
    End
  End
```

- 43 -

MAIN.FRM - 1

```

Sub PlotData (L#, Slope#, NumFitPts%)
    Dim J%, maxPoints!, maxLength!

    maxLength = 10      'mm
    maxPoints = 120      'time = Point*dt
    Plot.Picture1.Scale (0, maxLength)-(maxPoints, 0)
    Plot.Picture1.Cls: Plot.Picture1.CurrentY = maxLength
    Plot.Picture1.Print " Slope = " + Format$(Slope, "#.0")
    For J = 0 To maxPoints
        Plot.Picture1.Circle (J, L(J)), maxPoints / 200, RED      'raw data
        Plot.Picture1.Circle (J, L(J) * L(J) / 10), maxPoints / 200, GREEN 'linea
    Next J
    If J < NumFitPts And Sqr(Slope * .033333 * (J + 1)) <= 10 Then Plot.Picture1.Line (J, Sqr(Slope * .033333 * J))-(J + 1, Sqr(Slope * .033333 * (J + 1))), C
    YAN
    Next J

    Plot.PrintThreshold.Caption = "Threshold:" + Str$(Threshold)
    Plot.Show
End Sub

Sub DoWetButton_Click ()
    Static Pos(128) As Double
    ReDim Dry(257) As Long, Back(257) As Long
    Dim RunTime#, Slope#, r#, le#, NumFitPts%

    If Threshold = 0 Then
        MsgBox "Please Set Threshold.", MB_ICONEXCLAMATION, "Invalid Threshold"
        Exit Sub
    End If

    DoWetButton.Caption = "Release Fluid"
    Screen.MousePointer = 11
    DoEvents      'This should not be needed; but sometimes cDoWet didn't get started right
    NumFitPts = 30 '30=1sec
    RunTime = cDoWet(Pos(0), Threshold, Slope, NumFitPts)
    Screen.MousePointer = 0
    DoWetButton.Caption = "Do Wet"

    If RunTime < 0 Then
        MsgBox "Note RunTime Discrepancy. RunTime=" + Format$(Abs(RunTime), "#.00") + " sec", MB_ICONEXCLAMATION, "RunTime Error"
    End If

    PlotData Pos(), Slope, NumFitPts

    M.x.LinkExecute "[RUN(" + QS + "XWET.XLM!arrayCtoXL" + QS + ")]"
    M.x.LinkExecute "[FORMULA(" + Format$(Slope, "#.000") + ")]"

    If (Val(nWet.Text) + 1) > Val(maxWet.Text) Then      'set nFil/nWet for next
        nWet.Text = "1"
        If Val(nFil.Text) = Val(maxFil.Text) Then MsgBox "You have completed " +
            nFil.Text + " Filaments.", MB_ICONINFORMATION, "Reminder"
        nFil.Text = Str$(Val(nFil.Text) + 1)
        M.x.LinkExecute "[SAVE()]"      'save while new filament is loaded
        DoEvents
    Else
        nWet.Text = Str$(Val(nWet.Text) + 1)
    End If

```

- 44 -

```

MAIN.FRM - 2

    End If
End Sub

Sub Form_Click ()
    cLiveImage MarkerPosition.Value, MarkerSize.Value, StartCol.Value
End Sub

Sub MarkerPosition_Change ()
    cLiveImage MarkerPosition.Value, MarkerSize.Value, StartCol.Value
End Sub

Sub MarkerSize_Change ()
    cLiveImage MarkerPosition.Value, MarkerSize.Value, StartCol.Value
End Sub

Sub maxFil_Change ()
    putXL (maxFil.Text), "maxFil"
End Sub

Sub maxWet_Change ()
    putXL (maxWet.Text), "maxWet"
End Sub

Sub mCalibrate_Click ()
    Calibrate.Show MODAL
End Sub

Sub mExit_Click ()
    cQuitIP 'does IP8 QuitLib

    x.LinkMode = NONE 'close link to current spreadsheet
    x.LinkTopic = "Excel|xwet.xml"
    x.LinkMode = COLD
    x.LinkExecute "[RUN(" + Q$ + "XWET.XLM!ClearOut" + Q$ + ")]" 'close all exce
pt XWET.XLM

    it = WritePrivateProfileString("Defaults", "MarkerRow", Str$(MarkerPosition.
Value), IniFile)
    it = WritePrivateProfileString("Defaults", "MarkerSize", Str$(MarkerSize.Val
ue), IniFile)
    it = WritePrivateProfileString("Defaults", "StartCol", Str$(StartCol.Value),
IniFile)

    'AppActivate "Microsoft Excel - XWET.XLM"
    SendKeys "{TAB}", True
    SendKeys "ifx", True
    z{ = DoEvents()
End
End Sub

Sub mOpen_Click ()
    OpenSheet
End Sub

Sub mView_Click ()
    SendKeys "{TAB}", True
    'AppActivate "Microsoft Excel - " & OpenFileDialog.Filetitle
End Sub

Sub nFil_Change ()
    putXL (nFil.Text), "nFil"

```

- 45 -

MAIN.FRM - 3

End Sub

```
Sub nWet_Change ()  
    putXL (nWet.Text), "nWet"  
End Sub
```

```
Sub StartCol_Change ()  
    cLiveImage MarkerPosition.Value, MarkerSize.Value, StartCol.Value  
End Sub
```

- 46 -

Position Each Marker

Pixels Between Marks = 400

Millimeters Between Marks = 10

- 47 -

```

CALIBRAT.FRM - 1

VERSION 2.00
Begin Form Calibrate
  Caption      = "Calibrate"
  ControlBox   = 0 'False
  Height       = 4608
  Left         = 336
  LinkMode     = 1 'Source
  LinkTopic    = "Form1"
  MaxButton    = 0 'False
  MinButton    = 0 'False
  ScaleHeight  = 4188
  ScaleWidth   = 6108
  Top          = 1428
  Width        = 6204
  Begin CommandButton CancelButton
    Caption      = "Cancel"
    Height       = 495
    Left         = 3480
    TabIndex     = 10
    Top          = 3360
    Width        = 1335
  End
  Begin CommandButton OkButton
    Caption      = "OK"
    Height       = 495
    Left         = 1200
    TabIndex     = 9
    Top          = 3360
    Width        = 1335
  End
  Begin TextBox xPixPerKM
    Height       = 405
    Left         = 2760
    TabIndex     = 6
    Top          = 2400
    Width        = 1335
  End
  Begin CommandButton Calx
    Caption      = "Calculate"
    Height       = 375
    Left         = 960
    TabIndex     = 4
    Top          = 2400
    Width        = 1335
  End
  Begin HScrollBar HScroll2
    Height       = 255
    LargeChange  = 10
    Left         = 4320
    Max          = 509
    Min          = 156
    TabIndex     = 1
    Top          = 360
    Value        = 499
    Width        = 1215
  End
  Begin HScrollBar HScroll1
    Height       = 255
    LargeChange  = 10
    Left         = 2640
    Max          = 356

```

- 48 -

CALIBRAT.FRM - 2

```

      Min           = 2
      TabIndex      = 0
      Top           = 360
      Value         = 13
      Width         = 1215
End
Begin Label Label3
  Caption          = "Pixel/MM"
  Height           = 255
  Left             = 4200
  TabIndex         = 5
  Top              = 2520
  Width            = 975
End
Begin Label Label2
  Caption          = "Millimeters Between Marks = 10"
  Height           = 255
  Left             = 360
  TabIndex         = 3
  Top              = 1680
  Width            = 2895
End
Begin Label Pixels
  Caption          = "486"
  Height           = 252
  Left             = 2520
  TabIndex         = 8
  Top              = 1080
  Width            = 612
End
Begin Label Label4
  Caption          = "Pixels Between Marks ="
  Height           = 252
  Left             = 360
  TabIndex         = 7
  Top              = 1080
  Width            = 2052
End
Begin Label Label1
  Caption          = "Position Each Marker:"
  Height           = 255
  Left             = 360
  TabIndex         = 2
  Top              = 360
  Width            = 2055
End
End

```

- 49 -

```

CALIBRAT.FRM - 1
'Uses Global IniFile in FileButton_Click
Declare Sub cCalibrate Lib "cwet.dll" (ByVal LiveOrSnap$, ByVal l%, ByVal rt)

Sub Calx_Click ()
    xPixPerMM.Text = Format$(Val(Pixels.Caption) / 10, "#.0000")
End Sub

Sub CancelButton_Click ()
    cLiveImage M.MarkerPosition.Value, M.MarkerSize.Value, M.StartCol.Value
    Unload Calibrate
End Sub

Sub Form_Load ()
    cCalibrate "StartUp", HScroll1.Value, HScroll2.Value
End Sub

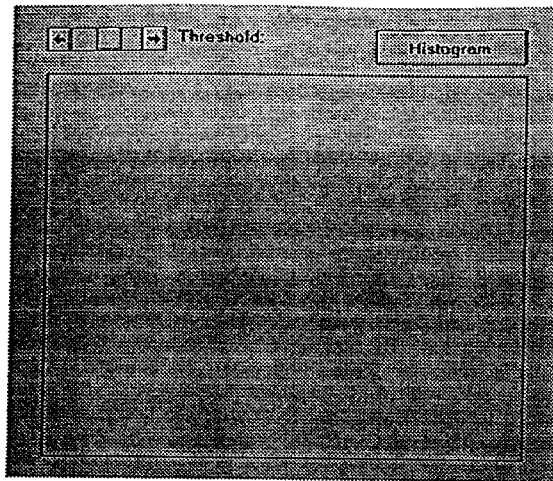
Sub HScroll1_Change ()
    cCalibrate "Scroll", HScroll1.Value, HScroll2.Value
    Pixels.Caption = Str$(HScroll2.Value - HScroll1.Value)
End Sub

Sub HScroll2_Change ()
    cCalibrate "Scroll", HScroll1.Value, HScroll2.Value
    Pixels.Caption = Str$(HScroll2.Value - HScroll1.Value)
End Sub

Sub OkButton_Click ()
    i% = WritePrivateProfileString("Defaults", "xPixPerMM", (xPixPerMM.Text), In
iFile)
    cSetPixPerMM (IniFile) 'tell C to get new value
    cLiveImage M.MarkerPosition.Value, M.MarkerSize.Value, M.StartCol.Value
    Unload Calibrate
End Sub

```

- 50 -



- 51 -

```

PLOT.FRM - 1
VERSION 2.00
Begin Form Plot
  Caption      = "Data and Fit"
  Height       = 5340
  Left         = 3096
  LinkMode     = 1 'Source
  LinkTopic    = "Form2"
  ScaleHeight  = 4920
  ScaleWidth   = 5652
  Top          = 480
  Width        = 5748
  Begin PictureBox Picture1
    AutoRedraw = -1 'True
    Height     = 3975
    Left       = 360
    ScaleHeight = 3948
    ScaleWidth  = 4908
    TabIndex   = 0
    Top        = 720
    Width      = 4935
  End
  Begin CommandButton Histogram
    Caption      = "Histogram"
    Height       = 375
    Left         = 3720
    TabIndex     = 3
    Top          = 240
    Width        = 1575
  End
  Begin HScrollBar ThresholdScroll
    Height       = 255
    LargeChange  = 10
    Left         = 360
    Max          = 255
    TabIndex     = 1
    Top          = 240
    Value        = 140
    Width        = 1215
  End
  Begin Label PrintThreshold
    Caption      = "Threshold:"
    Height       = 255
    Left         = 1680
    TabIndex     = 2
    Top          = 240
    Width        = 1335
  End
End
End

```

- 52 -

```

PLOT.FRM - 1

Dim MaxPix As Long

Sub Histogram_Click ()
    ReDim Dry(257) As Long, Back(257) As Long
    Dim J%, MaxGray%, Thresh%

    Thresh = cGetThreshold(Dry(0), Back(0), MaxPix)

    MaxGray = 255
    Plot.Picture1.DrawMode = 13 'copy pen
    Plot.Picture1.Cls
    Plot.Picture1.Scale (0, MaxPix)-(MaxGray, -2)
    For J = 0 To MaxGray - 1
        Plot.Picture1.Line (J, Back(J))-(J + 1, Back(J + 1)), RED
        Plot.Picture1.Line (J, Dry(J))-(J + 1, Dry(J + 1)), GREEN
    Next J
    Plot.Picture1.DrawMode = 7 'xor pen
    Plot.Picture1.Line (Threshold, 0)-(Threshold, MaxPix / 3), WHITE
    ThresholdScroll.Value = Thresh 'triggers ThresholdScroll_Change
    ThresholdScroll.SetFocus
End Sub

Sub ThresholdScroll_Change ()
    Plot.Picture1.Line (Threshold, 0)-(Threshold, MaxPix / 3), WHITE 'erase
    Threshold = ThresholdScroll.Value
    Plot.Picture1.Line (Threshold, 0)-(Threshold, MaxPix / 3), WHITE
    PrintThreshold.Caption = "Threshold:" + Str$(Threshold)
    cShowThreshold Threshold
End Sub

Sub ThresholdScroll_LostFocus ()
    Plot.Picture1.DrawMode = 13 'copy pen
End Sub

```

- 53 -

```

EXCEL.BAS - 1

Declare Function FindWindow Lib "User" (lpClassName As Any, lpWindowName As Any)
As Integer

Function FileExists (FileName$) As Integer
    Dim s As OFSTRUCT
    'This assumes no OFN_NOCHANGEDIR flag in OpenFileDialog box; ie file in current
dir
    it = OpenFile(FileName, s, &H4000) 'OF_EXIST = &H4000
    If it = -1 Then
        FileExists = False
    Else
        FileExists = True
    End If
End Function

Function getXL$ (Item$)
    M.x.LinkItem = Item
    M.x.LinkRequest
    getXL = Left$(M.x.Text, Len(M.x.Text) - 2) 'remove last 2 somethings that Excel includes
End Function

Sub Main ()
    QS = Chr$(34) 'double quote used various places

    Path = "c:\projects\wetting"
    ChDir Path
    IniFile = Path + "\wet.ini"

    If cInitIP() <> 0 Then
        MsgBox "Initialization Error " + Str$(it), MB_ICONSTOP, "IPS Error"
    End If

    If FindWindow(ByVal "XLMain", ByVal 0) = False Then
        x$ = "Excel " + Path + "\XWET.XLM"
        z$ = Shell(x$, 4) ' Start Excel. 4=Normal w/o focus,7=Min w/o
    End If

    Plot.Show
    M.Show
    OpenSheet

    cSetPixPerMM (IniFile) 'tell C to get xPixPerMM
    M.MarkerPosition.Value = GetPrivateProfileInt("Defaults", "MarkerRow", 99, IniFile)
    M.MarkerSize.Value = GetPrivateProfileInt("Defaults", "MarkerSize", 99, IniFile)
    M.StartCol.Value = GetPrivateProfileInt("Defaults", "StartCol", 99, IniFile)
    cLiveImage M.MarkerPosition.Value, M.MarkerSize.Value, M.StartCol.Value
End Sub

Sub OpenSheet ()
    M.OpenDialog.DefaultExt = "xls" 'This section sets up and calls Open Dialog Box
    M.OpenDialog.DialogTitle = "Open/Create File"
    M.OpenDialog.FileName = ""
    M.OpenDialog.Filter = "All Files (*.*)|*.*|Excel Sheets (*.xls)|*.xls"
    M.OpenDialog.Flags = OFN_CREATEPROMPT 'OFN_NOCHANGEDIR: let change, note C

```

- 54 -

```

EXCEL.BAS - 2

hDir below
M.OpenDialog.InitDir = "data"
M.OpenDialog.Action = 1 'Windows does Dialog Box
If M.OpenDialog.FileName = "" Then Exit Sub 'Cancel returns empty filename

M.x.LinkMode = NONE 'close link to current spreadsheet
M.x.LinkTopic = "Excel[System]"
M.x.LinkMode = COLD
M.x.LinkExecute "[RUN(" + Q$ + "XWET.XLM!ClearOut" + Q$ + ")]" 'close all ex
cept XWET.XLM & CONTROL.XLS

If FileExists((M.OpenDialog.FileTitle)) Then
    M.x.LinkExecute "[OPEN(" + Q$ + M.OpenDialog.FileName + Q$ + ")]"
Else
    M.x.LinkExecute "[OPEN(" + Q$ + Path + "\xwet.xlt" + Q$ + ")]"
    M.x.LinkExecute "[SAVE.AS(" + Q$ + M.OpenDialog.FileName + Q$ + ",1)]"
End If

ChDir Path

M.x.LinkTopic = "Excel|" + M.OpenDialog.FileTitle
M.x.LinkMode = COLD

M.nFil.Text = getXL("nFil") 'ReadExcel
M.nWet.Text = getXL("nWet")
M.maxFil.Text = getXL("maxFil")
M.maxWet.Text = getXL("maxWet")

M.FileFrame.Caption = " File: " & M.OpenDialog.FileTitle
M.FileFrame.Visible = True
M.MarkerFrame.Visible = True

Threshold = 0 'Force evaluation of new Threshold in M.DoWetButton_Click
k
End Sub

Sub putXL (ValStr$, Item$)
M.x.LinkItem = Item
M.x.Text = ValStr
M.x.LinkPoke
End Sub

```


- 55 -

```

GLOBAL.BAS - 1

Global Path$, IniFile$      'set in Excel.bas, Sub Main
Global Q$                   'quotes " ; set in Excel main ; used in LinkExecute
Global Threshold$           'set in Plot ThresholdScroll_Change, used in M DoWet

'***** cWET.DLL calls *****
Declare Function cInitIP Lib "cwet.dll" ()
Declare Sub cQuitIP Lib "cwet.dll" ()
Declare Sub cSetPixPerMM Lib "cwet.dll" (ByVal IniFileName$)
Declare Sub cLiveImage Lib "cwet.dll" (ByVal Position$, ByVal Size$, ByVal Start
Col$)
Declare Function cDoWet Lib "cwet.dll" (l As Double, ByVal Threshold$, slope$,
ByVal NumFitPts$)
Declare Sub cShowThreshold Lib "cwet.dll" (ByVal thresh$)
Declare Function cGetThreshold Lib "cwet.dll" (Wet As Long, Back As Long, MaxPi
x As Long)

'***** Windows API calls, From WINAPI.WRI *****
Declare Function WritePrivateProfileString Lib "Kernel" (ByVal lpAppName$, ByVal
l lpKeyName$, ByVal lpString$, ByVal lpFileName$)
Declare Function GetPrivateProfileInt Lib "Kernel" (ByVal lpAppName$, ByVal lpK
eyName$, ByVal nDefault$, ByVal lpFileName$)

Type OFSTRUCT ' OpenFile() Structure, used by Excel.bas FileExists
  cBytes As String * 1
  fFixedDisk As String * 1
  nErrCode As Integer
  reserved As String * 4
  szPathName As String * 128
End Type
Declare Function OpenFile Lib "Kernel" (ByVal lpFileName As String, lpReOpenBuff
As OFSTRUCT, ByVal wStyle As Integer) As Integer

'***** Visual Basic global constant file; Edited by WTC 4/92 *****
*****
Global Const NONE = 0

Global Const mLEFT = 1 'LEFT_BUTTON
Global Const mRIGHT = 2 'RIGHT_BUTTON

' MsgBox parameters
Global Const MB_OK = 0 ' OK button only
Global Const MB_OKCANCEL = 1 ' OK and Cancel buttons
Global Const MB_ABORTRETRYIGNORE = 2 ' Abort, Retry, and Ignore buttons
Global Const MB_YESNOCANCEL = 3 ' Yes, No, and Cancel buttons
Global Const MB_YESNO = 4 ' Yes and No buttons
Global Const MB_RETRYCANCEL = 5 ' Retry and Cancel buttons

Global Const MB_ICONSTOP = 16 ' Critical message
Global Const MB_ICONQUESTION = 32 ' Warning query
Global Const MB_ICONEXCLAMATION = 48 ' Warning message
Global Const MB_ICONINFORMATION = 64 ' Information message

Global Const MB_DEFBUTTON1 = 0 ' First button is default
Global Const MB_DEFBUTTON2 = 256 ' Second button is default
Global Const MB_DEFBUTTON3 = 512 ' Third button is default

```

- 56 -

```

GLOBAL.BAS - 2

' MsgBox return values
Global Const IDOK = 1           ' OK button pressed
Global Const IDCANCEL = 2       ' Cancel button pressed
Global Const IDABORT = 3        ' Abort button pressed
Global Const IDRETRY = 4        ' Retry button pressed
Global Const IDIGNORE = 5       ' Ignore button pressed
Global Const IDYES = 6          ' Yes button pressed
Global Const IDNO = 7           ' No button pressed

' Show (form)
Global Const MODAL = 1
Global Const MODELESS = 0

' LinkMode (controls)
Global Const HOT = 1            ' 1 - Hot
Global Const COLD = 2          ' 2 - Cold

' Value (check box)
Global Const UNCHECKED = 0      ' 0 - Unchecked
Global Const CHECKED = 1        ' 1 - Checked
Global Const GRAYED = 2         ' 2 - Grayed

Global Const WINDOW_TEXT = &H80000008 ' Text in windows.
Global Const GRAY_TEXT = &H80000011    ' Grayed (disabled) text. This
color is set to 0 if the current display driver does not support a solid gray co
lor.
Global Const BUTTON_TEXT = &H80000012   ' Text on push buttons.

Global Const BLACK = &H0&
Global Const RED = &HFF&
Global Const GREEN = &HFF00&
Global Const YELLOW = &HFFFF&
Global Const BLUE = &HFF0000
Global Const MAGENTA = &HFF00FF
Global Const CYAN = &HFFFF00
Global Const WHITE = &HFFFFFF

```

- 57 -

XWET.XLM

Print
=UpdatePlot()
=PRINT(2,1,1,1,FALSE,TRUE,1)
=ArrayToValues()
=RETURN()
ArrayToValues
=SELECT(Z)
=COPY(Z)
=PASTE.SPECIAL(3,1,FALSE,FALSE)
=CANCEL.COPY()
=RETURN()
AddHiLight
Z=(ROW(SELECTION)-ROW(IStartRef)-1)*ImaxWet+COLUMN(SELECTION)-COLUMN(IStartRef)
=ACTIVATE(GET.DOCUMENT(1)&" Chart 2")
=SELECT("S"&Z)
=PATTERNS(2,1,1,1,0,2,15,3)
=RETURN()
CancelHiLight
=ACTIVATE(GET.DOCUMENT(1)&" Chart 2")
=SELECT("S1")
=PATTERNS(0,1,1,1,2,1,1,1,TRUE)
=RETURN()
ReturnToSFW
=SEND.KEYS("%{TAB}")
=RETURN()
arrayCtoXL
Z=OFFSET(IPlotRef,1,(InFil-1)*ImaxWet+InWet,31,1)
=FORMULA.ARRAY(CALL("cwet.dll","cCtoXL",Z),Z)
=FORMULA("F"&InFil&"W"&InWet,OFFSET(Z,-1,0))
=SELECT(OFFSET(IStartRef,InFil,InWet,1,1))
=RETURN()
UpdatePlot
Z=OFFSET(IPlotRef,1,0,31,(InFil-1)*ImaxWet+InWet)
=SELECT("Chart 2")
=CHART.WIZARD(FALSE,Z,,2,1,2)
=RETURN()

XWET.XLM

```

ClearOut
=SET.NAME("Docs",DOCUMENTS())
=FOR("Z",1,COLUMNS(Docs))
= INDEX(Docs,Z)
= IF(AND(B4<>"XWET.XLM",B4<>"XCONTROL.XLS"))
= ACTIVATE(B4)
= FILE.CLOSE(1)
= END.IF()
=NEXT()
=RETURN()

FillNames
=SELECT(OFFSET(IStartRef,1,0,3,1))
=FillAuto(OFFSET(IStartRef,1,0,1,maxFill,1),FALSE)
=UpdatePlot()
=RETURN()

Auto_Open_Mac
=ADD.TOOLBAR("SFW Toolbar",4,"xwet.xml!Print",FALSE,TRUE,0,"Print (w/Preview)",0,0,0,0,0;138,"xwet.x
=SHOW.TOOLBAR("SFW Toolbar",TRUE,5,,,500)

=WINDOW.MAXIMIZE()
=APP.MAXIMIZE()
=SEND.KEYS("%{TAB}")
=RETURN()

Auto_Close_Mac
=SAVE()
=RETURN()

```

- 59 -

9/27/94

BEB-PAT Xwet.XLT

FTRL No.: 123
 Package No.:
 Sample ID:
 Operator:
 cArea: 0.0
 cArea StdDev:
 dpl:

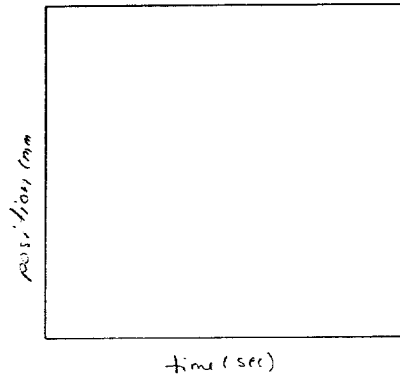
	Slope	Vo	mpf	b
Avg:	#DIV/0!	#DIV/0!	#DIV/0!	#DIV/0!
StdDev:	#DIV/0!	#DIV/0!	#DIV/0!	#DIV/0!
CV:	#DIV/0!			

mpf is two way

Slopes:

Wet 1 Wet 2 Wet 3

Fint 1
 Fint 2
 Fint 3
 Fint 4
 Fint 5
 Fint 6
 Fint 7
 Fint 8
 Fint 9
 Fint 10
 Fint 11
 Fint 12
 Fint 13
 Fint 14
 Fint 15
 Fint 16
 Fint 17
 Fint 18
 Fint 19
 Fint 20

Units:Slope [mm²/sec]

Vo [mm/sec] = SQRT(Slope/4T) where T=.022sec

mpf [cm³/(gm*hr)] = 2*.1620*cArea*Vo/dplb [cm⁴/(gm*hr)] = .0081*cArea*Slope/dpl

Note: b = .05*SQRT(T)*SQRT(Slope)*mpf

Measurement of Advancing Contact Angle

The technique (Modified Wilhelmy Slide Method) used to measure the adhesion tension can also be used to measure the Advancing Contact Angle θ_a . The force which is recorded on the microbalance is equal to the adhesion tension times the perimeter of the sample film.

$$\text{Force} = \text{Adhesion Tension} \times \text{Perimeter}$$

$$= \gamma \cos \theta_a \times p$$

Where

γ is the surface tension of the fluid (dynes/cm)

θ_a is the advancing contact angle (degree)

p is the perimeter of the film (cm)

or solving for θ_a :

$$\theta_a = \cos^{-1} \left[\frac{\text{Force}}{\gamma p} \right]$$

For pure fluids and clean surfaces, this is a very simple calculation. However, for the situation which exists when finishes are applied to surfaces and some of this finish comes off in the fluid the effective γ is no longer the γ of the pure fluid. In most cases the materials which come off are materials which lower significantly the surface tension of the pure fluid (water in this case). Thus, the use of the pure fluid surface tension can cause considerable error in the calculation of θ_a .

To eliminate this error a fluid is made up which contains the pure fluid (water in this case) and a small amount of the material (finish) which was deposited on the sample surface. The amount of the finish added should just exceed the critical micelle level. The surface tension of this fluid is now measured and is used in the θ_a calculation instead of the pure fluid γ . The sample is now immersed in this fluid and the Force determined. θ_a is now determined using the surface tension of the pure fluid with finish added and the Force as measured in the pure fluid with finish added. This θ_a can now be used in $(1-X \theta_a)$ expression to determine if the expression is negative.

Determination of Crimp Amplitude and Crimp Frequency

This describes the determination of crimp amplitude and crimp frequency for fibers in which the crimp is helical (3-dimensional).

The sample is prepared by randomly picking 25 groups of filaments. One filament is picked from each group for testing. Results are the average of the 25 filaments.

A single fiber specimen is placed on a black felt board next to a NBS ruler with one end of the fiber on zero. The relaxed length (L_r) is measured.

The number of crimp peaks (N) are counted with the fiber in the relaxed length. Only top or bottom peaks are counted but not both. Half peaks at both ends are counted as one. Half counts are rounded up.

The single fiber specimen is grasped with tweezers at one end and held at zero on the ruler, and the other end is extended just enough to remove crimp without stretching the filament. The extended length (L_e) is measured.

Definitions

Crimp Frequency=The number of crimps per unit straight length of fiber.

Crimp Amplitude=The depth of the crimp, one-half of the total height of the crimp, measured perpendicular to the major axis along the center line of the helically crimped fiber.

Calculations

For a true helix of pitch angle ϕ having N total turns, a relaxed length L_r , and an extended (straight) length L_e , the following equations apply:

$$L_e \cos \phi = N\pi(2A)$$

$$L_e \sin \phi = L_r$$

where A is the previously defined crimp amplitude. From these equations, A is readily calculated from the measured values of L_r , L_e , and N as follows:

$$\phi = \sin^{-1}(L_r / L_e)$$

$$A = \frac{L_e}{2N\pi} \cos \phi$$

Crimp frequency (C) as previously defined is calculated as follows:

$$C = \frac{N}{L_e}$$

When L_e and L_r are expressed in inches, crimp amplitude has units of inches and crimp frequency has units of crimps per inch.

The following examples are to illustrate the invention but should not be interpreted as a limitation thereon.

EXAMPLE 1

Six denier per filament grooved polyester fibers shaped as shown in FIG. 9 and lubricated with 0.5% of a mixture of 98% polyoxyethylene sorbitan monolaurate and 2% 4-cetyl-4-ethylmorpholinum ethosulfate in accordance with this invention as described hereinabove are blended with 10% weight polyester binder fiber during carding and a 70 grain (~54,000 denier) sliver was produced. This sliver was then passed through an air flow oven at 325° F. and the residence time was approximately 1 minute to activate the binder. This bonded sliver was then tested by a beautician. Significant improvements in keeping the fluid away from the skin were observed which reduces irritation and burning. An improvement in handling of this product was noted when compared to the cotton sliver currently used in this area. The breaking strength was 105 grams.

EXAMPLE 2

Same as Example 1 except binder fiber was at the 10% level of sheath core binder fiber. The end use results were the same as in Example 10.

EXAMPLE 3

Same as Example 1 except the binder fiber is ~10% binder powder. The carded web was 100% polyester grooved fiber and the binder powder was added at the infrared oven. The warm bonded sliver was collected and coiled into an approximately circular shape. The same advantages listed in Example 10 were observed with this product also.

75

For Examples 4, 5, and 6, the staple length of the fibers is 3 inches, shape factor is 2.7, maximum potential flux is 122 cc/g/hr, and surface tension of the measuring fluid is 62 dynes/cm.

EXAMPLE 4

The material in Example 1 at the same blend ratio (90/10) was used to make a 100,000 denier sliver in the same manner as disclosed in Example 10. This size sliver probably represents the upper limit on a practical manageable sliver for this end use.

EXAMPLE 5

Same as Example 4 except the sliver denier is 30,000. This size sliver probably represents the lower practical size limit to do a useful job in this end use.

EXAMPLE 6

It is clear that the breaking strength of the sliver can be too weak (cannot handle the sliver without it coming apart) or too strong (difficult to break by the beautician). Experiments on various slivers suggest that 100 grams is a reasonable minimum strength limit and 2,000 grams represent a reasonable maximum strength limit.

EXAMPLE 7

It is also clear that the higher the maximum potential flux, the better able the sliver can manage the fluid. A 50,000 denier sliver made from 26 dpf, 6 in. staple, helically crimped, 5 crimps per inch with a shape factor of 3.99, an MPF of about 800 cc/h/g and a breaking strength of 168 grams was shown to be very useful in this end use. Slivers can easily be made from fiber having maximum potential flux as high as 2700 cc/g/hr. Other things being equal (softness, breaking strength, appearance, etc.) the higher the maximum potential flux the better.

Unless otherwise specified, all parts, percentages, etc., are by weight.

The invention has been described in detail with particular reference to preferred embodiments thereof, but it will be understood that variations and modifications can be effected within the spirit and scope of the invention. Moreover, all patents, patent applications (published or unpublished, foreign or domestic), literature references or other publications noted above are incorporated herein by reference for any disclosure pertinent to the practice of this invention.

We claim:

1. An absorbent head band for protecting skin and eyes from irritation or other unpleasant sensations caused by contact with liquids used in cosmetology comprising a sliver of spontaneously wettable fibers, said sliver having a size of about 30,000–100,000 denier, the fibers of said sliver being held together by a binder such as to have a tensile strength of between 100 and 2000 grams, said fibers having a dpf of 3–30, a staple length of 1½–6 inches, a shape factor of 1.5–5 and a maximum potential flux of at least 75 cc/g/hr using a liquid having a surface tension of about 60–65 dynes/cm and a viscosity of about 1 centipoise.

2. A head band according to claim 1 wherein said sliver has a size of about 40,000–60,000 denier.

76

3. A head band according to claim 1 wherein said fibers have a staple length of about 2–3 inches.

4. A head band according to claim 1 wherein said sliver has a tensile strength of about 150–1000 grams.

5. A head band according to claim 1 wherein the fibers therein satisfy the following equation

$$(1-X \cos \theta_a) < 0,$$

wherein

θ_a is the advancing contact angle of water measured on a flat film made from the same material as the fiber and having the same surface treatment, if any,

X is a shape factor of the fiber cross-section that satisfies the following equation

$$x = \frac{P_w}{4r + (\pi - 2)D}$$

wherein

P_w is the wetted perimeter of the fiber and r is the radius of the circumscribed circle circumscribing the fiber cross-section and D is the minor axis dimension across the fiber cross-section.

6. A head band according to claim 1 wherein the fibers therein satisfy the following equation

$$(1-X \cos \theta_a) < -0.7,$$

wherein

θ_a is the advancing contact angle of water measured on a flat film made from the same material as the fiber and having the same surface treatment, if any,

X is a shape factor of the fiber cross-section that satisfies the following equation

$$x = \frac{P_w}{4r + (\pi - 2)D}$$

wherein

P_w is the wetted perimeter of the fiber and r is the radius of the circumscribed circle circumscribing the fiber cross-section and D is the minor axis dimension across the fiber cross-section.

7. A head band according to claim 1 wherein the fibers therein satisfy the following equation

$$(1-X \cos \theta_a) < 0,$$

wherein

θ_a is the advancing contact angle of water measured on a flat film made from the same material as the fiber and having the same surface treatment, if any,

X is a shape factor of the fiber cross-section that satisfies the following equation

$$x = \frac{P_w}{4r + (\pi - 2)D}$$

wherein

P_w is the wetted perimeter of the fiber and r is the radius of the circumscribed circle circumscribing the fiber cross-section and D is the minor axis dimension across the fiber cross-section,

77

and wherein the maximum potential flux of said fiber is at least 75 cc/g/hr when measured using a liquid having a surface tension of about 60–65 dynes/cm².

8. An absorbent head band according to claim **1** wherein the fibers are polyethylene terephthalate having an I.V. of

78

about 0.62–0.64 and have a shape generally as shown in FIG. **9**, have a denier per filament of about 6, and the sliver has a denier of about 50,000–60,000.

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